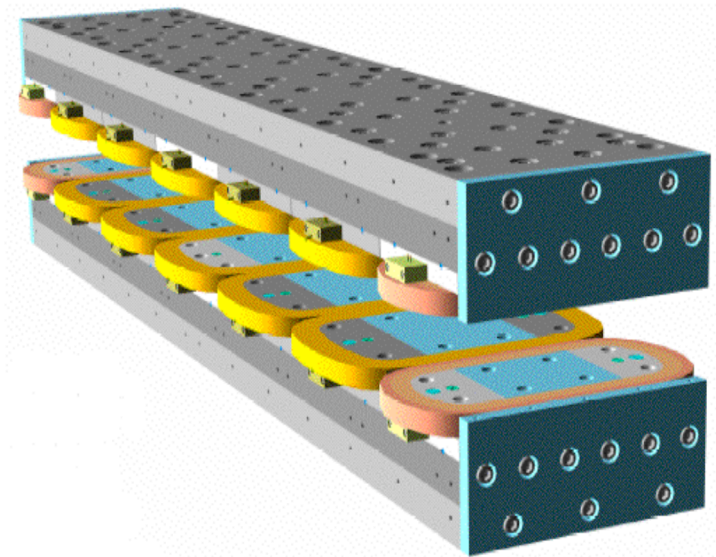
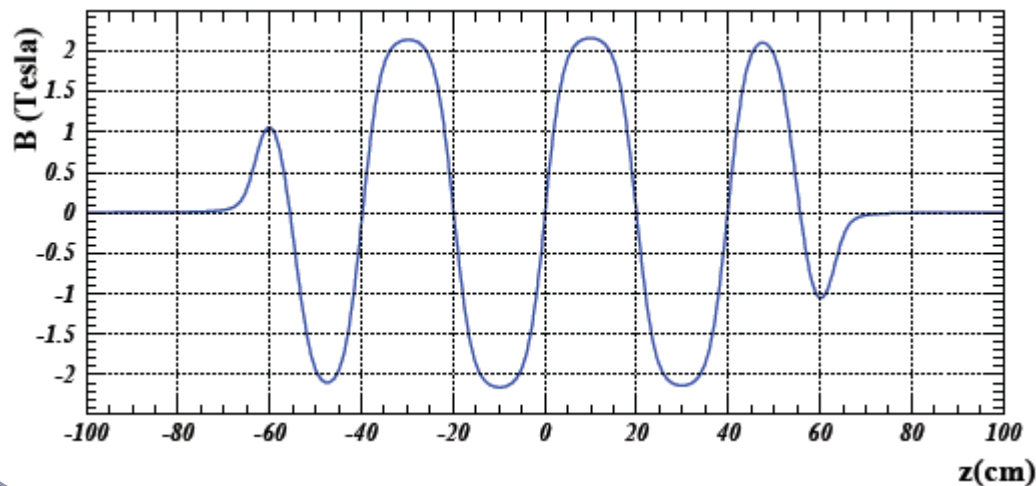


Modeling and Simulation for CESR-c & ILC W wigglers

Jeremy Urban
LEPP, Cornell University
Advisor: Gerry Dugan
WIGGLER 2005 Mini-Workshop
February 22nd, 2005

CESR-c Wiggler Design

- Energy = 1.88 GeV
- Superferric
- 8-Pole Wiggler
- Length = 1.3 m
- Peak Field = 2.1 T
- Horizontal Uniformity = 90 mm
- Period = 400 mm
- Gap Height = 76 mm
- Pole Width = 238 mm
- Realistic End Poles



CESR-c Wiggler Modeling

- OPERA 3-D _ Discrete
- Fit _ Analytic 1
- Analytic _ Hamiltonian

[1] D. Sagan, J. A. Crittenden, D. Rubin, E. Forest,
A Field Model for Wigglers and Undulators, PAC 2003

CESR-c Wiggler Modeling

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Note: k_{xn} & k_{sn} are free parameters in the fit, not = $2n\lambda/\lambda$



$f_n=2$ and $f_n=3$ select different combinations for fit

BMAD Tracking Methods

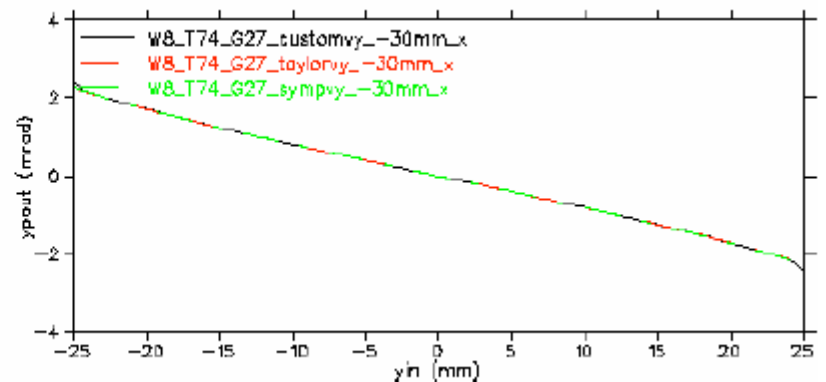
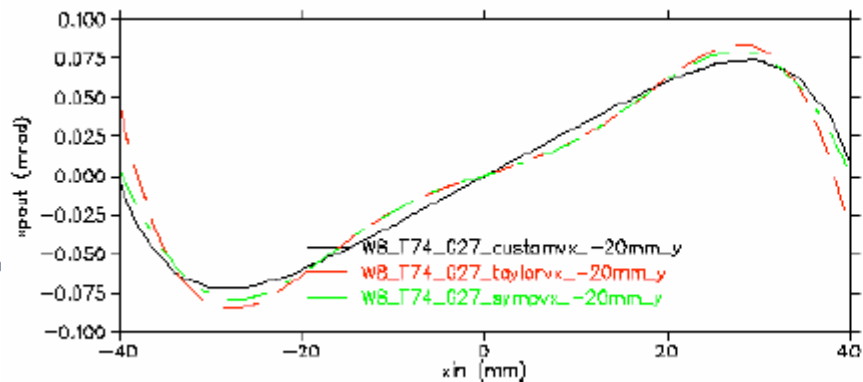
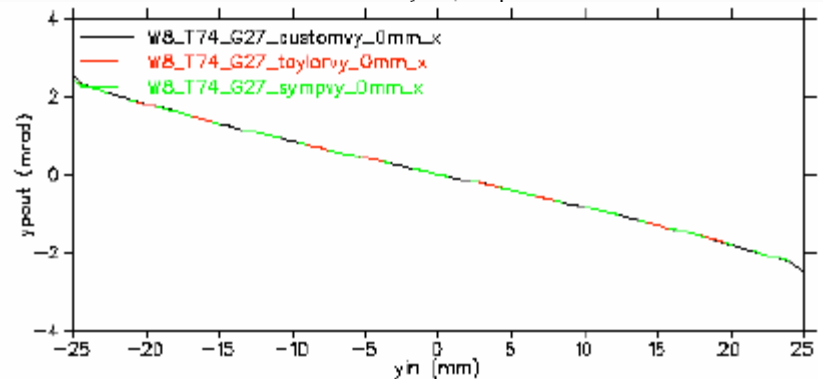
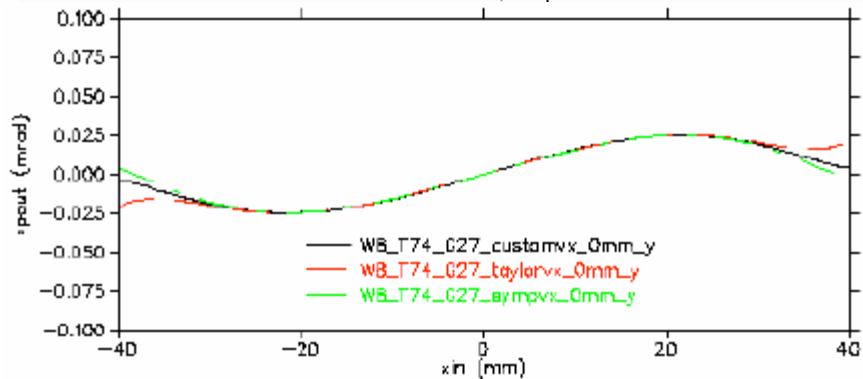
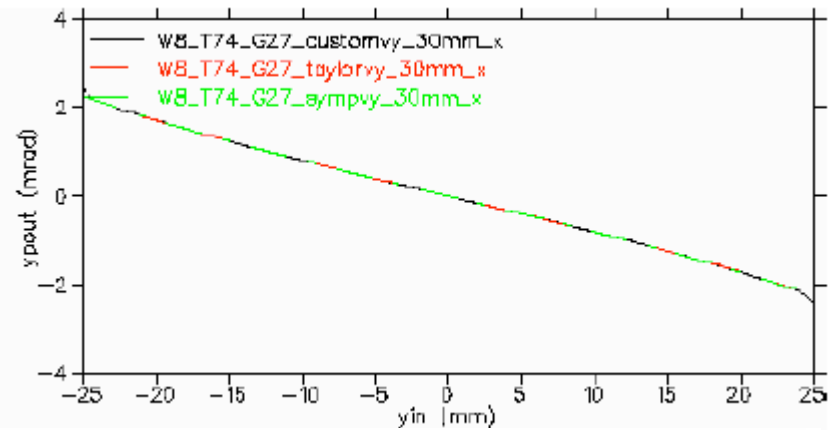
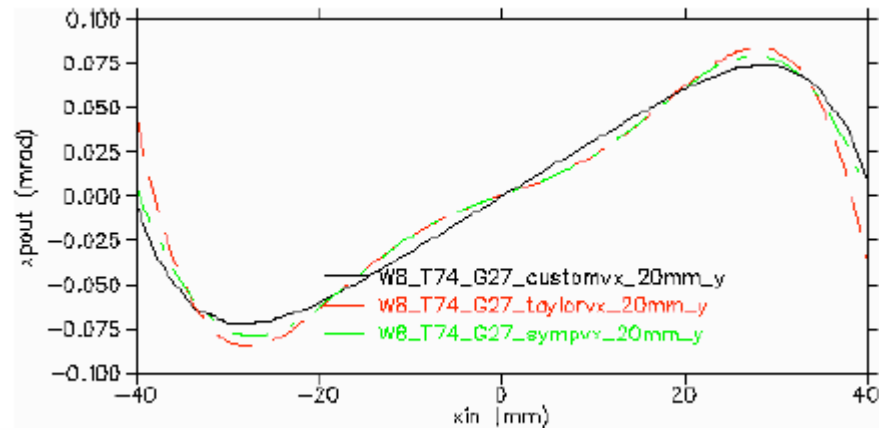
- Hamiltonian in Paraxial Approximation:

$$\begin{aligned} & \frac{1}{2} \left(\frac{dx}{ds} \right)^2 + \frac{1}{2} \left(\frac{dy}{ds} \right)^2 + \frac{1}{2} \left(\frac{dz}{ds} \right)^2 + \frac{1}{2} \left(\frac{d\phi}{ds} \right)^2 + \frac{1}{2} \left(\frac{d\psi}{ds} \right)^2 \\ & - \frac{1}{2} \left(\frac{d\chi}{ds} \right)^2 - \frac{1}{2} \left(\frac{d\eta}{ds} \right)^2 - \frac{1}{2} \left(\frac{d\theta}{ds} \right)^2 - \frac{1}{2} \left(\frac{d\mu}{ds} \right)^2 - \frac{1}{2} \left(\frac{d\nu}{ds} \right)^2 \end{aligned}$$

- Symplectic Inetgration²
 - To Track (250 steps)
 - To Generate Taylor Map (3rd order)
- Runge-Kutta through Field Table

[2] Y. Wu, E. Forest, D. S. Robin, H. Nishimura, A. Wolski, V. N. Litvinenko, *Symplectic Models for General Insetion Devices*, PAC 2001

CESR-c Transfer Functions

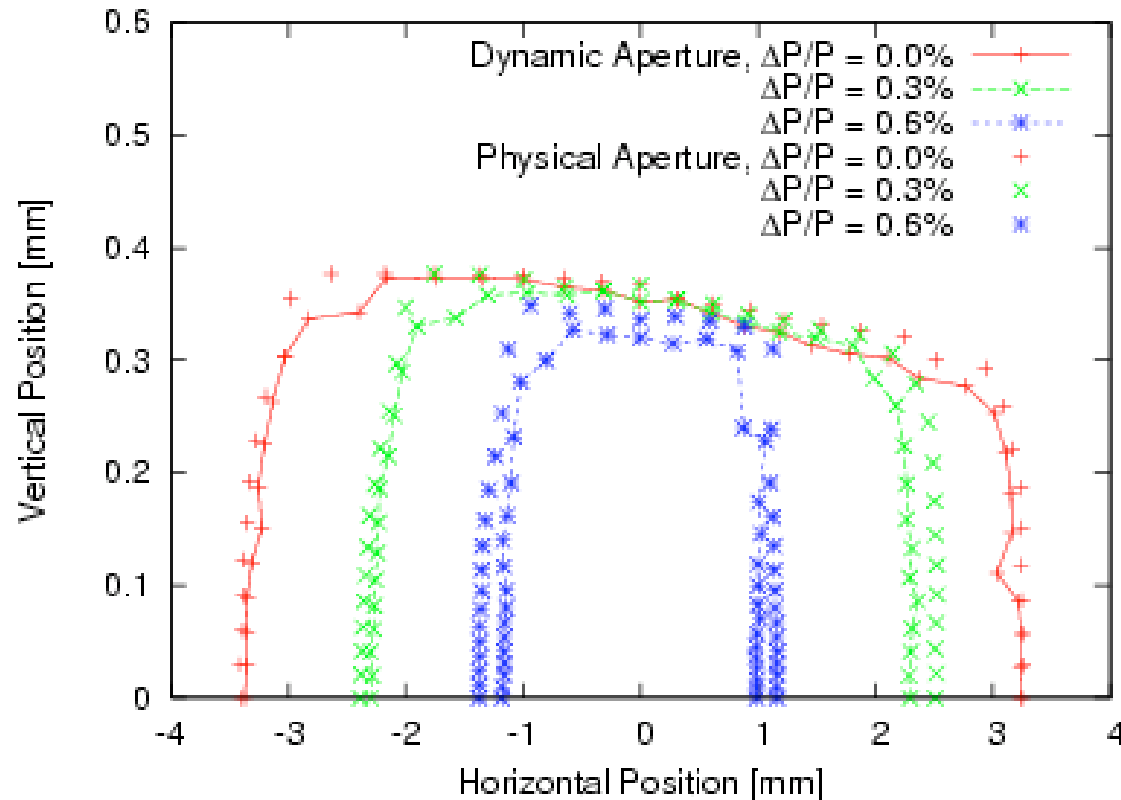


Simulation of CESR

Dynamic Aperture in CESR-c

$\Delta p/p = 0\%$, 0.3% , 0.6%

$Q_x = 0.518$, $Q_y = 0.584$, $Q_z = -0.089$

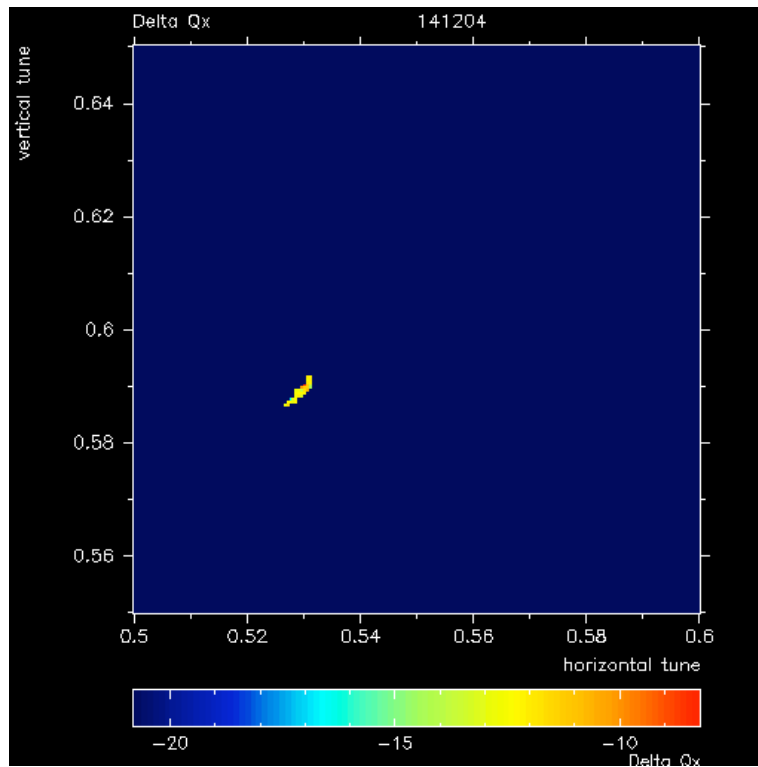


Simulation of CESR

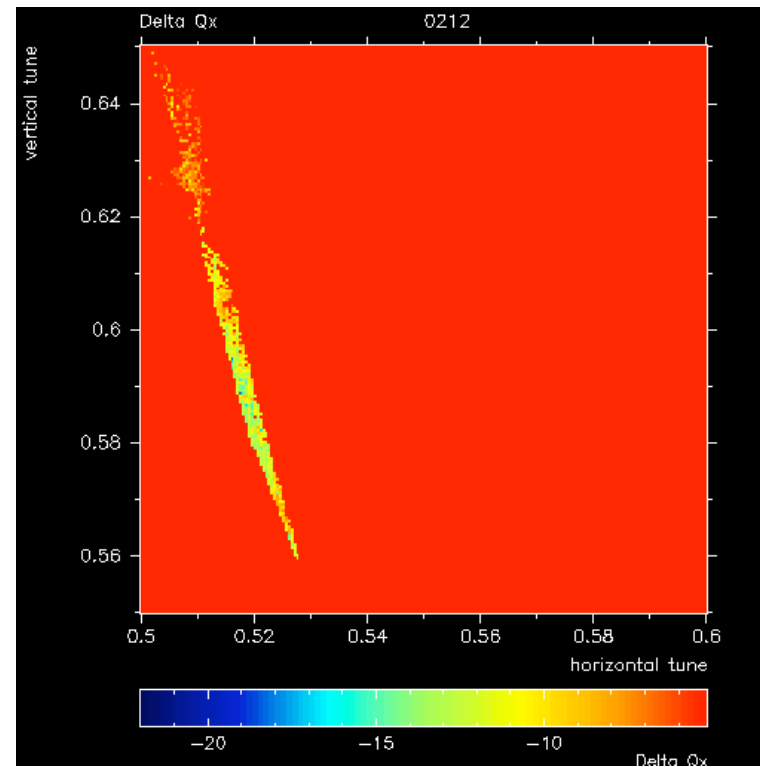
Horizontal Tune Shift vs. Tune in CESR-c

$$Q_x = 0.53, Q_y = 0.59, Q_z = -0.089$$

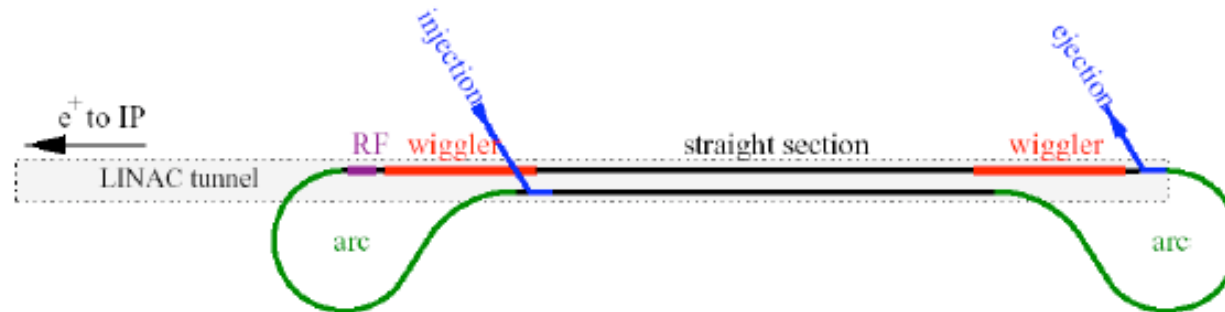
Linear Wiggler Model



Non-Linear Wiggler Model



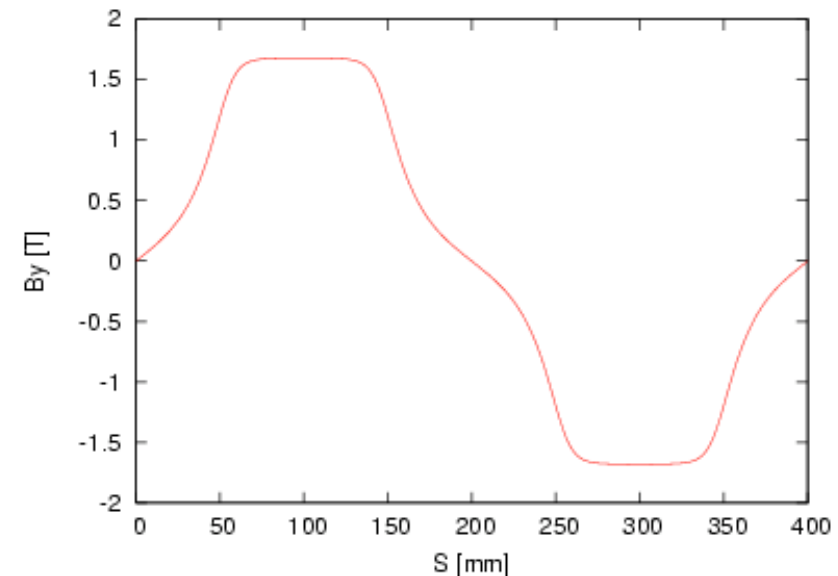
ILC Wiggler Design



Schematic of Dogbone Damping Ring from TESLA TDR

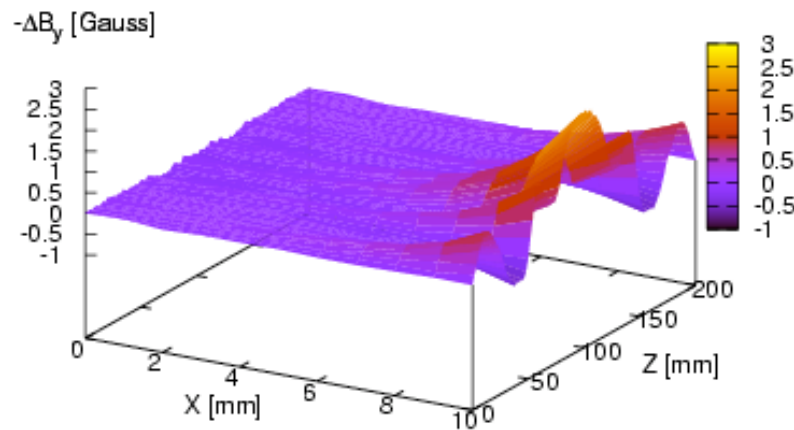
- Energy = 5 GeV
- Permanent Magnet
- Wiggler Length = 430 m
- Peak Field = 1.67 T
- Period = 400 mm
- Pole Width = 60 mm
- Gap Height = 25 mm
- Aperture = $2.8^*_{-y,e^+,inj.}$

Magnetic Field Profile

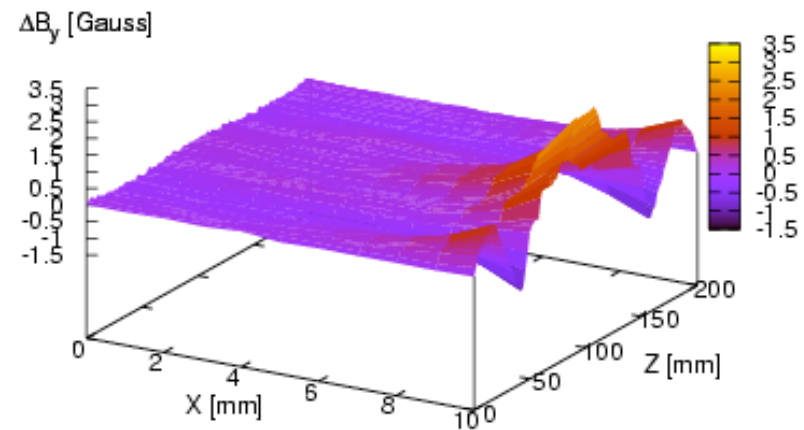


ILC Modeling

- Using 132 terms, differences with field table are less than 1 G on-axis and a few G at large amplitudes.

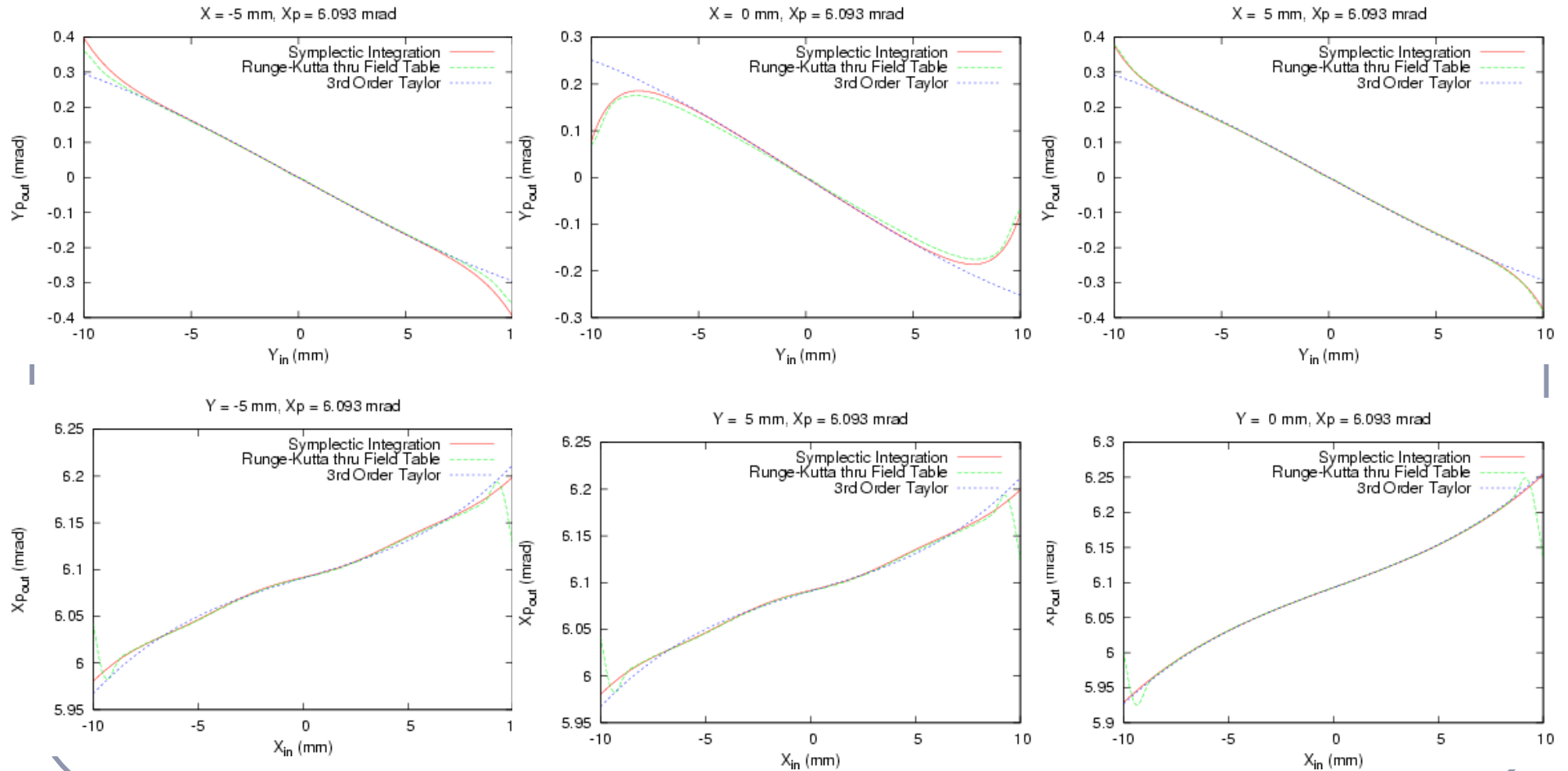


Residuals at Y = 0 mm



Residuals at Y = 6 mm

ILC Transfer Functions

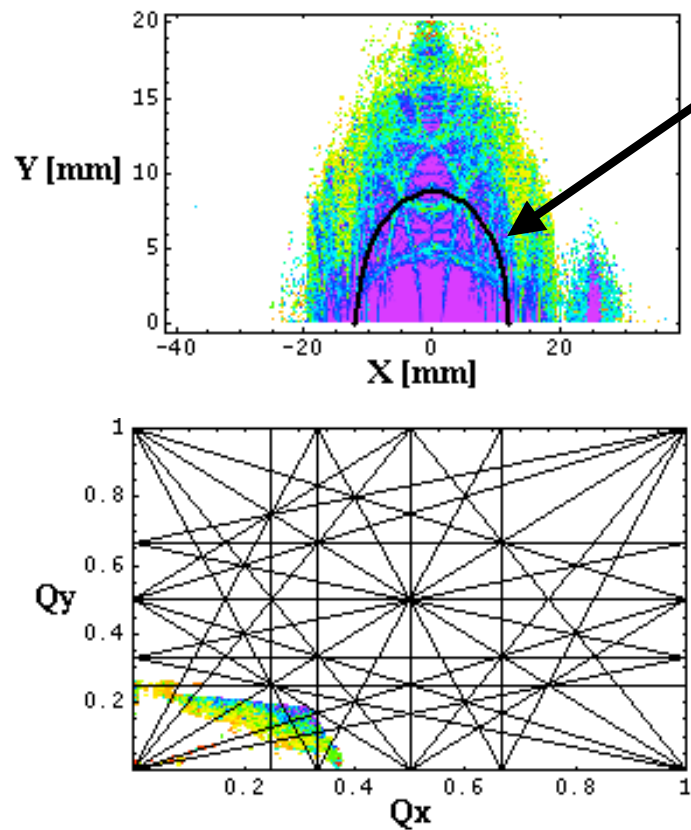


In the Dogbone Damping Ring

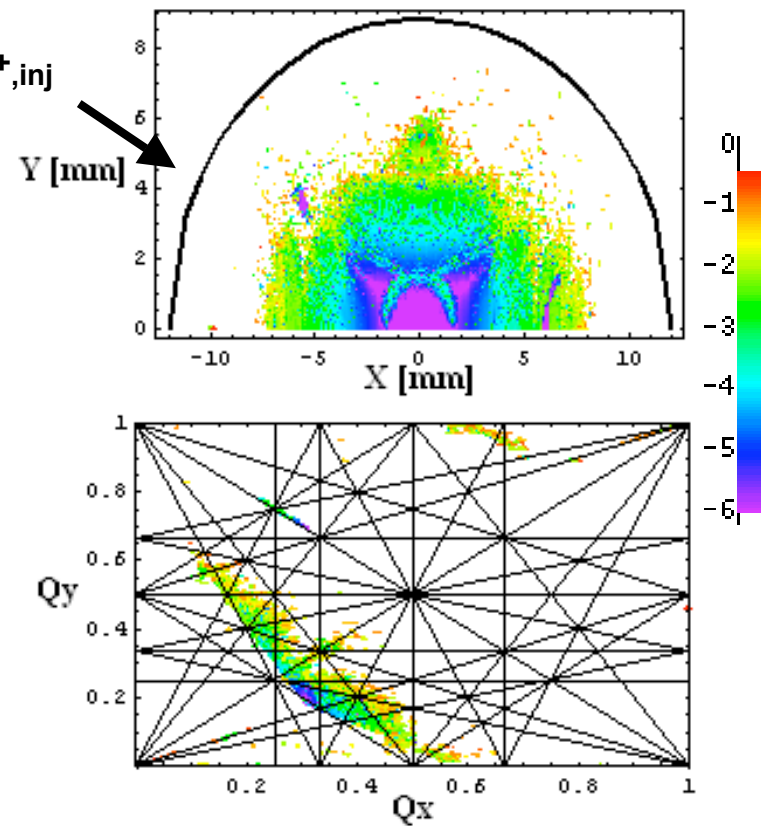
- Frequency Map Analysis
 - Intensity = $\text{Log}(_Q_x)$
- Dynamic Aperture
 - Reference Curve = 3*Injected Positron Beam Size
- Tune Scan
 - Intensity = Area Enclosed By Dynamic Aperture
- On-Momentum
- Working Point: $Q_x = 0.31, Q_y = 0.18$
- Match Tune with Matrix Transformation
- Sextupoles Untouched in Dogbone Lattice
- Tracking using 3rd order Taylor Map

Impact of Non-Linear Wiggler

Linear Model



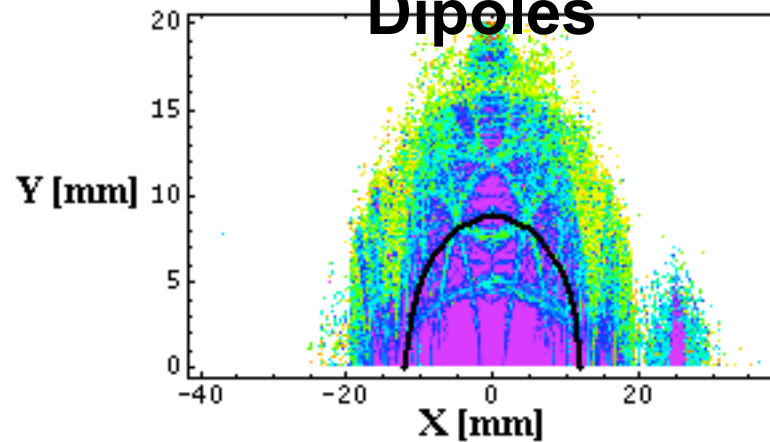
Non-Linear Model



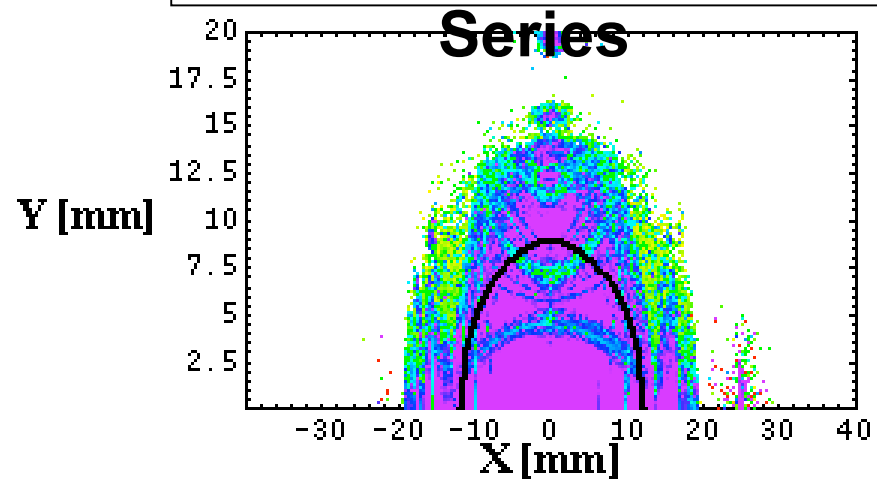
Which non-linearities restrict the DA?

“Linear” Model:
Alternating

Dipoles



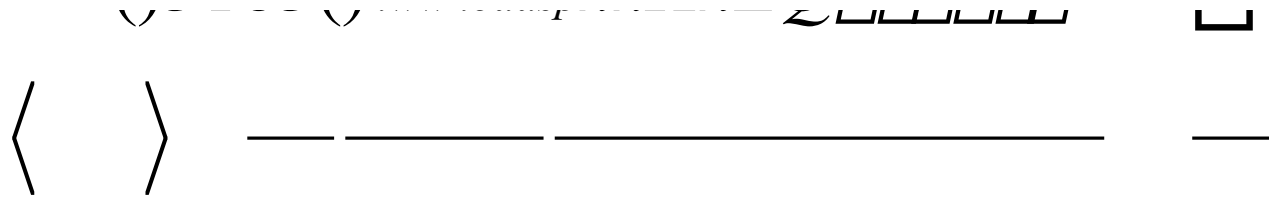
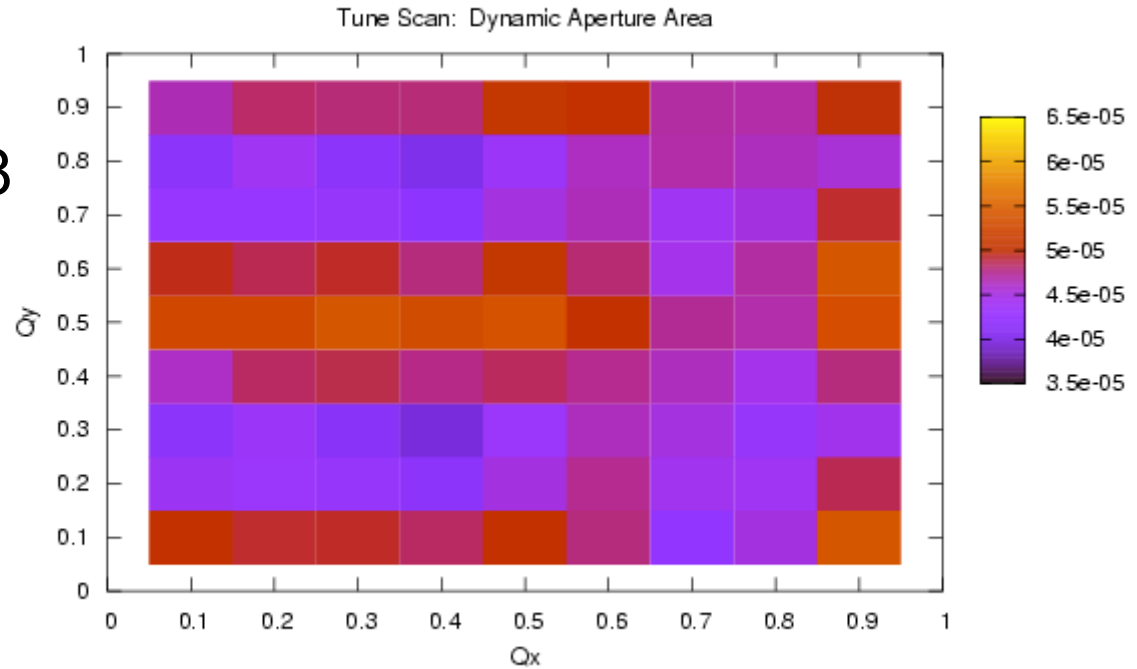
Linear Model:
1st Order Taylor
Series



- The Perfect Wiggler:
 - pole width = ∞ ; $B_y \sim \sin(z)$
 - dominant non-linearity is the vertical octupole term
 - In Progress...

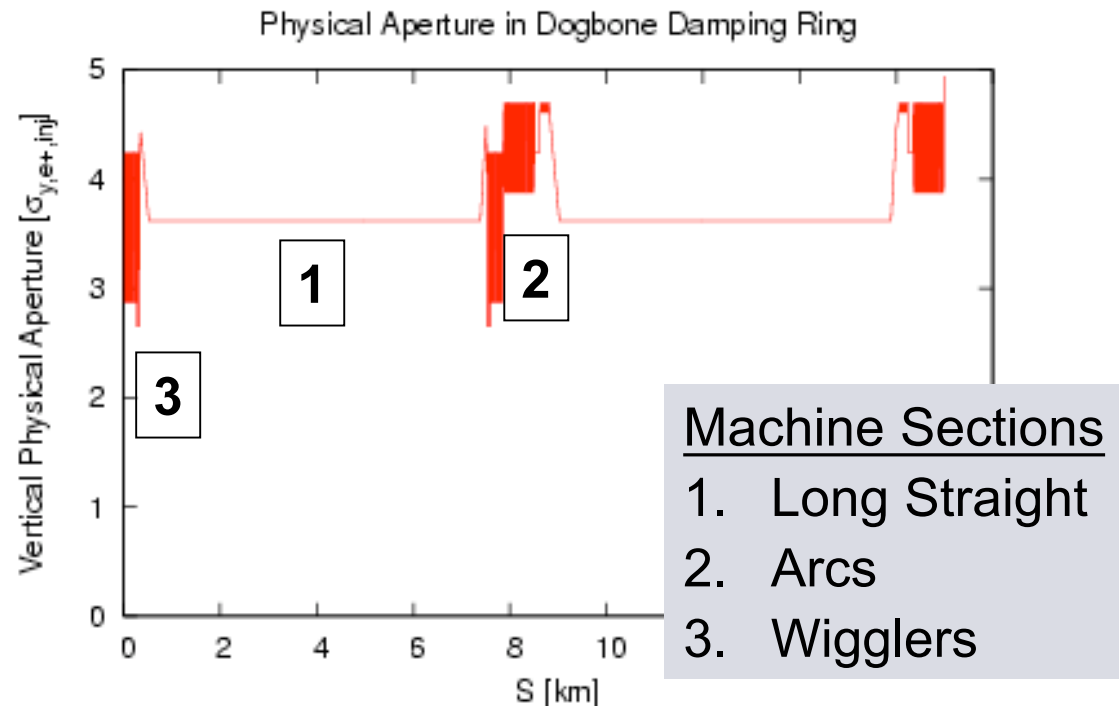
Tune Scan

- Working Point:
 $Q_x = 0.31, Q_y = 0.18$
- The tune footprint is large but maybe better operating points exist.
- Analytic Vertical Tune Spread:



Physical vs. Dynamic Aperture

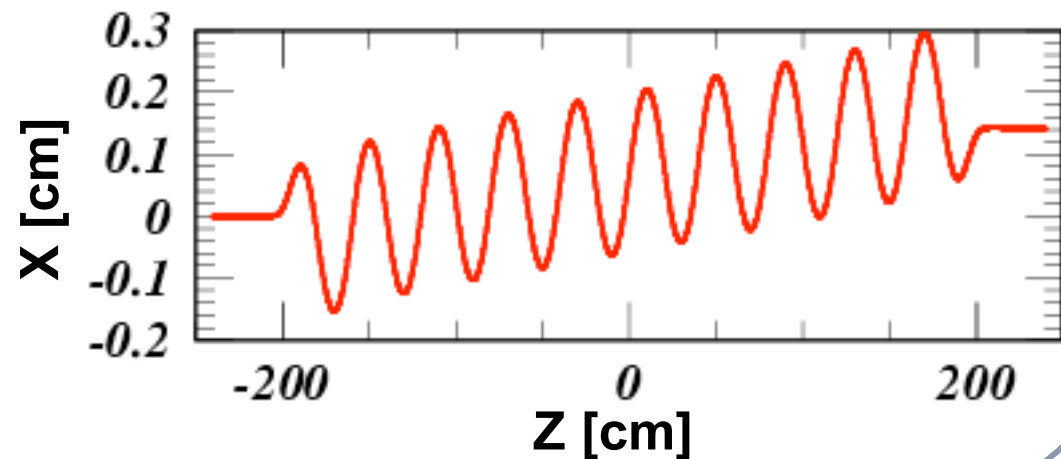
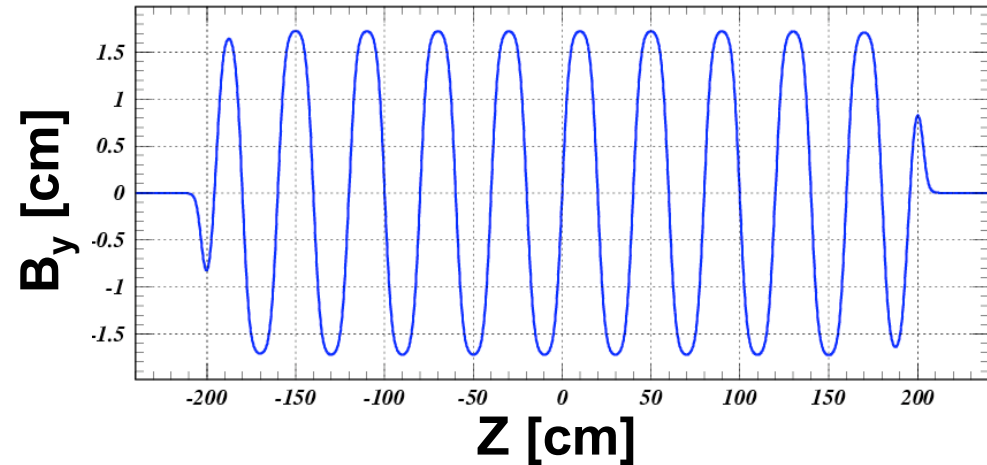
- Wiggler Gap Height = 25 mm
- Straight, Quad Bore Radius = 52 mm



- How big do we need? How much will real effects in magnets reduce the dynamic aperture?
- In Progress: random distribution of multipole errors on every quadrupole, e.g.

Modified CESR-c Wiggler

- Possible Benefits:
 - Larger Gap Height
 - Larger Pole Width
 - It's a real magnet!
- Modifications:
 - Lowered Peak Field
 - Lengthened Magnet
- In Progress...



Future Plans

- Identify non-linearities of ILC wiggler design which restrict the dynamic aperture
 - Investigate ILC wiggler options to maximize dynamic and physical aperture
 - Vary Pole Width
 - Vary Gap Height
 - Superconducting
- Modified CESR-c
Wiggler Design
- Move to experimental investigation with CESR-c