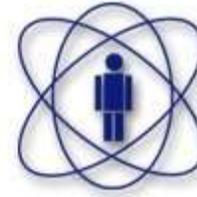


**PIERRE  
AUGER**  
OBSERVATORY



**CBPF**

# The Angular Resolution of the Pierre Auger Observatory

**Carla Bonifazi**

CBPF – CNRS/In2p3

**Pierre Auger Collaboration**

Vulcano Workshop 2006 - Frontier Objects in Astrophysics and Particle Physics  
May 21 – 27, Vulcano, Italy

## Objective

**Extract optimal arrival direction information**

# Angular Resolution for Surface Detector

# Angular Resolution for Surface Detector

- From experimental data

# Angular Resolution for Surface Detector

- From experimental data
- Using the information from the geometrical reconstruction

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---

*Ground*

# Angular Resolution for Surface Detector

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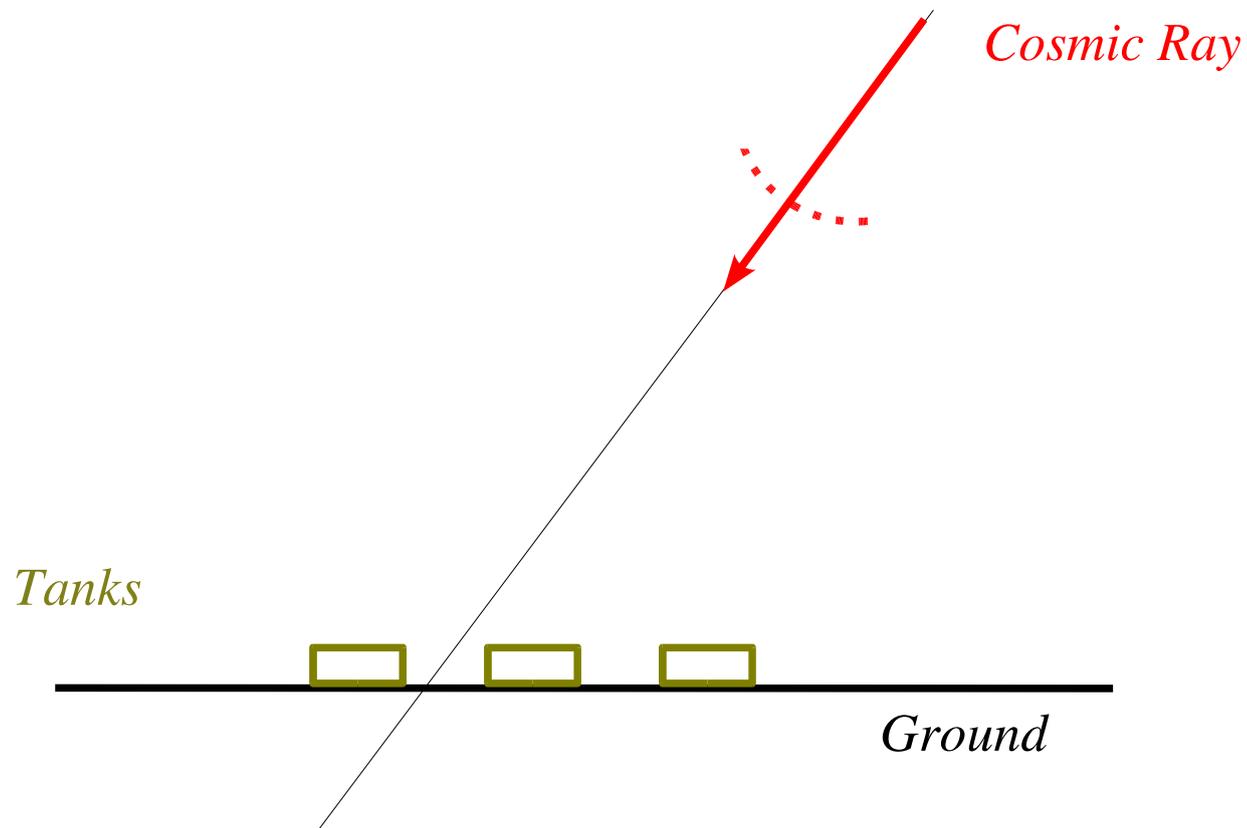
*Tanks*



*Ground*

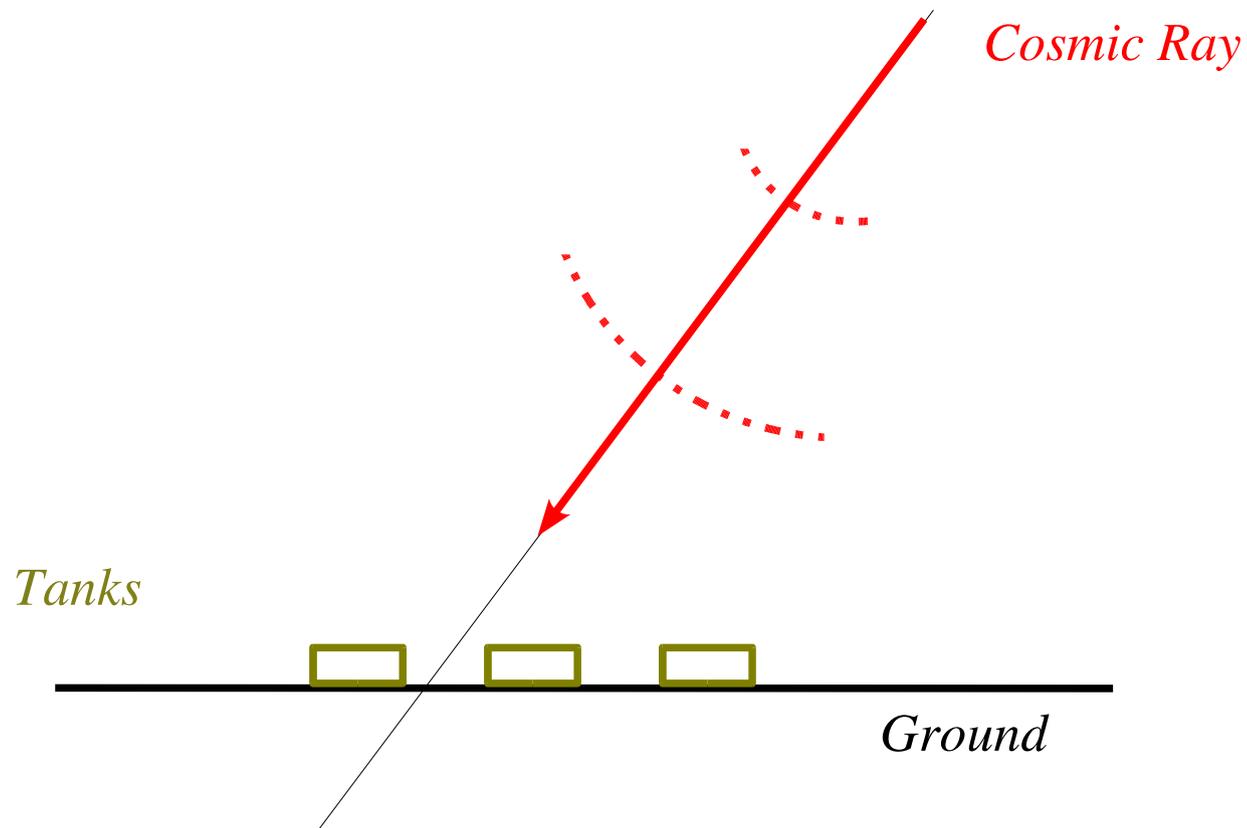
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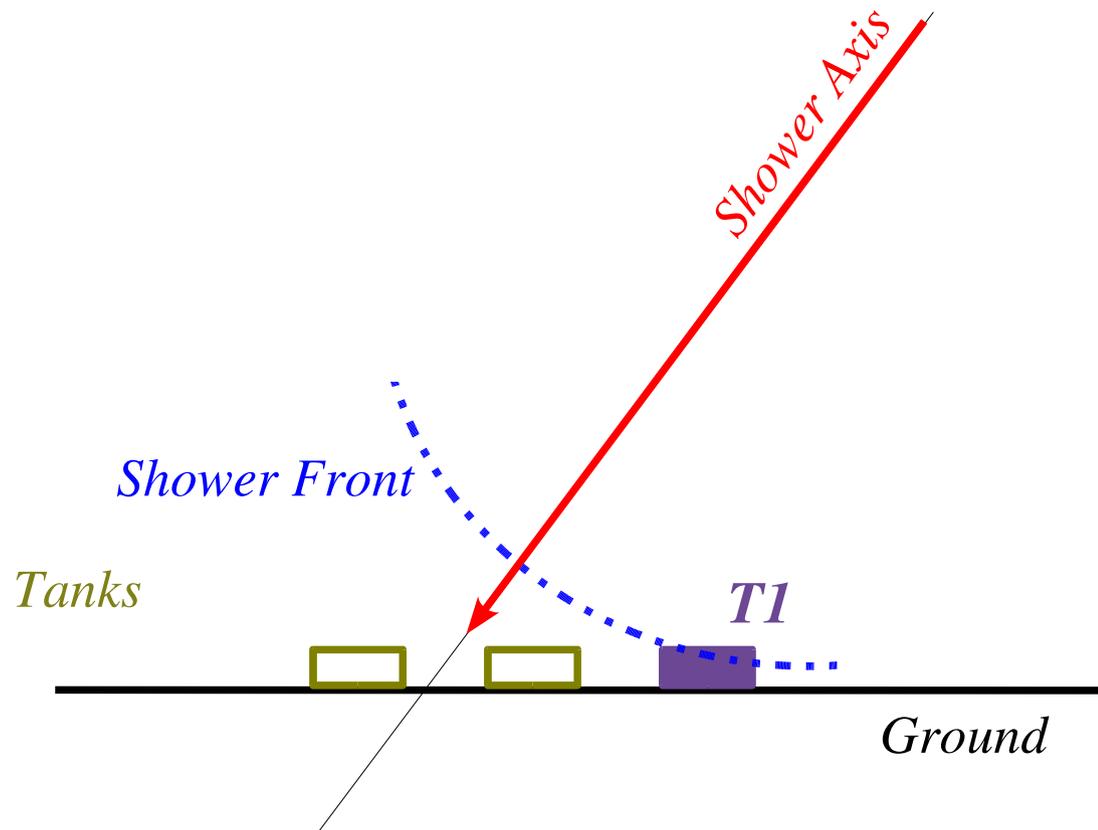
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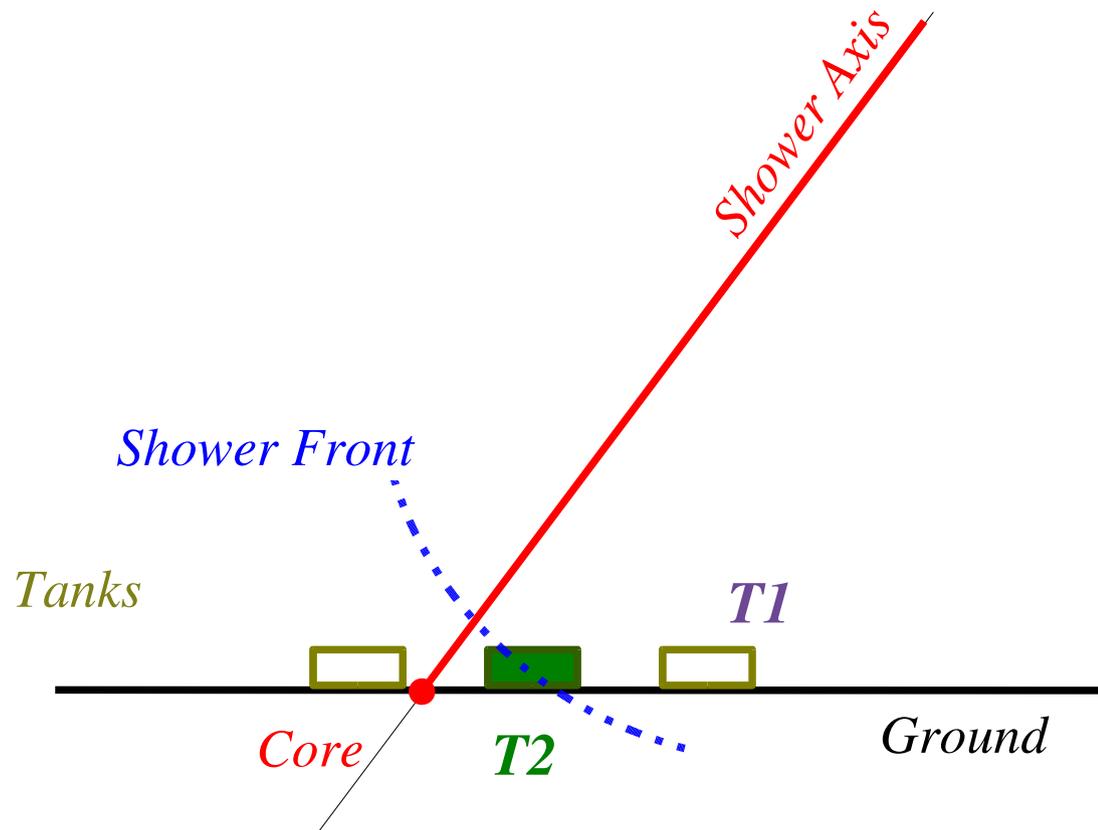
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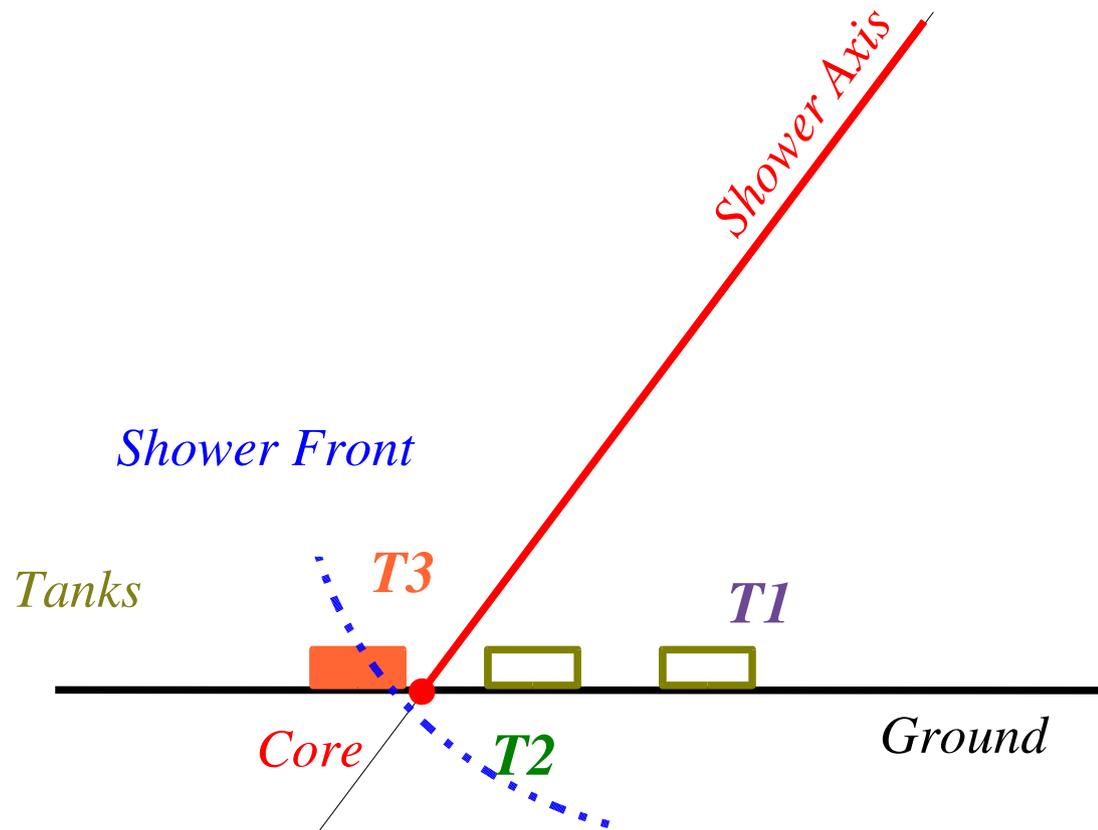
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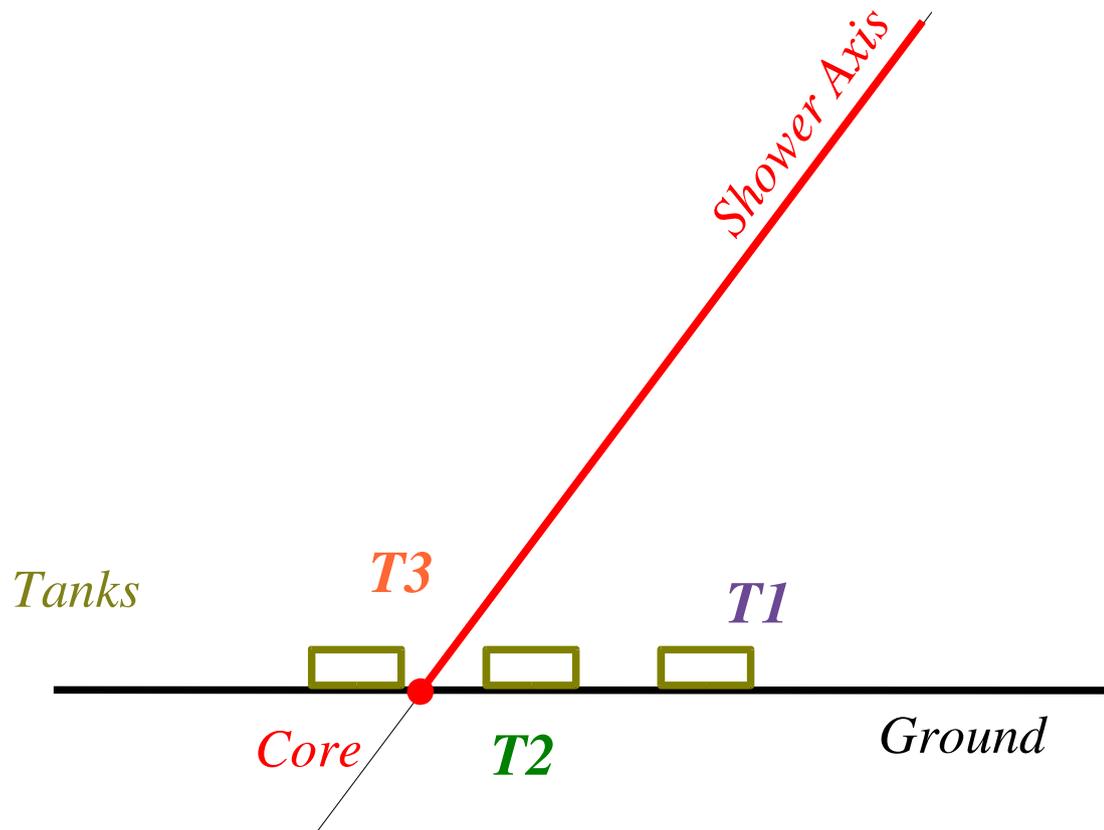
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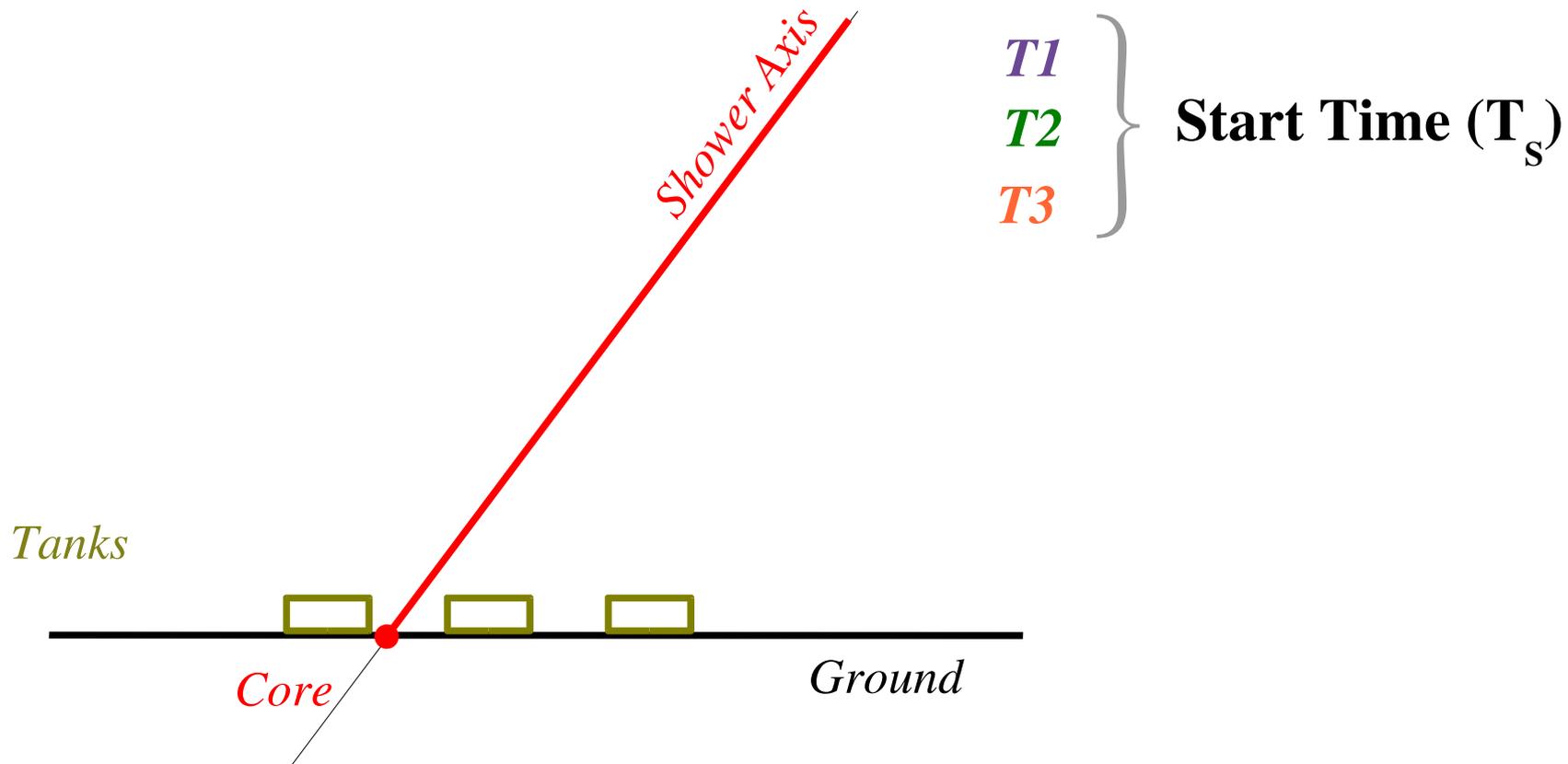
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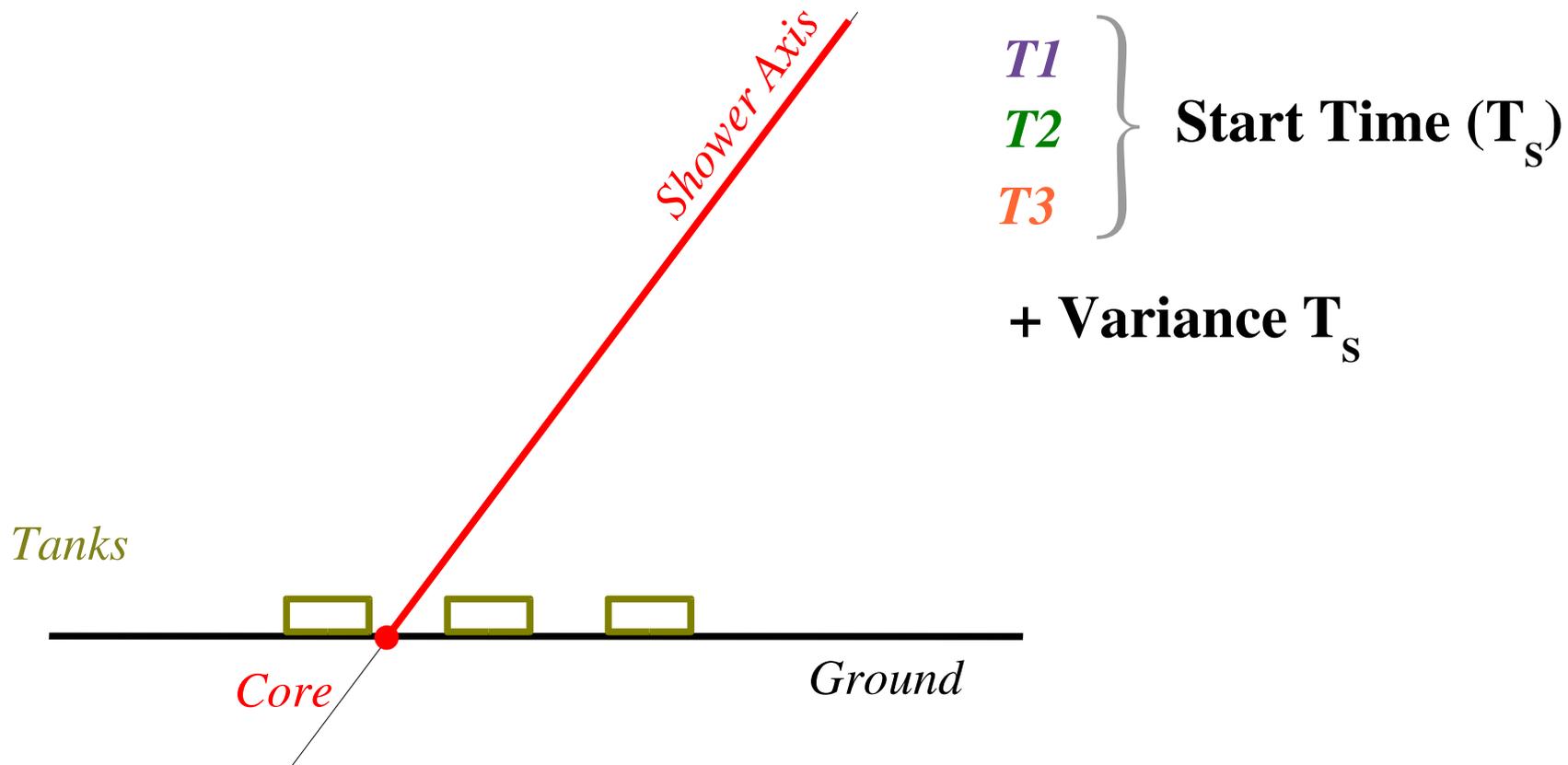
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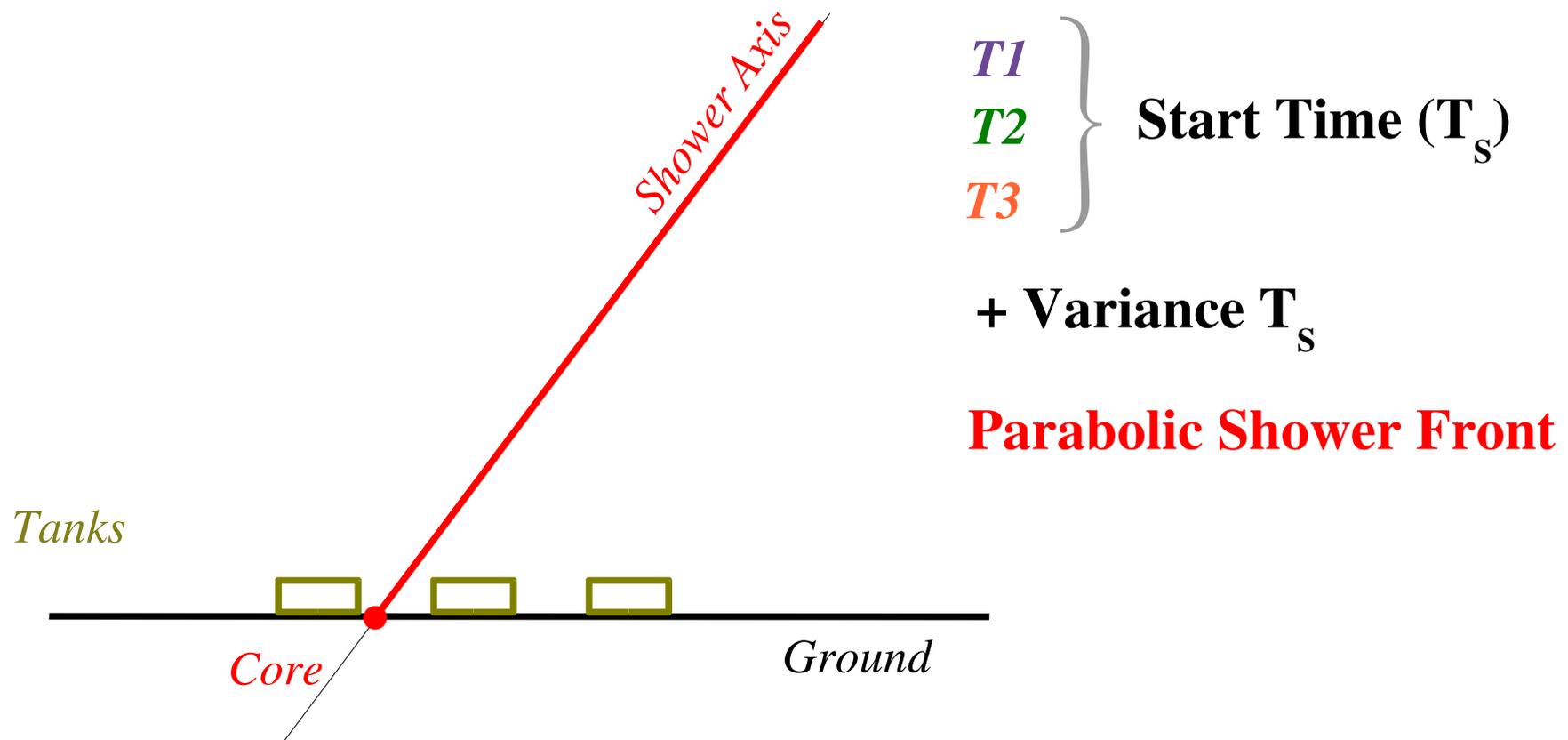
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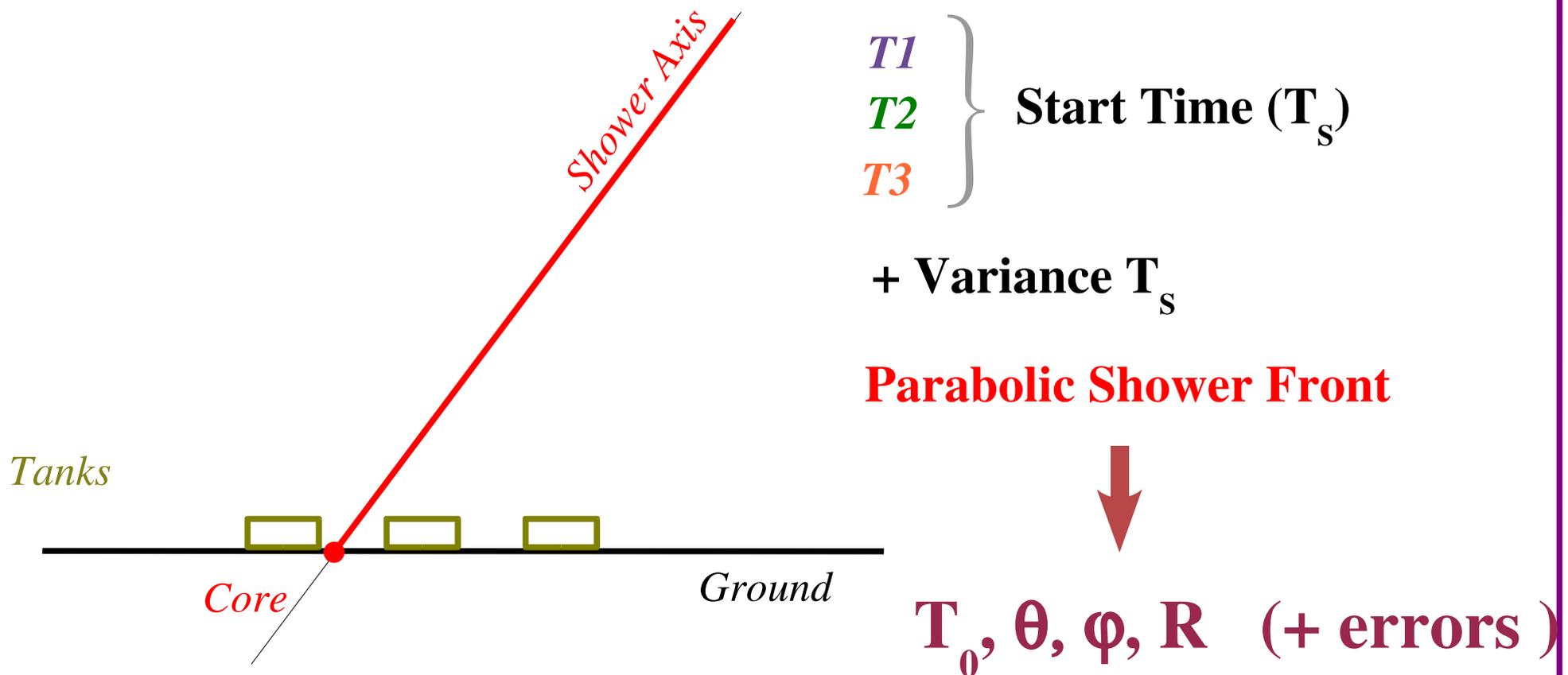
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# Angular Resolution

The Angular Resolution is defined by the angular radius contour that contains 68% of the event coming from a point source.

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$$F(\eta) = \frac{1}{2} ( V[\theta] + \sin^2(\theta) V[\phi] )$$

$\eta$  is the spacial angle

$\theta$  is the zenith angle

$\phi$  is the azimuth angle

If  $\theta$  and  $\phi/\sin^2(\theta)$  have Gaussian distribution with variance  $\sigma^2$ , then

$F(\eta) = \sigma^2$ , and  $\eta$  has distribution proportional to  $\exp \{-\eta^2/2\sigma^2\} d(\cos(\eta))d\phi$

The relation between  $\sigma$  and the angular resolution is: **AR = 1.5  $\sigma$**

# Angular Resolution from Experimental Data

**SD Resolution depends on:**

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**Data set:** January 2004 to March 2006

## Time Variance Model

Shower front described as a Poisson process (n particles arriving uniformly within time T)

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## Time Variance Model

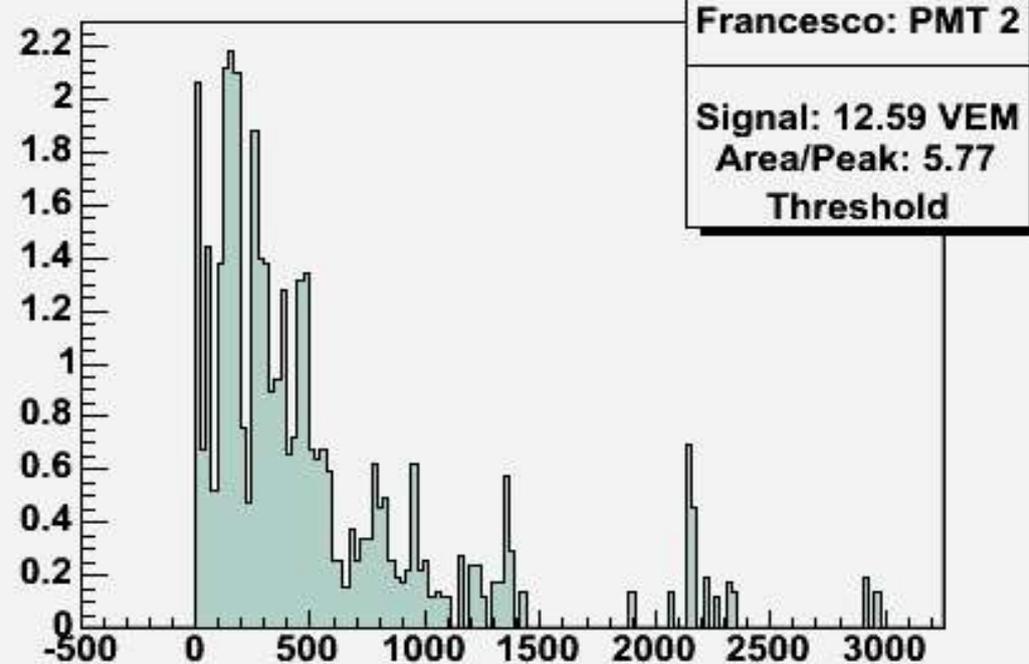
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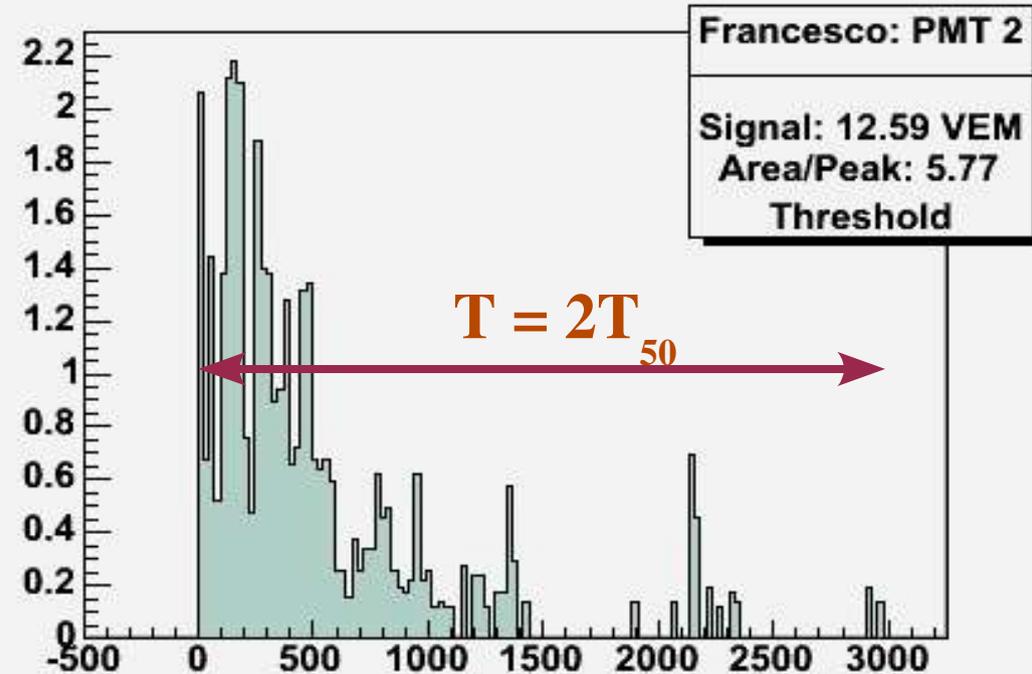
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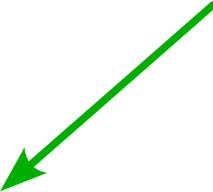
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$$\mathbf{n} = \frac{\mathbf{S}}{\mathbf{TL}(\theta)}$$

$\mathbf{S}$  = Integrated Signal in VEM

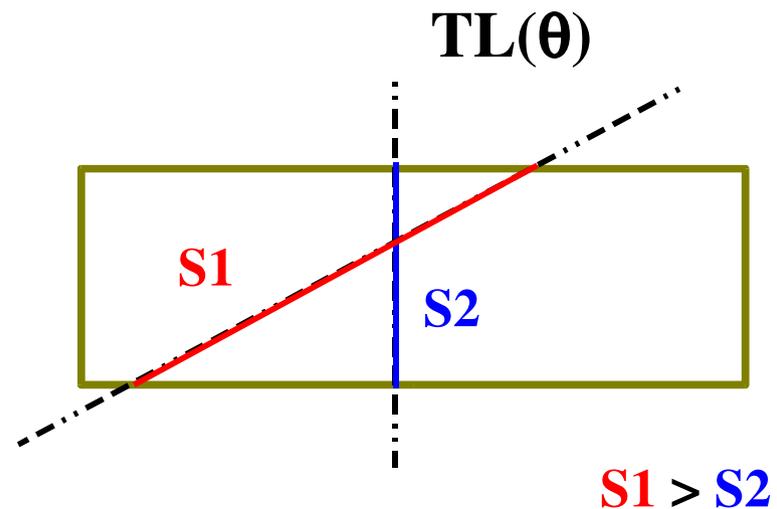
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# Time Variance Model

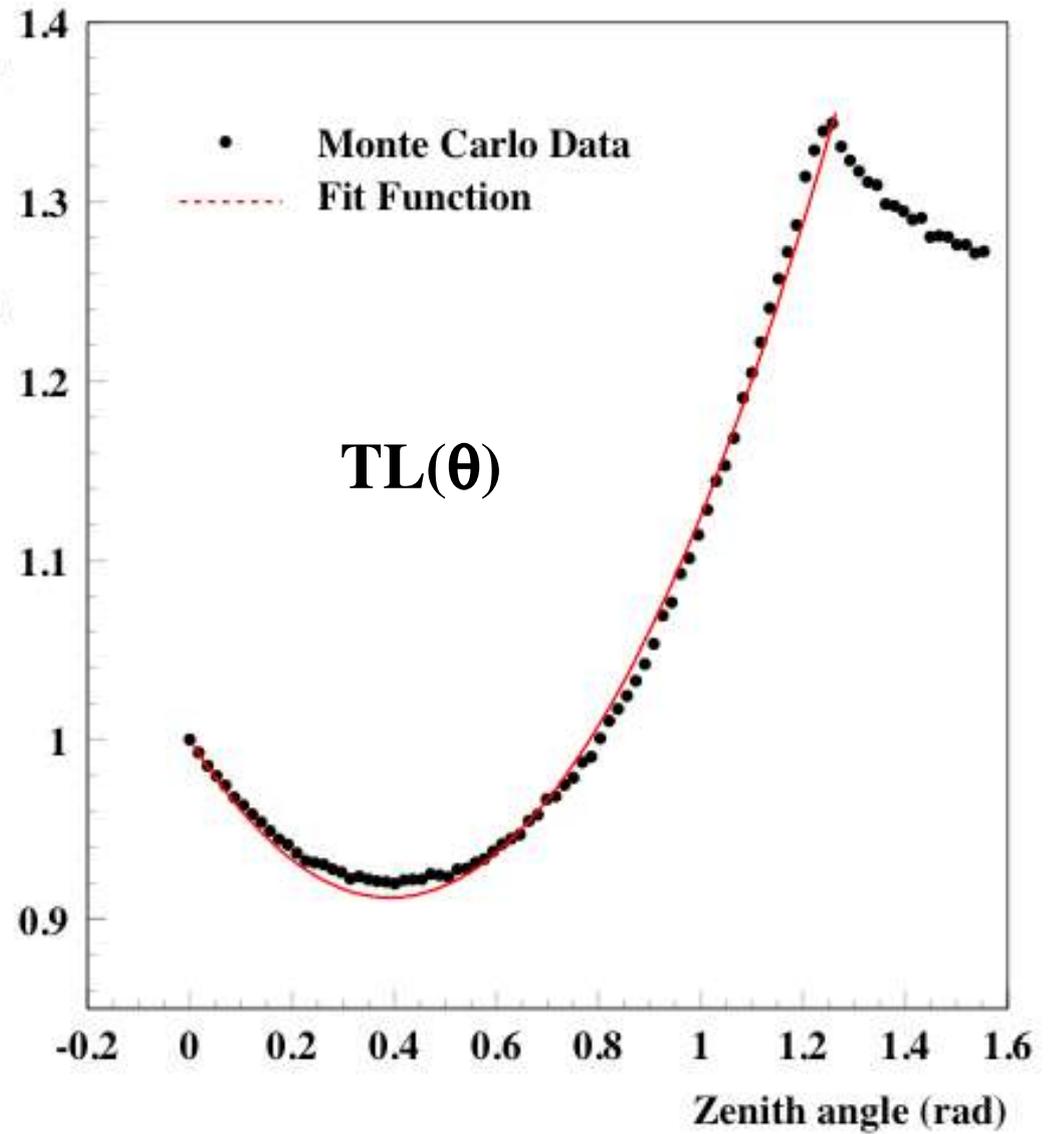
Shower front described as a Poisson process (n particles arriving uniformly within

$$V[T_s] = a^2 \left( \frac{2 T_{50}}{n} \right)^2$$

Average Track Length

$$n = \frac{S}{TL(\theta)}$$

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$$\mathbf{b} = 12 \text{ ns} = \sqrt{25^2/12 + 10^2} \quad (\text{FADC resolution} + \text{GPS accuracy})$$

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or adjusted on the doublet data...

# Doublets



$$\mathcal{L} = \prod_{k=1}^N \frac{1}{\sqrt{2\pi V[\Delta T_k]}} e^{-\frac{\Delta T_k^2}{2 V[\Delta T_k]}}$$

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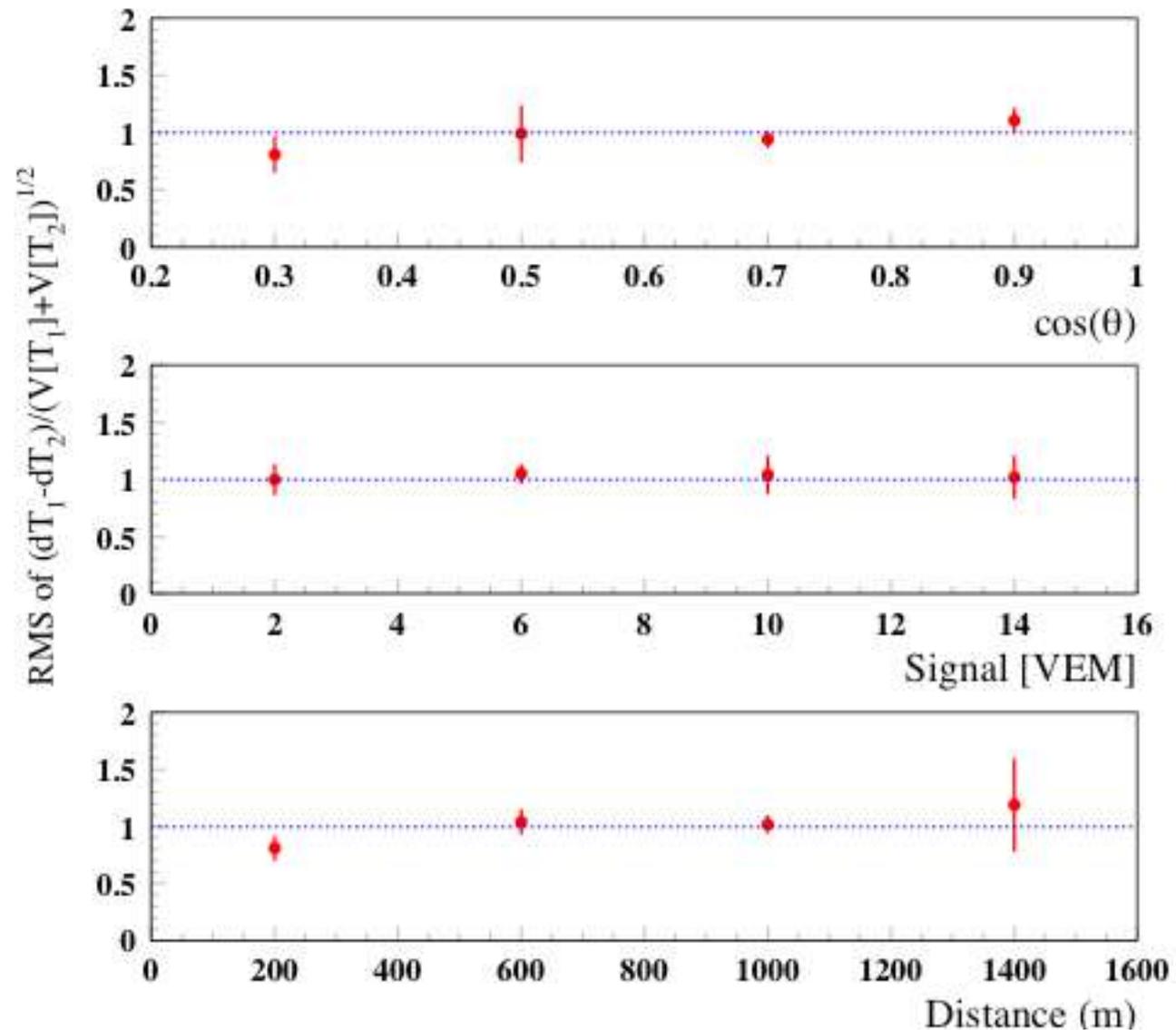
$$\mathbf{a} = 1.00 \pm 0.03$$

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**Extraordinarily consistent !**

# Doublets

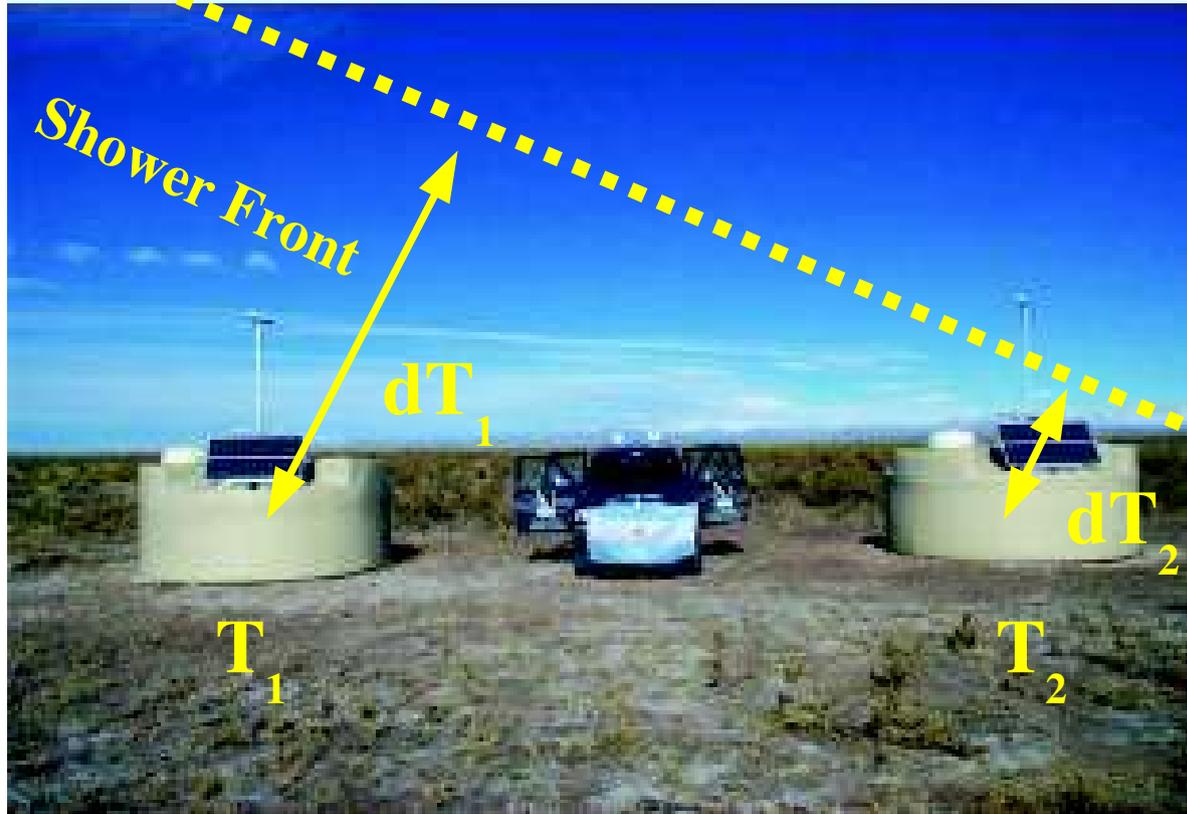
Verifying model quality on doublet data:



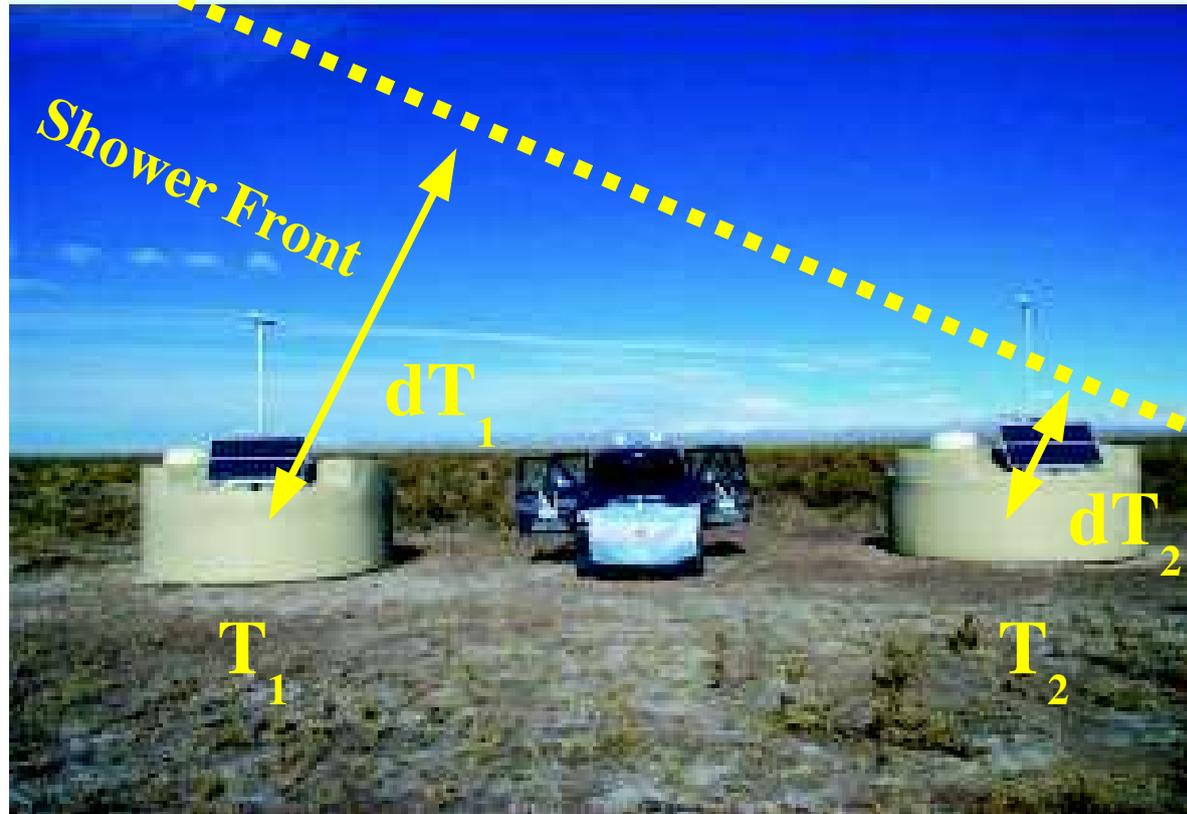
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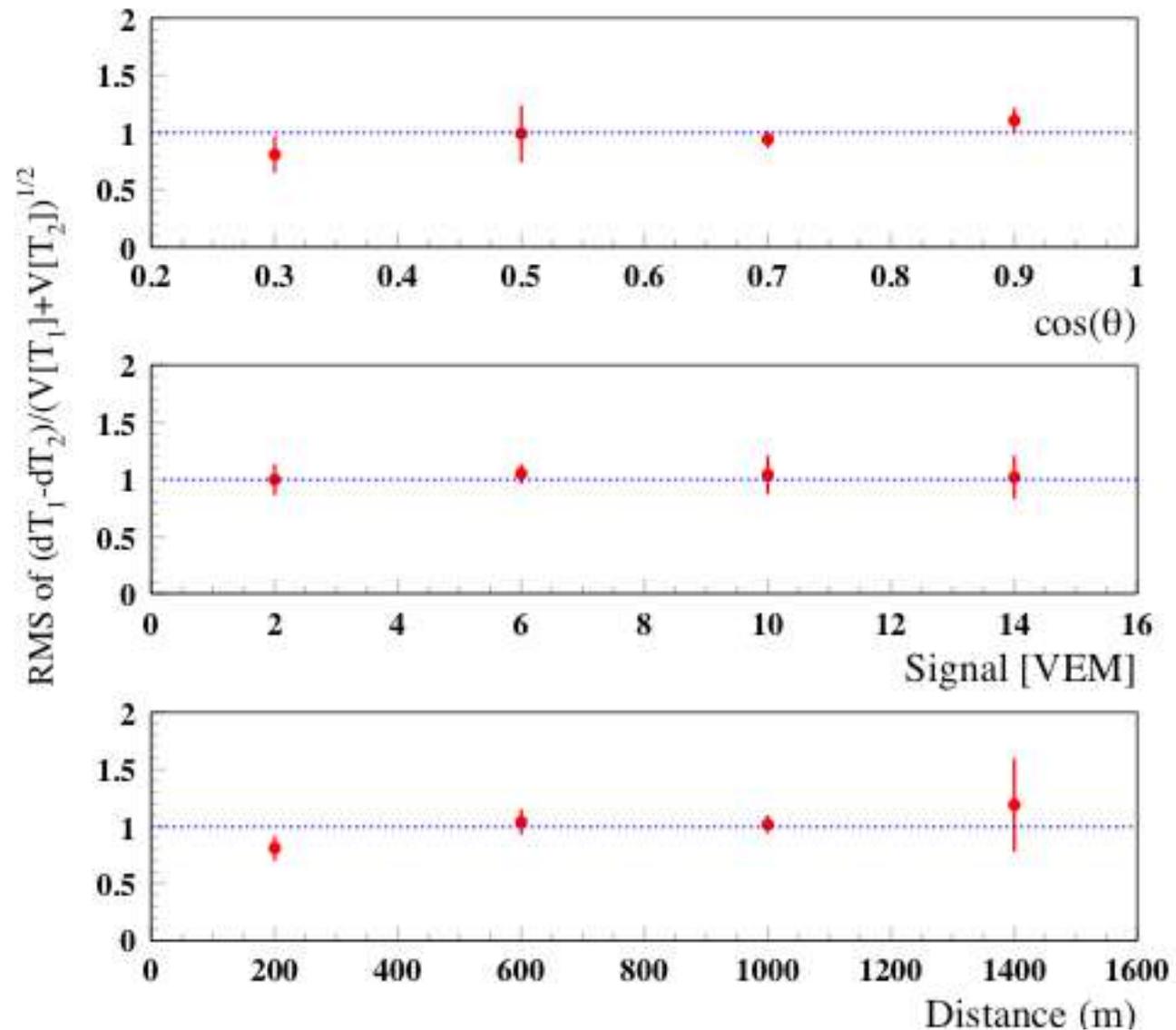
# Doublets



$$\frac{dT_1 - dT_2}{\sqrt{V[T_1] + V[T_2]}}$$

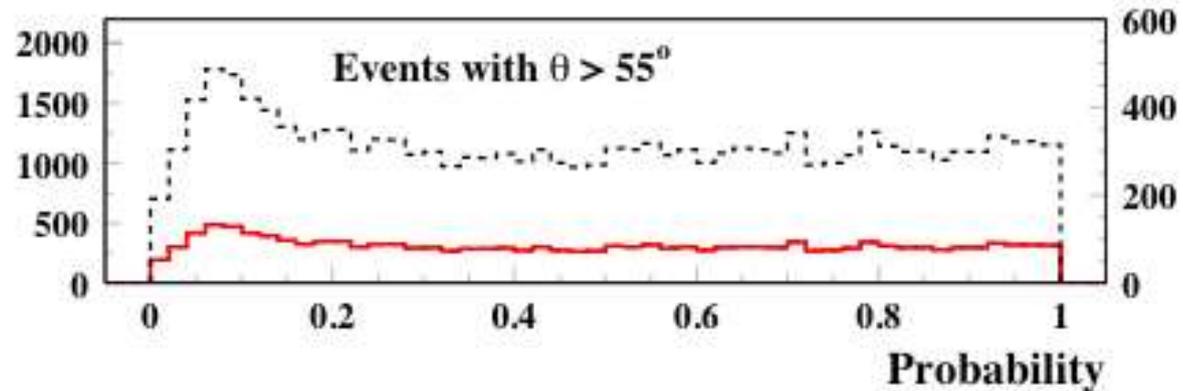
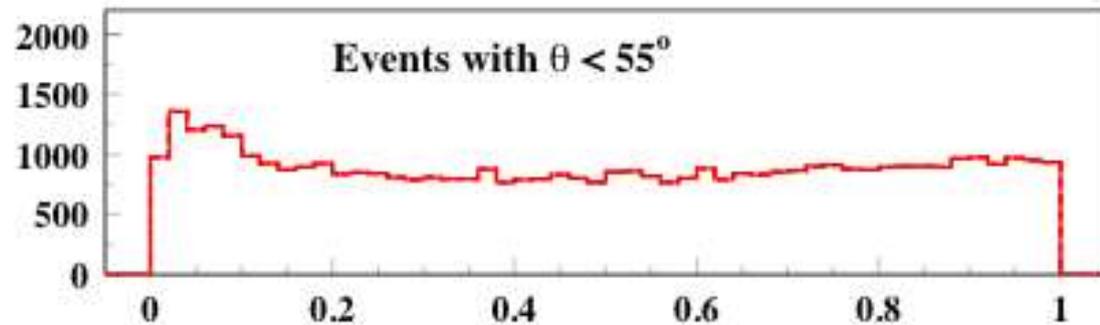
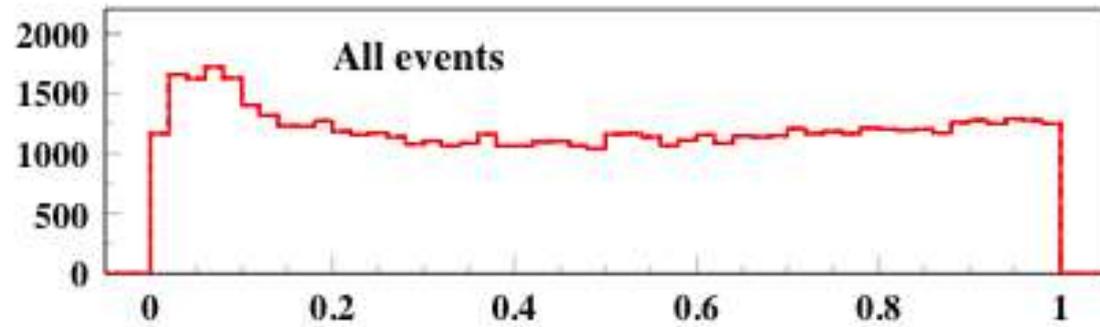
# Doublets

Verifying model quality on doublet data:



# All Data

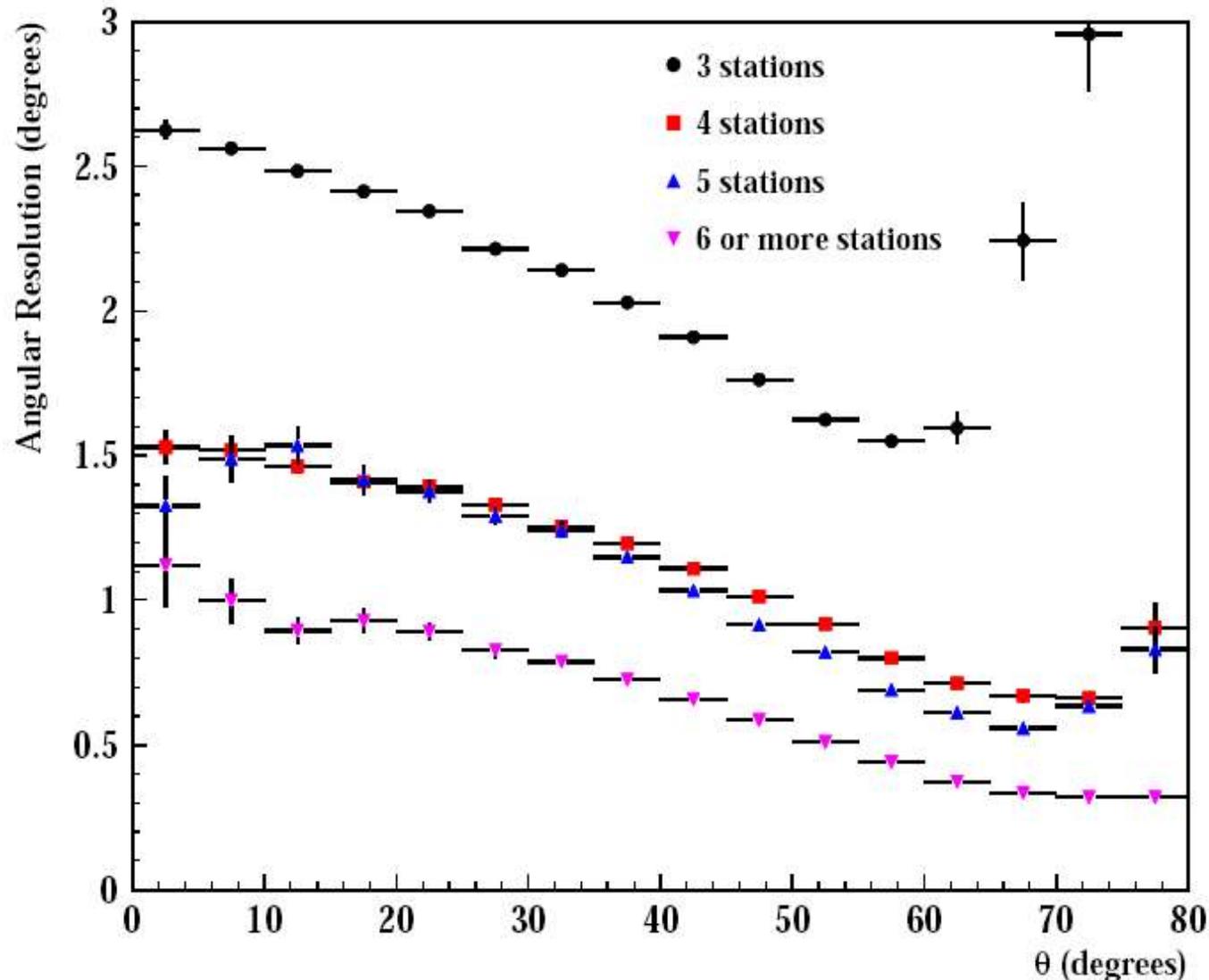
$\chi^2$  probability distribution:



# All Data

$$AR = 1.5 \sqrt{(V[\theta] + V[\varphi]\sin^2(\theta))/2}$$

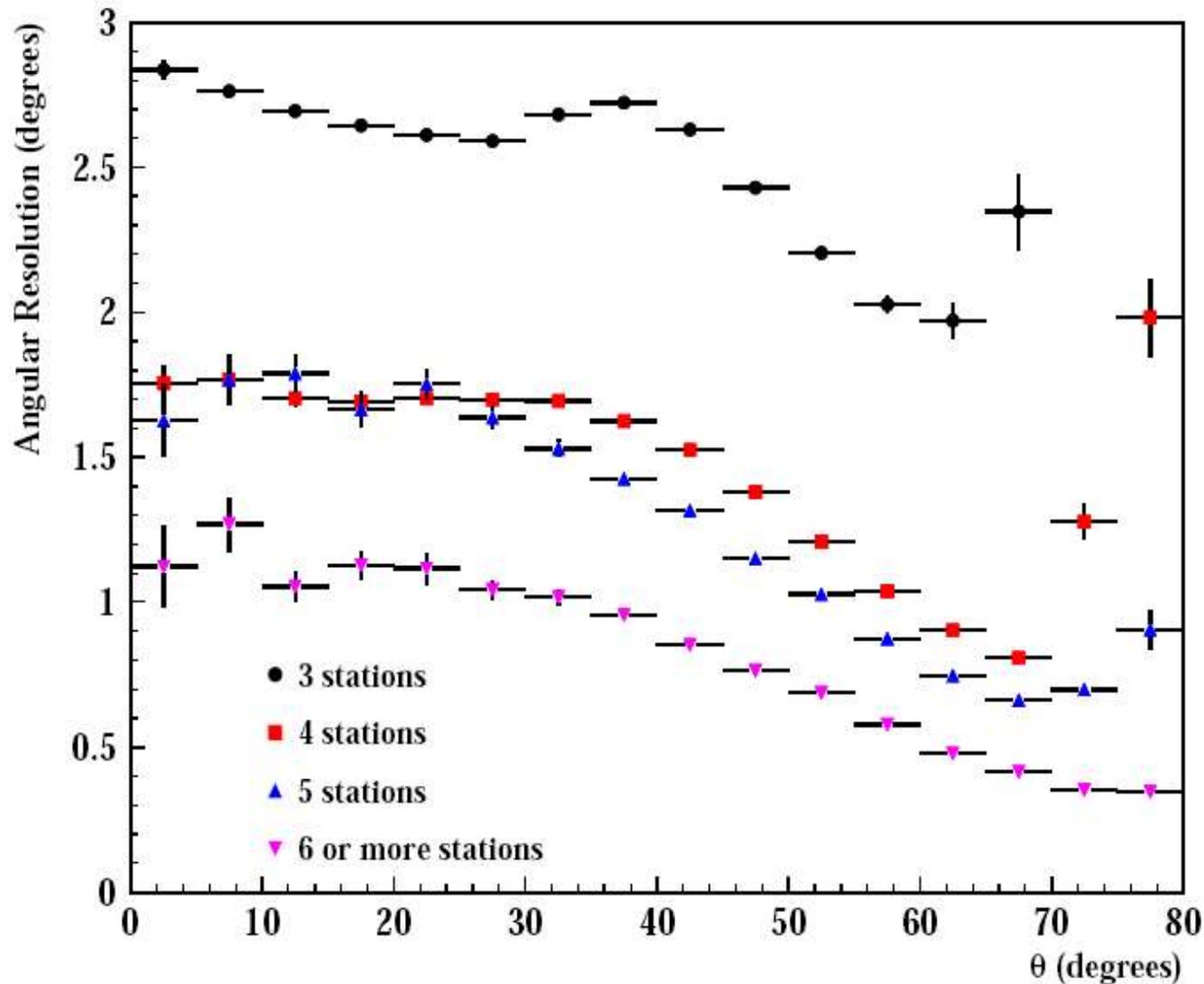
Resolution extracted from the **geometrical reconstruction**



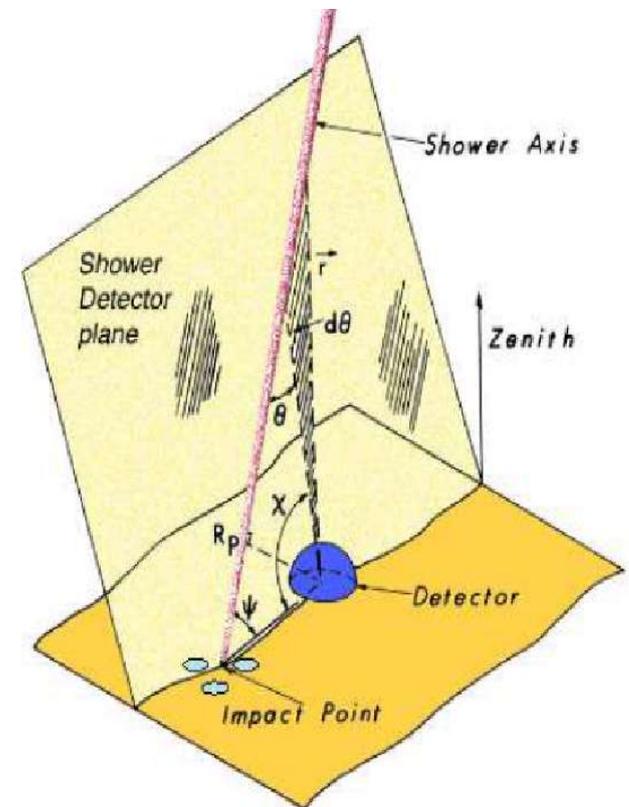
# All Data

$$AR = 1.5 \sqrt{(V[\theta] + V[\phi]\sin^2(\theta))/2}$$

Resolution extracted from the **full reconstruction**

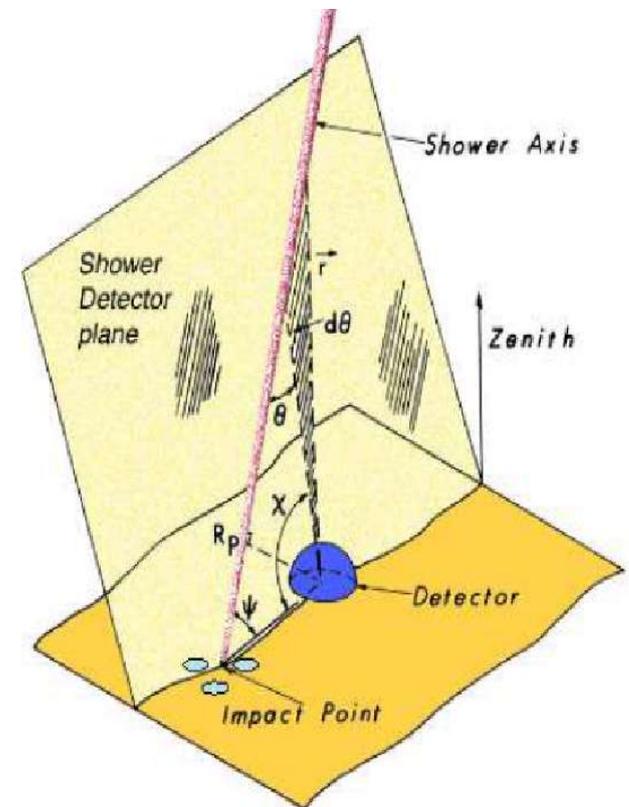


# Comparison with hybrid data

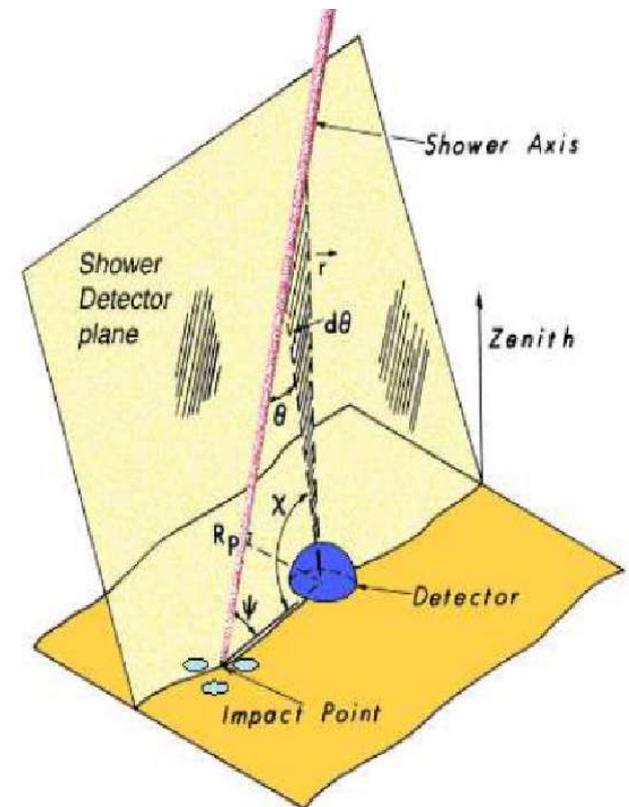


# Comparison with hybrid data

**Miguel Mostafá**  
**(next talk)**

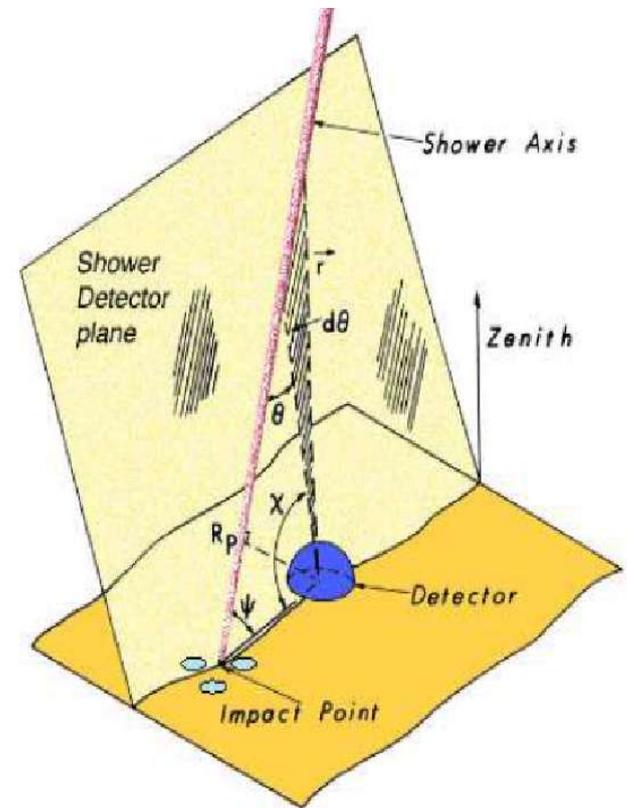


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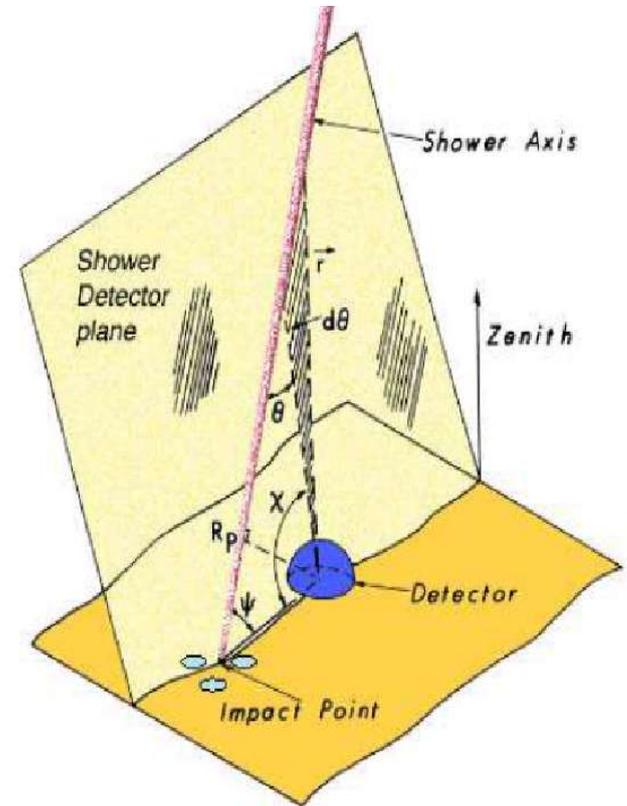
## Comparison with hybrid data

- Good angular resolution in the arrival direction



# Comparison with hybrid data

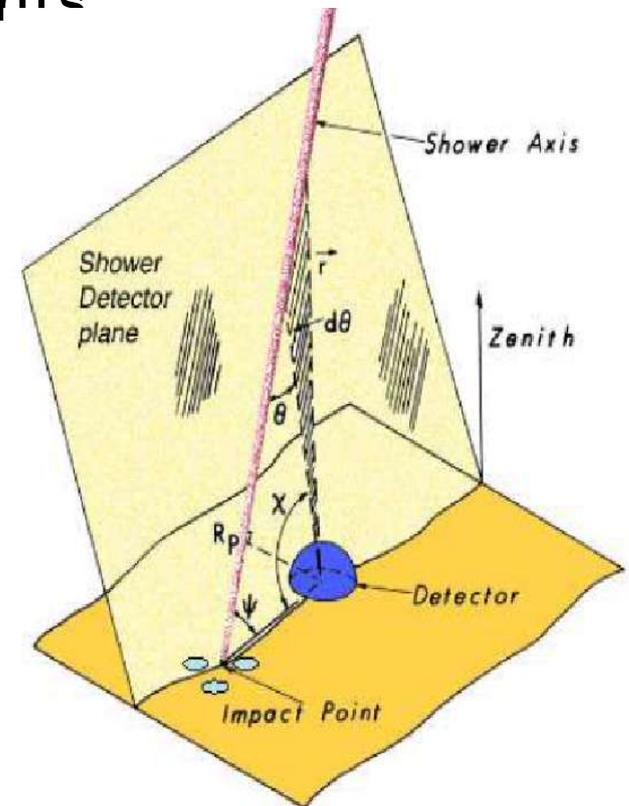
- Good angular resolution in the arrival direction
- Low statistics



## Comparison with hybrid data

- Good angular resolution in the arrival direction
- Low statistics

Angular resolution for hybrid events was obtained with the same formula used for SD-only events

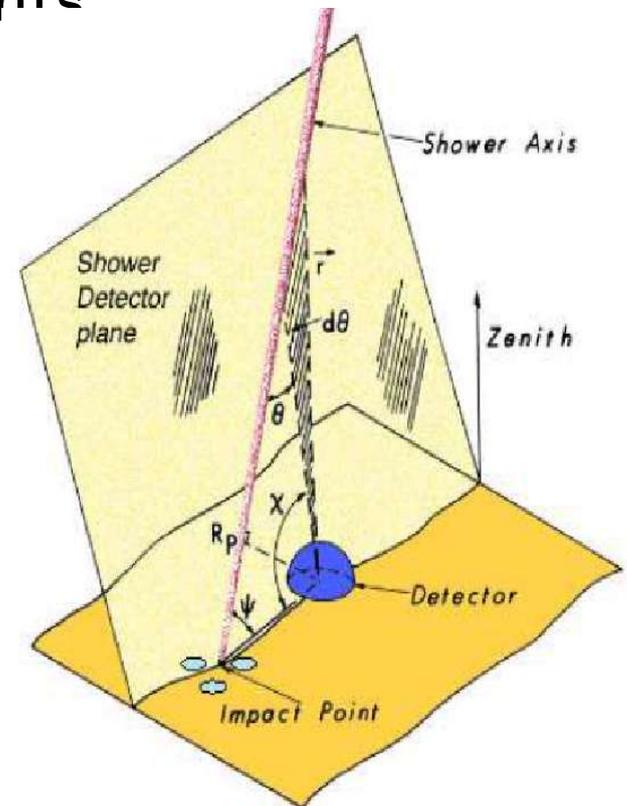


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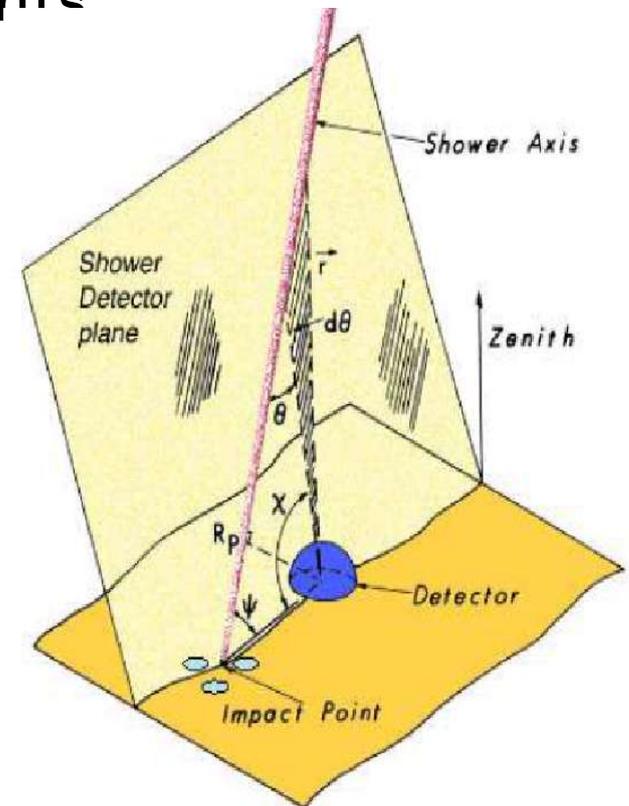
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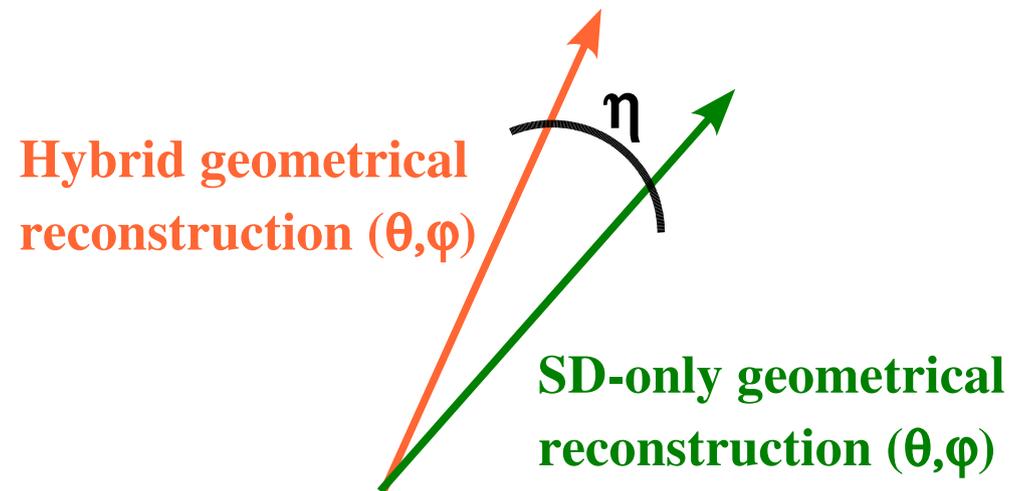
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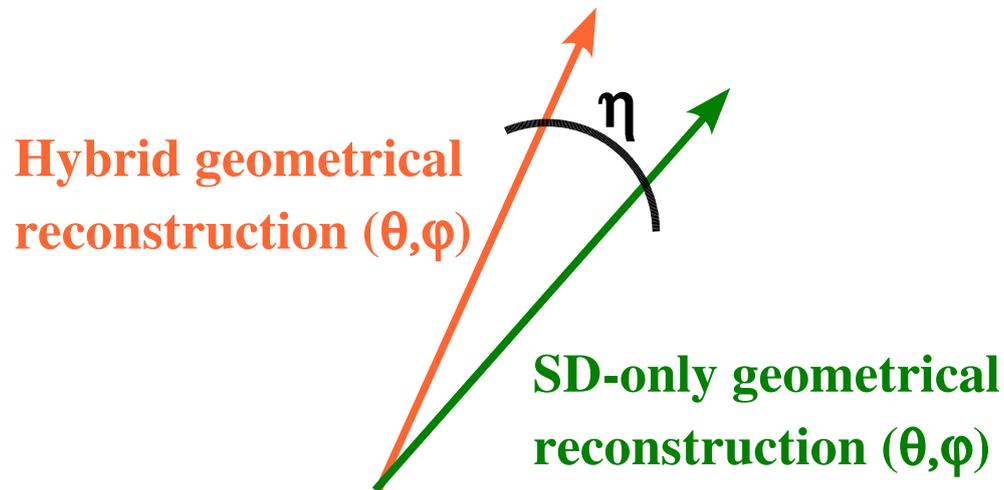
| <u># Tank</u> | <u>AR</u> |
|---------------|-----------|
| 3             | 0.8°      |
| 4             | 0.7°      |
| 5             | 0.6°      |
| ≥ 6           | 0.5°      |



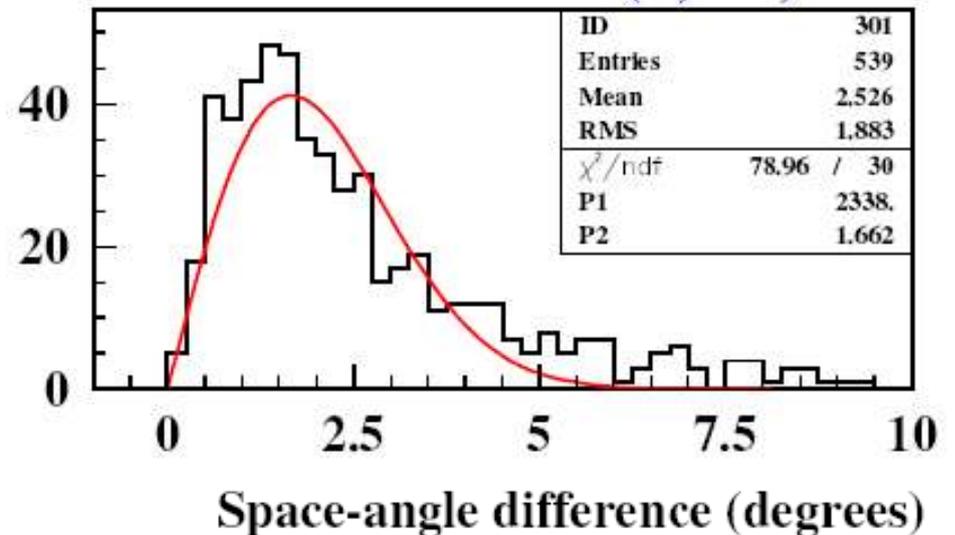
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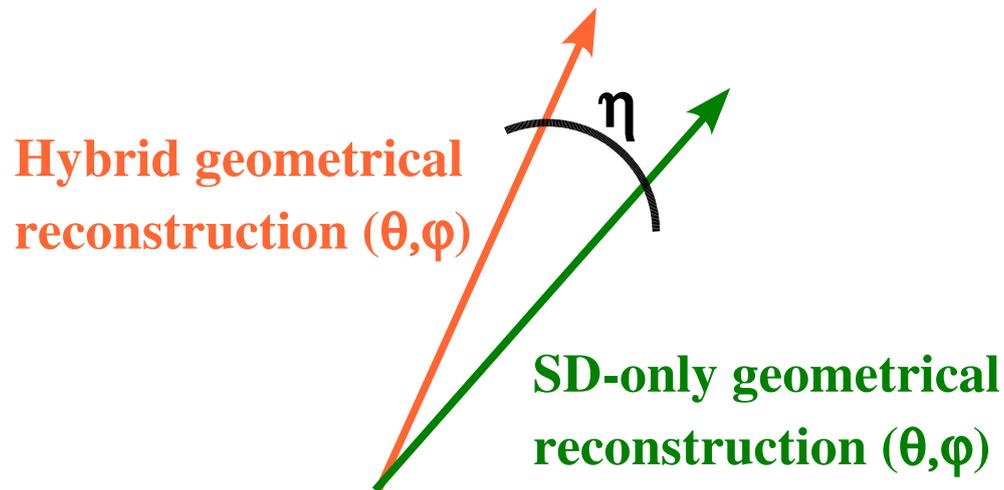
# Comparison with hybrid data



3 stations -  $\theta \in (0, 30)$

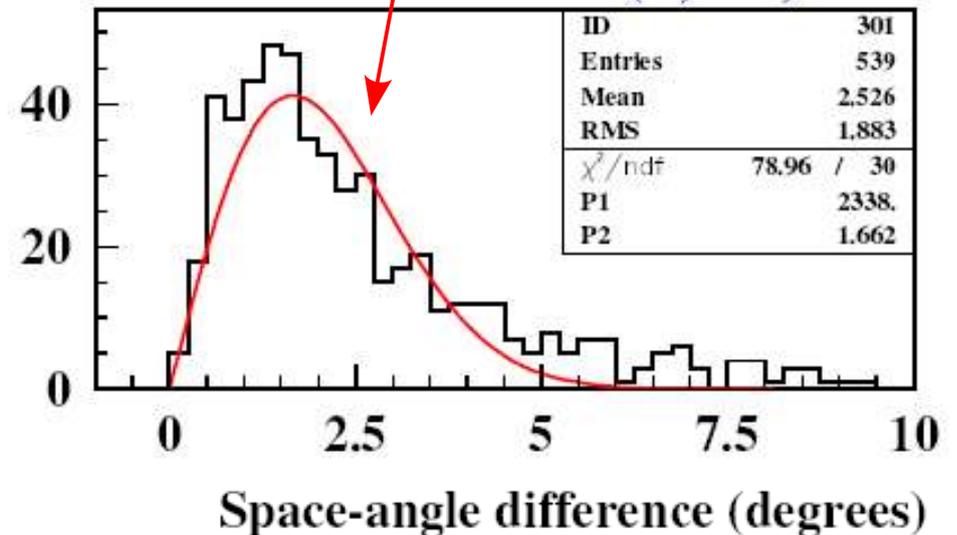


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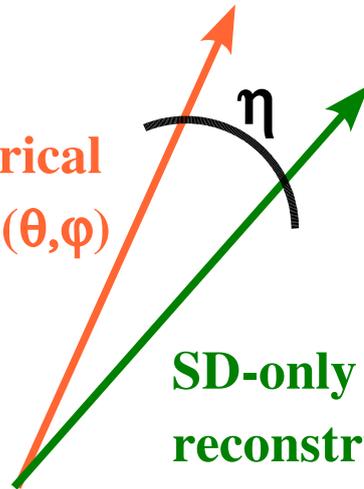
$$e^{-\eta^2/2\sigma^2} d(\cos(\eta))d\phi,$$

3 stations -  $\theta \in (0, 30)$



# Comparison with hybrid data

Hybrid geometrical reconstruction ( $\theta, \phi$ )

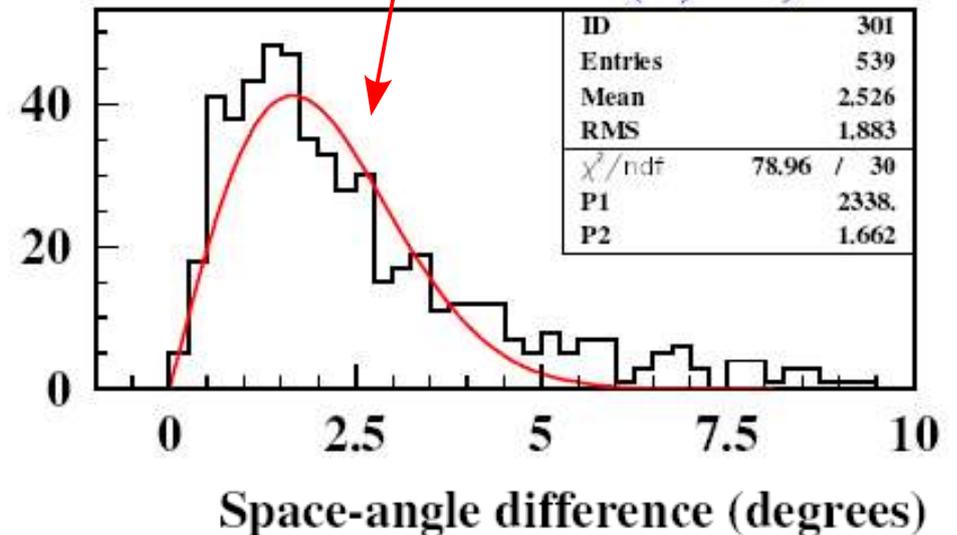


SD-only geometrical reconstruction ( $\theta, \phi$ )

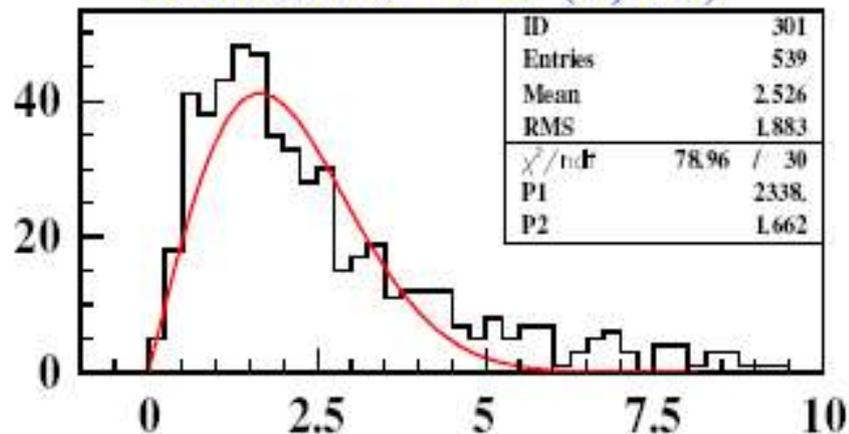
$$e^{-\eta^2/2\sigma^2} d(\cos(\eta))d\phi,$$

$$\sigma_{SD} = \sqrt{(\sigma_{\eta}^2 - \sigma_{Hyb}^2)}$$

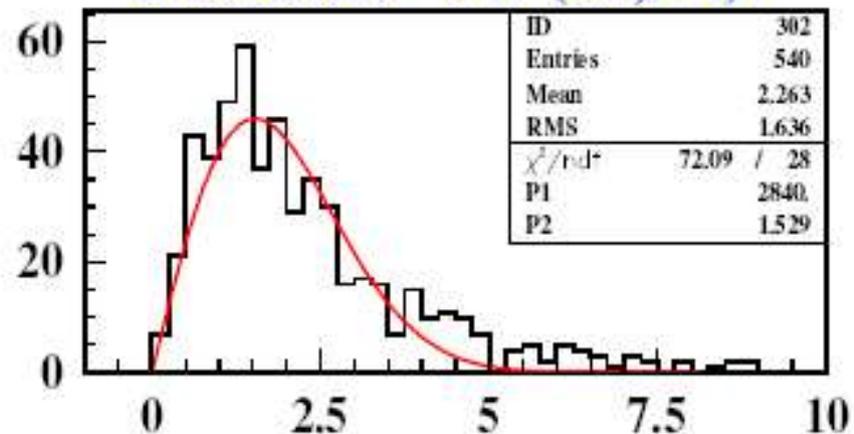
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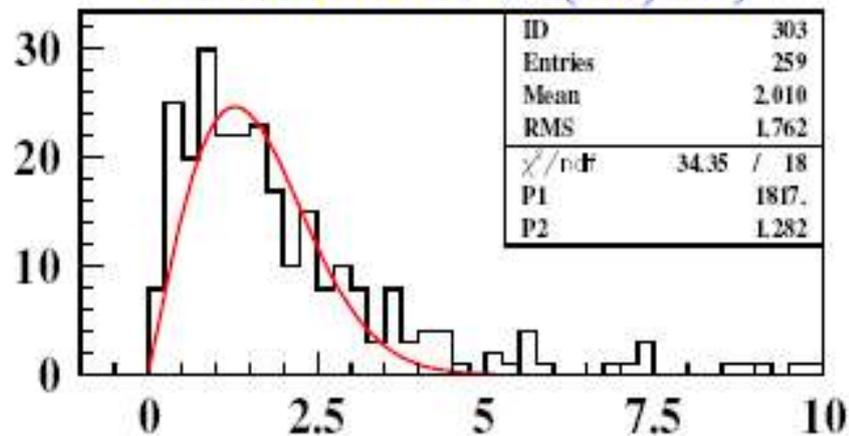
3 stations -  $\theta \in (0, 30)$



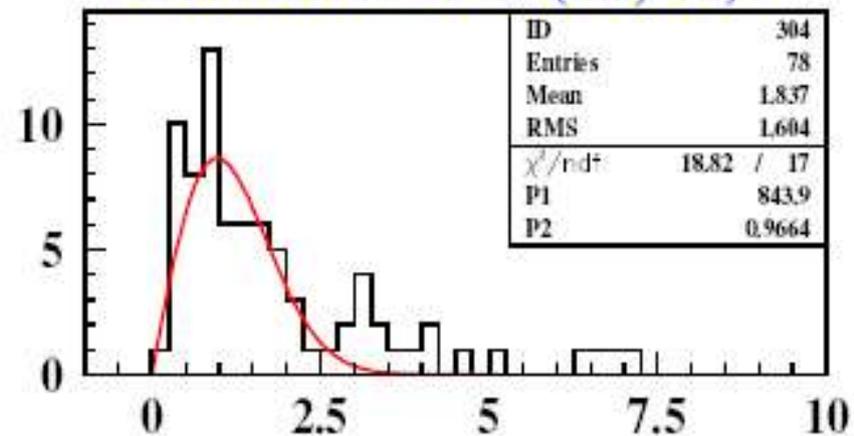
3 stations -  $\theta \in (30, 50)$



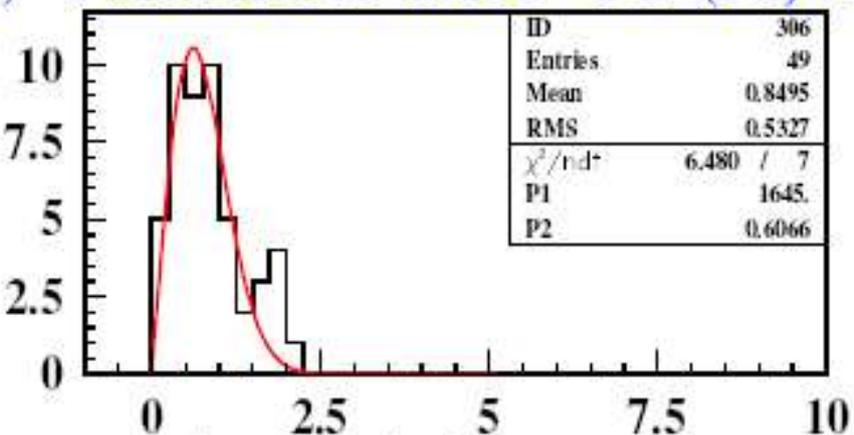
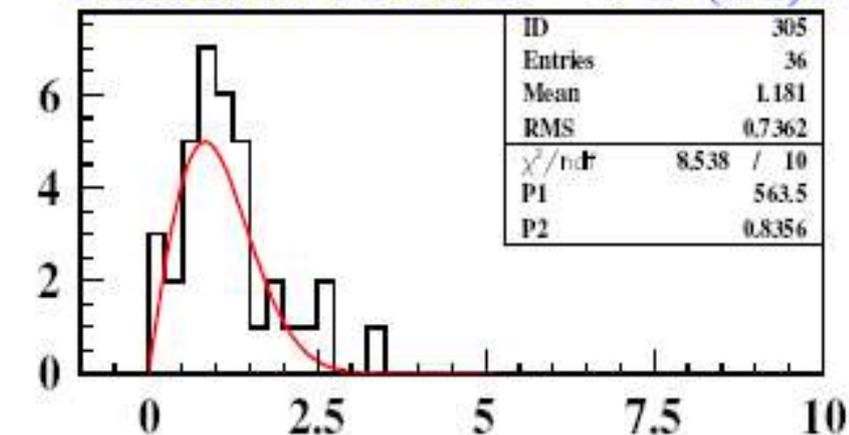
4 stations -  $\theta \in (30, 50)$



5 stations -  $\theta \in (30, 50)$



6 stations or more -  $\theta \in (30, 50)$     6 stations or more -  $\theta \in (50, 70)$



Space-angle difference (degrees)

## Comparison with hybrid data

| # Stations | $\theta$ range | $\sigma_{\eta}$ | $\sigma_{Hyb}$ | $\sigma_{SD-only}$ | $\sigma_{SD}$ from $\sigma_{\eta}$ |
|------------|----------------|-----------------|----------------|--------------------|------------------------------------|
| 3          | [0°; 30°]      | 1.7°            | 0.6°           | 1.8°               | 1.6°                               |
| 3          | [30°; 50°]     | 1.5°            | 0.6°           | 1.8°               | 1.4°                               |
| 4          | [30°; 50°]     | 1.3°            | 0.5°           | 1.1°               | 1.2°                               |
| 5          | [30°; 50°]     | 1.0°            | 0.4°           | 1.0°               | 0.9°                               |
| 6 or more  | [30°; 50°]     | 0.8°            | 0.4°           | 0.6°               | 0.7°                               |
| 6 or more  | [50°; 70°]     | 0.6°            | 0.3°           | 0.4°               | 0.5°                               |

## Comparison with hybrid data

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|------------|----------------|-----------------|----------------|--------------------|------------------------------------|
| 3          | [0°; 30°]      | 1.7°            | 0.6°           | 1.8°               | 1.6°                               |
| 3          | [30°; 50°]     | 1.5°            | 0.6°           | 1.8°               | 1.4°                               |
| 4          | [30°; 50°]     | 1.3°            | 0.5°           | 1.1°               | 1.2°                               |
| 5          | [30°; 50°]     | 1.0°            | 0.4°           | 1.0°               | 0.9°                               |
| 6 or more  | [30°; 50°]     | 0.8°            | 0.4°           | 0.6°               | 0.7°                               |
| 6 or more  | [50°; 70°]     | 0.6°            | 0.3°           | 0.4°               | 0.5°                               |

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**Thank you !**