Feynman Integrals, Polylogarithms and Symbols

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based on work with Claude Duhr & Volodya Smirnov



7 September 2011

let us consider *I*-loop *n*-point Feynman integrals

example: I-loop *n*-point scalar Feynman integral without internal or external masses

$$I_n^D(\{\nu_i\}; \{Q_i^2\}) \propto \int \frac{d^D k}{i\pi^{D/2}} \prod_{i=1}^n \frac{1}{D_i^{\nu_i}}$$
$$D_1 = k^2 + i0, \qquad D_m = \left(k + \sum_{j=1}^{m-1} k_j\right)^2 + i0, \qquad m = 2, \dots, n$$

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suppose that we can compute analytically the Feynman integral, which is given as a combination of multiple polylogarithms

$$G(a, \vec{w}; z) = \int_0^z \frac{\mathrm{d}t}{t-a} G(\vec{w}; t), \qquad G(a; z) = \ln\left(1 - \frac{z}{a}\right)$$
Goncharov 98

suppose that the result is quite involved, which is the analytic outcome of the Feynman integral, but that we are interested in a ``simpler'' analytic result, e.g. because either we want to study the underlying theory, or we just need a numeric result, but we hope to use simpler numeric routines of the functions involved

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- suppose that the only tool we have is some (complicated) functional relations which relate multiple polylogarithms
- using those functional relations, it may become a frustating and unyielding exercise to simplify the result

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Duhr Smirnov VDD 09

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- \bigcirc the result was given in terms of $O(10^3)$ multiple polylogarithms $G(u_1, u_2, u_3)$
- it turned out to be unfeasible to ``simplify" the result through functional relations which related the multiple polylogarithms

N=4 Super Yang-Mills

- maximal supersymmetric theory (without gravity) conformally invariant, β fn. = 0
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 4 spin I/2 gluinos
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- AdS/CFT duality Maldacena 97
 - Solution String Large-λ limit of 4dim CFT ↔ weakly-coupled string theory (aka weak-strong duality)

at any order in the coupling, a colour-ordered MHV amplitude in N=4 SYM can be written as tree-level amplitude times helicity-free loop coefficient $M_n^{(L)} = M_n^{(0)} m_n^{(L)}$

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at 2 loops, iteration formula for the *n*-pt amplitude

 $m_n^{(2)}(\epsilon) = \frac{1}{2} \left[m_n^{(1)}(\epsilon) \right]^2 + f^{(2)}(\epsilon) m_n^{(1)}(2\epsilon) + Const^{(2)} + R$

Anastasiou Bern Dixon Kosower 03

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at all loops, ansatz for a resummed exponent

$$m_n^{(L)} = \exp\left[\sum_{l=1}^{\infty} a^l \left(f^{(l)}(\epsilon) m_n^{(1)}(l\epsilon) + Const^{(l)} + E_n^{(l)}(\epsilon)\right)\right] + R$$

Bern Dixon Smirnov 05

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$$\begin{array}{ll} \label{eq:mnn} & \mbox{at l loop} \\ & m_n^{(1)} = \sum_{pq} F^{2\mathrm{me}}(p,q,P,Q) \\ & \mbox{at 2 loops, iteration formula for the n-pt amplitude} \\ & \mbox{mnn}^{(2)}(\epsilon) = \frac{1}{2} \left[m_n^{(1)}(\epsilon) \right]^2 + f^{(2)}(\epsilon) m_n^{(1)}(2\epsilon) + Const^{(2)} \\ & \mbox{Anastasiou Bern Dixor Kosower 03} \\ & \mbox{at all loops, ansatz for a resummed exponent} \\ & \mbox{mnn}^{(L)} = \exp \left[\sum_{l=1}^{\infty} a^l \left(f^{(l)}(\epsilon) m_n^{(1)}(l\epsilon) + Const^{(l)} + E_n^{(l)}(\epsilon) \right) \right] + R \\ & \mbox{Bern Dixor Smirnov 05} \end{array}$$



Bern Dixon Smirnov 05

Cachazo Spradlin Volovich 06 Bern Czakon Kosower Roiban Smirnov 06

the ansatz checked for the 3-loop 4-pt amplitude 2-loop 5-pt amplitude

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Bern Dixon Kosower Roiban Spradlin Vergu Volovich 08 Alday Maldacena 07; Bartels Lipatov Sabio-Vera 08 the ansatz checked for the 3-loop 4-pt amplitude 2-loop 5-pt amplitude

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at 2 loops, the remainder function characterises the deviation from the ansatz

$$R_n^{(2)} = m_n^{(2)}(\epsilon) - \frac{1}{2} \left[m_n^{(1)}(\epsilon) \right]^2 - f^{(2)}(\epsilon) m_n^{(1)}(2\epsilon) - Const^{(2)}$$

 $R_6^{(2)}$ known analytically Duhr Smirnov VDD 09

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- for n = 4, 5, R is a constant
 for n ≥ 6, R is an unknown function of conformally invariant cross ratios
- \bigcirc for n = 6, the conformally invariant cross ratios are

$$u_1 = \frac{x_{13}^2 x_{46}^2}{x_{14}^2 x_{36}^2} \qquad u_2 = \frac{x_{24}^2 x_{15}^2}{x_{25}^2 x_{14}^2} \qquad u_3 = \frac{x_{35}^2 x_{26}^2}{x_{36}^2 x_{25}^2}$$
$$x_i \text{ are variables in a dual space s.t.} \quad p_i = x_i - x_{i+1}$$

thus
$$x_{k,k+r}^2 = (p_k + \ldots + p_{k+r-1})^2$$



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straightforward computation

finite answer, but in intermediate steps many divergences output is punishingly long: $O(10^3)$ multiple polylogarithms $G(u_1, u_2, u_3)$

yet, our result was given in terms of polylogarithms

Goncharov Spradlin Vergu Volovich 10

$$R_{6,WL}^{(2)}(u_1, u_2, u_3) = \sum_{i=1}^{3} \left(L_4(x_i^+, x_i^-) - \frac{1}{2} \text{Li}_4(1 - 1/u_i) \right) - \frac{1}{8} \left(\sum_{i=1}^{3} \text{Li}_2(1 - 1/u_i) \right)^2 + \frac{J^4}{24} + \frac{\pi^2}{12} J^2 + \frac{\pi^4}{72} J^4 + \frac{\pi^4}{72} J^$$



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where

$$\begin{aligned} x_i^{\pm} &= u_i x^{\pm} \qquad x^{\pm} = \frac{u_1 + u_2 + u_3 - 1 \pm \sqrt{\Delta}}{2u_1 u_2 u_3} \qquad \Delta = (u_1 + u_2 + u_3 - 1)^2 - 4u_1 u_2 u_3 \\ L_4(x^+, x^-) &= \sum_{m=0}^3 \frac{(-1)^m}{(2m)!!} \log(x^+ x^-)^m (\ell_{4-m}(x^+) + \ell_{4-m}(x^-)) + \frac{1}{8!!} \log(x^+ x^-)^4 \\ \ell_n(x) &= \frac{1}{2} \left(\operatorname{Li}_n(x) - (-1)^n \operatorname{Li}_n(1/x) \right) \qquad J = \sum_{i=1}^3 (\ell_1(x_i^+) - \ell_1(x_i^-)) \end{aligned}$$



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 $x_{i}^{\pm} = u_{i}x^{\pm} \qquad x^{\pm} = \frac{u_{1} + u_{2} + u_{3} - 1 \pm \sqrt{\Delta}}{2u_{1}u_{2}u_{3}} \qquad \Delta = (u_{1} + u_{2} + u_{3} - 1)^{2} - 4u_{1}u_{2}u_{3}$ $L_{4}(x^{+}, x^{-}) = \sum_{i=1}^{3} \frac{(-1)^{m}}{(2m)!!} \log(x^{+}x^{-})^{m} (\ell_{4-m}(x^{+}) + \ell_{4-m}(x^{-})) + \frac{1}{8!!} \log(x^{+}x^{-})^{4}$

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not a new, independent, computation just a manipulation of our result



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answer is short and simple introduces symbols in TH physics

Wednesday, September 7, 2011

Solution Fn. F of deg(F) = n: fn. with log cuts, s.t. Disc = $2\pi i \times f$, with deg(f) = n - 1

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 $\Theta \quad \deg(const) = 0 \rightarrow \deg(\pi) = 0$ $\ln x : \text{cut along } [-\infty, 0] \text{ with } Disc = 2\pi i \rightarrow \deg(\ln x) = 1$ $\text{Li}_2(x) : \text{cut along } [1, \infty] \text{ with } Disc = -2\pi i \ln x \rightarrow \deg(\text{Li}_2(x)) = 2$

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take a fn. defined as an iterated integral of logs of rational functions R_i

$$T_k = \int_a^b \mathrm{d} \ln R_1 \circ \cdots \circ \mathrm{d} \ln R_k = \int_a^b \left(\int_a^t \mathrm{d} \ln R_1 \circ \cdots \circ \mathrm{d} \ln R_{k-1} \right) \mathrm{d} \ln R_k(t)$$

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the symbol $\operatorname{Sym}[T_k] = R_1 \otimes \cdots \otimes R_k$ Zagier, Goncharov

is defined on the tensor product of the group of rational functions, modulo constants

$$\cdots \otimes R_1 R_2 \otimes \cdots = \cdots \otimes R_1 \otimes \cdots + \cdots \otimes R_2 \otimes \cdots$$
$$\cdots \otimes (cR_1) \otimes \cdots = \cdots \otimes R_1 \otimes \cdots$$

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 $\operatorname{Li}_{1}(z) = -\ln(1-z) \qquad \operatorname{Li}_{k}(z) = \int_{0}^{z} \mathrm{d}\ln t \, \operatorname{Li}_{k-1}(t) \qquad \operatorname{Sym}[\operatorname{Li}_{k}(z)] = -(1-z) \otimes \underbrace{z \otimes \cdots \otimes z}_{k-1 \text{ times}}$

 $\operatorname{Sym}[\ln x \, \ln y] = x \otimes y + y \otimes x$

- $\Theta \qquad \text{Disc}(\ln x \ln y) = \begin{cases} 2\pi i \ln x & \text{along the } y \text{ cut } [-\infty, 0] \\ 2\pi i \ln y & \text{along the } x \text{ cut } [-\infty, 0] \end{cases}$ $\text{Sym}[\ln x \ln y] = x \otimes y + y \otimes x$
- $\bigcirc \quad \text{in general, if } Disc(f g) = Disc(f) g + f Disc(g) \\ \text{and} \quad \operatorname{Sym}[f] = \otimes_{i=1}^{n} R_{i} \qquad \operatorname{Sym}[g] = \otimes_{i=n+1}^{m} R_{i} \\ \text{then} \quad \operatorname{Sym}[fg] = \sum_{\sigma} \otimes_{i=1}^{n} R_{\sigma(i)}$

where σ denotes the set of all shuffles of n+(m-n) elements

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$$\begin{array}{ll} \textbf{e.g.} & \operatorname{Sym}[f] = R_1 \otimes R_2 & \operatorname{Sym}[g] = R_3 \otimes R_4 \\ \\ \operatorname{Sym}[fg] &= R_1 \otimes R_2 \otimes R_3 \otimes R_4 + R_1 \otimes R_3 \otimes R_2 \otimes R_4 + R_1 \otimes R_3 \otimes R_4 \otimes R_2 \\ &+ R_3 \otimes R_1 \otimes R_2 \otimes R_4 + R_3 \otimes R_1 \otimes R_4 \otimes R_2 + R_3 \otimes R_4 \otimes R_1 \otimes R_2 \end{array}$$

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- - $Sym[fg] = R_1 \otimes R_2 \otimes R_3 \otimes R_4 + R_1 \otimes R_3 \otimes R_2 \otimes R_4 + R_1 \otimes R_3 \otimes R_4 \otimes R_2 \\ + R_3 \otimes R_1 \otimes R_2 \otimes R_4 + R_3 \otimes R_1 \otimes R_4 \otimes R_2 + R_3 \otimes R_4 \otimes R_1 \otimes R_2$
- symbols form a shuffle algebra, *i.e.* a vector space with a shuffle product (also iterated integrals and multiple polylogarithms form shuffle algebras)

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- in general, if Disc(fg) = Disc(f)g + fDisc(g)and $Sym[f] = \bigotimes_{i=1}^{n} R_i$ $Sym[g] = \bigotimes_{i=n+1}^{m} R_i$ then $Sym[fg] = \sum_{\sigma} \bigotimes_{i=1}^{n} R_{\sigma(i)}$ where σ denotes the set of all shuffles of n+(m-n) elements

e.g. Sym
$$[f] = R_1 \otimes R_2$$
 Sym $[g] = R_3 \otimes R_4$
Sym $[fg] = R_1 \otimes R_2 \otimes R_3 \otimes R_4 + R_1 \otimes R_3 \otimes R_2 \otimes R_4 + R_1 \otimes R_3 \otimes R_4 \otimes R_2$
 $+ R_3 \otimes R_1 \otimes R_2 \otimes R_4 + R_3 \otimes R_1 \otimes R_4 \otimes R_2 + R_3 \otimes R_4 \otimes R_1 \otimes R_2$

- symbols form a shuffle algebra, *i.e.* a vector space with a shuffle product (also iterated integrals and multiple polylogarithms form shuffle algebras)
- polylogarithm identities satisfied by the function f become algebraic identities satisfied by its symbol

take f, g with deg(f) = deg(g) = n and Sym[f] = Sym[g] then f-g = h with deg(h) = n - I the symbol does not know about h info on the degree n-1 is lost by taking the symbol

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Thus, we have a procedure to simplify a generic function of polylogarithms:

- find suitable variables such that arguments of multiple polylogarithms become rational functions
- determine the symbol of the function
- Itrough some symbol-processing procedure,
 find a simpler form of the integral in terms of multiple polylogarithms

polylogarithm identities satisfied by the function f become algebraic identities satisfied by its symbol

let us prove the identity $\operatorname{Li}_2(1-x) = -\operatorname{Li}_2(x) - \ln x \ln(1-x) + \frac{\pi^2}{6}$

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proof
$$\operatorname{Sym}[\operatorname{Li}_2(x)] = -(1-x) \otimes x$$
 $\operatorname{Sym}[\operatorname{Li}_2(1-x)] = -x \otimes (1-x)$
 $\operatorname{Sym}[\ln x \ln(1-x)] = x \otimes (1-x) + (1-x) \otimes x$

thus $Sym[Li_2(1-x)] = Sym[-Li_2(x) - \ln x \ln(1-x)]$

which determines the function up to functions of lesser degree

$$\operatorname{Li}_{2}(1-x) = -\operatorname{Li}_{2}(x) - \ln x \ln(1-x) + c \pi^{2} + i\pi \left(c' \ln x + c'' \ln(1-x)\right)$$

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but the equation is real for 0 < x < 1, so c'=c''=0

at
$$x = 1$$
 $0 = -\frac{\pi^2}{6} - 0 + c \pi^2$ \longrightarrow $c = \frac{1}{6}$

let us prove the identity

$$\operatorname{Li}_{2}\left(1-\frac{1}{x}\right) = -\operatorname{Li}_{2}(1-x) - \frac{1}{2}\ln^{2}x$$

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= $x\otimes(1-x)-x\otimes x$

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multiple polylogarithms can also be defined through nested harmonic sums

$$\operatorname{Li}_{m_1,\dots,m_k}(u_1,\dots,u_k) = \sum_{n_k=1}^{\infty} \frac{u_k^{n_k}}{n_k^{m_k}} \sum_{\substack{n_{k-1}=1}}^{n_k-1} \dots \sum_{\substack{n_1=1}}^{n_2-1} \frac{u_1^{n_1}}{n_1^{m_1}}$$
$$= (-1)^k G_{m_k,\dots,m_1}\left(\frac{1}{u_k},\dots,\frac{1}{u_1\cdots u_k}\right)$$

$$G_{m_1,...,m_k}(u_1,...,u_k) = G\left(\underbrace{0,...,0}_{m_1-1}, u_1,...,\underbrace{0,...,0}_{m_k-1}, u_k; 1\right)$$

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special values as polylogarithms and Nielsen logarithms

$$G(\vec{0}_{n};x) = \frac{1}{n!} \ln^{n} x \qquad G(\vec{a}_{n};x) = \frac{1}{n!} \ln^{n} \left(1 - \frac{x}{a}\right)$$
$$G(\vec{0}_{n-1},a;x) = -\operatorname{Li}_{n} \left(\frac{x}{a}\right) \qquad G(\vec{0}_{n},\vec{a}_{m};x) = (-1)^{m} S_{n,m} \left(\frac{x}{a}\right) \qquad S_{n-1,1}(x) = \operatorname{Li}_{n}(x)$$

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when the root equals I, multiple polylogarithms become harmonic polylogarithms (HPLs)

$$Li_n(x) = H(\vec{0}_{n-1}, 1; x) \qquad \qquad S_{n,m}(x) = H(\vec{0}_n, \vec{1}_m; x)$$

HPLs are defined through iterated integrals

$$H(a, \vec{w}; z) = \int_0^z dt f(a; t) H(\vec{w}; t) \qquad f(-1; t) = \frac{1}{1+t}, \quad f(0; t) = \frac{1}{t}, \quad f(1; t) = \frac{1}{1-t}$$

with $\{a, \vec{w}\} \in \{-1, 0, 1\}$

Wednesday, September 7, 2011

... on to symbols

Sym
$$[\ln x] = x$$
 Sym $\left[\frac{1}{n!}\ln^n x\right] = \underbrace{x \otimes \cdots \otimes x}_{n \text{ times}} \equiv x^{\otimes n}$

 $\begin{aligned} \operatorname{Sym}[\operatorname{Li}_{n}(x)] &= -(1-x) \otimes x^{\otimes (n-1)} \\ \operatorname{Sym}[S_{n,m}(x)] &= (-1)^{m}(1-x)^{\otimes m} \otimes x^{\otimes n} \\ \operatorname{Sym}[H(a_{1},\ldots,a_{n};x)] &= (-1)^{k}(a_{n}-x) \otimes \cdots \otimes (a_{1}-x) \\ & \{a_{i}\} \in \{0,1\} \\ k \text{ is the number of } a \text{'s equal to I} \end{aligned}$

weight I: $B_1^{(1)}(x) = \ln x$, $B_1^{(2)}(x) = \ln(1-x)$, $B_1^{(3)}(x) = \ln(1+x)$

weight 2: $B_2^{(1)}(x) = \text{Li}_2(x), \qquad B_2^{(2)}(x) = \text{Li}_2(-x), \qquad B_2^{(3)}(x) = \text{Li}_2\left(\frac{1-x}{2}\right)$

- weight 3: polylogarithms of type Li₃ of various arguments
- weight 4: polylogarithms of type Li₄ of various arguments, plus a few polylogarithms of type Li_{2,2}, like Li_{2,2}(-1, x) etc. Alternatively, the polylogarithms of type Li_{2,2} can be replaced by the HPLs: H(0,1,0,-1;x) and H(0,1,1,-1;x)

if needed numerically, any combination of HPLs up to weight 4 can be evaluated in terms of a minimal set of numerical routines using symbols, one can reduce the HPLs to a minimal set

weight I: $B_1^{(1)}(x) = \ln x$, $B_1^{(2)}(x) = \ln(1-x)$, $B_1^{(3)}(x) = \ln(1+x)$

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These features generalise to multiple polylogarithms Duhr Gangl Rhodes (in progress) weight 1: one needs functions of type ln x

| weight 6: | $Li_6(x)$, $Li_{2,4}(x,y)$, $Li_{3,3}(x,y)$, $Li_{2,2,2}(x,y)$ |
|-----------|---|
| weight 5: | $Li_5(x), Li_{2,3}(x,y)$ |
| weight 4: | $Li_4(x), Li_{2,2}(x,y)$ |
| weight 3: | $Li_3(x)$ |
| weight z. | |



