Finite density simulations using a determinant estimator

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Overview

- Motivation and introduction
- The algorithm: Hybrid Noisy Monte Carlo
- Determinant estimator
- Algorithm check and volume dependence
- Conclusions and outlook

Canonical partition function



 $\det_k M \equiv \frac{1}{2\pi} \int d\phi e^{-ik\phi} \det M_{\phi}^2$ Constraint: $n_u + n_d = k$.

Projected determinant

- To compute the projected determinant we need to evaluate the determinant for all phases -- not feasible
- We use an approximation where we employ a discrete Fourier transform



$$\det_k^{\prime} M^2(U) = \frac{1}{N} \sum_{\varphi_i} e^{-ik\varphi_i} \det M^2_{\varphi_i}(U)$$

Exact determinant simulations: scaling

- We carried out a study on 4⁴ lattices that used LU decomposition to compute the fermionic determinant
- To produce physical results we need at least 6³x4 lattices.
- The scaling of the exact algorithm goes like V⁴
- The estimator method was expected to scale like V²
- As we will show the estimator scales with V³, which still makes it the method of choice when moving to larger volume.

Hybrid Noisy Monte Carlo

$$Z_{C}(V,k,T) = \int DU \ e^{-S_{G}(U)} \det'_{k} M^{2}(U)$$
$$= \int DUD\xi \ e^{-S_{G}(U)} \det M^{2}(U) f_{k}(U,\xi)$$

$$\int D\xi \ g(U,\varphi,\xi) = \frac{\det M_{\varphi}^{2}(U)}{\det M^{2}(U)}$$
$$f_{k}(U,\xi) = \frac{1}{N} \sum_{\varphi_{i}} e^{-ik\varphi_{i}} g(U,\varphi_{i},\xi)$$

The updating process

$$Z_{C}(V,n,T) = \int DUD\xi \ e^{-S_{G}(U)} \det M^{2}(U) f_{n}(U,\xi)$$

$$= \int DUD\xi \ e^{-S_{G}(U)} \det M^{2}(U) |f_{n}(U,\xi)| \frac{f_{n}(U,\xi)}{|f_{n}(U,\xi)|}$$
Simulation measure phase
$$(U,\xi) \xrightarrow{HMC + Acc/rej} (U',\xi) \xrightarrow{Acc/rej} (U',\xi')$$
The accept/reject steps are based on the ratios $\frac{|f_{n}(U,\xi)|}{|f_{n}(U,\xi)|}$ and $\frac{|f_{n}(U',\xi')|}{|f_{n}(U',\xi)|}$.

The estimator

To set up the estimator we write

$$\frac{\det M_{\phi}^2}{\det M^2} = e^{2\operatorname{Tr}(\ln M_{\phi} - \ln M)}$$

We first develop an estimator for the exponent:

- Use Z(4) noise for trace
- Use Pade approximation for log M
- Improve the estimator using unbiased subtraction
- Use the trace estimator with Bhanot Kennedy method to turn it into and unbiased estimator for the determinant

Exponent estimator: Pade approximation

$$\ln \det M = \operatorname{Tr} \ln M \cong b_0 \operatorname{Tr} I + \sum_{k=1}^{K} \operatorname{Tr} \frac{b_k}{c_k + M}$$



Trace improvement

$$Tr \ln M = \int d\eta \eta^{+} M\eta$$

$$Tr \ln M \approx b_{0} Tr I + \sum_{k=1}^{K} Tr \frac{b_{k}}{c_{k} + M}$$

$$Tr \frac{1}{c + M} = Tr(\frac{1}{c + M} - \sum_{i} O_{i})$$

$$Tr \frac{1}{c + M} = \frac{1}{1 + c} + \frac{\kappa}{(1 + c)^{2}} D + \frac{\kappa^{2}}{(1 + c)^{3}} D^{2} + \dots$$

$$O_{i} = \frac{\kappa^{i}}{(1 + c)^{i+1}} (D^{i} - \frac{1}{Tr1} Tr D^{i})$$

Number of loops for a 4⁴ lattice: 4 - 10, 6 - 112, 8 - 2884, 10 - 84360.



Bhanot-Kennedy estimator

$$\det M = e^{Tr \ln M} \qquad \langle g_1(\eta) \rangle = Tr \ln M, \quad P(g_1 = 0) = 0$$
$$\langle g_2(\eta) \rangle = \frac{1}{2} Tr \ln M, \quad P(g_2 = 0) = \frac{1}{2}$$
$$\vdots$$
$$\langle g_k(\eta) \rangle = \frac{1}{k} Tr \ln M, \quad P(g_k = 0) = \frac{k-1}{k}$$
$$\vdots$$

 $f(\eta_1, \eta_2, ...) = 1 + g_1(\eta_1) + g_1(\eta_1)g_2(\eta_2) + g_1(\eta_1)g_2(\eta_2)g_3(\eta_3) + ...$ $\left\langle f(\eta_1, \eta_2, ...) \right\rangle = \det M$

Variance



Estimator breakup

Variance vs breakup level



Testing the algorithm



We run the program at the same parameters as in our previous study: kappa=0.158, N=12 and the same values of beta

Determining the breakup level





Simulation details

- We run the program at the same parameters as in our previous study: kappa=0.158, N=12 and the same values of beta
- On 4⁴ lattices the estimator takes less time than the exact calculation (100s vs 140s)
- We used small HMC trajectories so that the gauge acceptance rate stays above 50%.
- The acceptance rate for gauge updates matches or is slightly less that in the exact runs using the same trajectory length
- The acceptance rates for the stochastic field is very high 65%-95% (this indicates that the estimator has small variance)

Estimator vs exact simulations



Estimator vs exact simulations



Sign problem



Volume dependence



Algorithm scaling

- We find that our algorithm should scale with V³:
 - one factor of V because the dirac matrix inversion scales with V
 - one factor of V to keep the same density.
 - one factor of V because the breakup level has to be increased with V
- In conclusion the estimator method scales with V³ -- still better than the exact method's V⁴

• Since already on 4⁴ lattices the estimator method is faster for 6³x4 this method seems to be the clear winner.

Conclusions and outlook

- The stochastic algorithm is correct and it is faster than the exact one.
- The sign oscillations are comparable to the ones in the previous study.
- The algorithm scales with V^{3.}
- The new algorithm makes 6³x4 simulations feasible.
- We plan to run this new algorithm 6³x4 lattices and scan the parameter space looking for the phase transition line.