

# A Data Acquisition System for Transverse Dynamics Measurements

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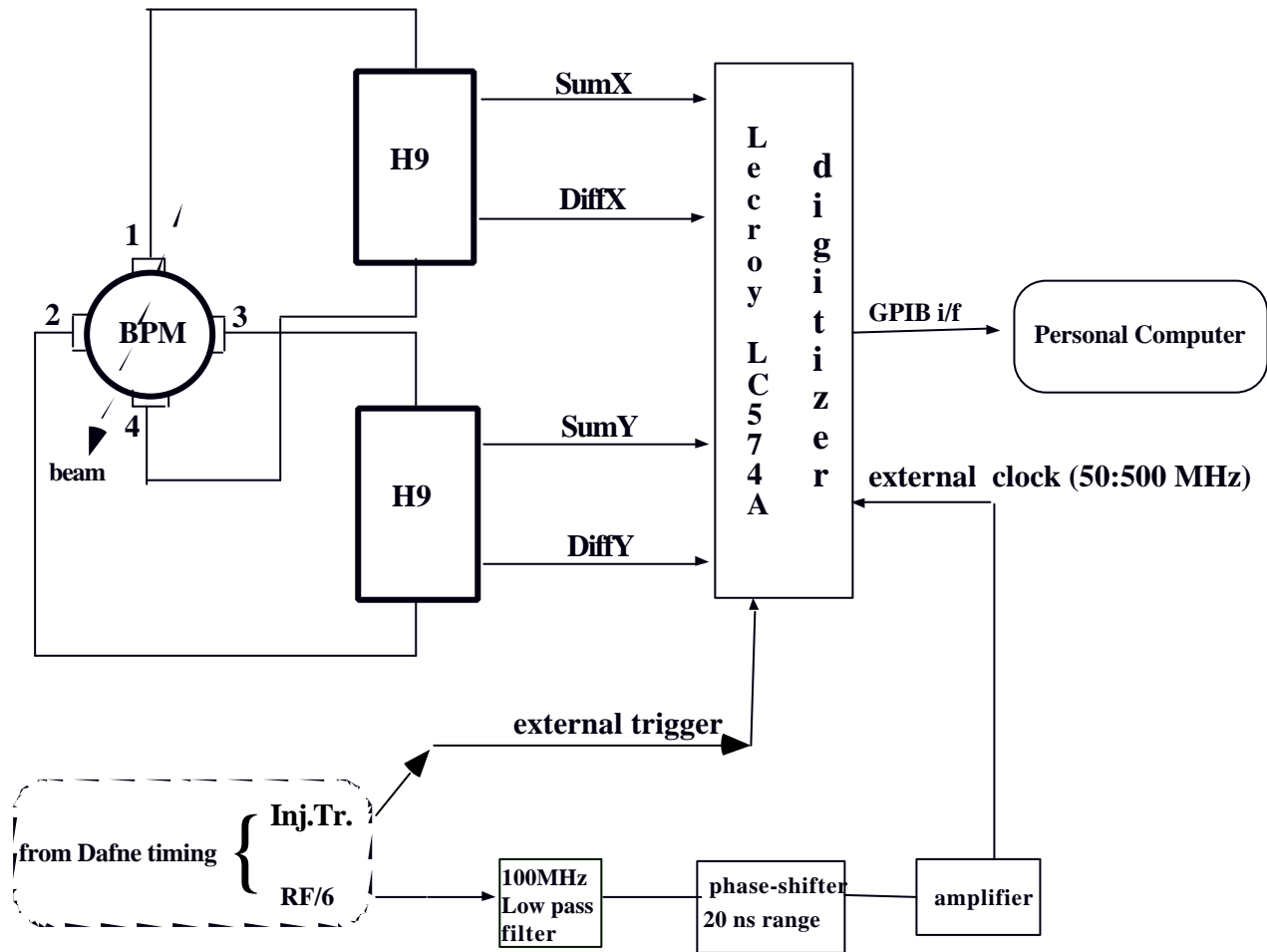
INFN-LNF, Frascati, Italy

- Aim of this presentation is to describe a transverse dynamic tracking data acquisition system.
- In the DaΦne  $\phi$ -Factory, the high Luminosity asks for a careful tune-up of many machine parameters.
- It is useful to study the transverse dynamic behavior of the beam versus different sextupole and octupole magnet setups.

# Basics

- A four button BPM is used to obtain sum and difference signals in the horizontal and vertical transverse planes (of the beam motion).
- A second BPM with a suitable betatron phase advance in respect of the first one can be used to obtain sum and difference signals relative to the passage of the bunch in an other point of the ring.
- After kicking the beam, these signals are sampled and acquired at every turn (up to 25k), converted in mm and stored in a data-base.

# The Acquisition System



# The Digitizer



- LeCroy LC584AM Digital Oscilloscope
- Built around a PowerPC working @ 96MHz
- Floppy Disk, 16 M RAM
- IEEE 488 parallel i/f
- RS232 serial i/f
- VGA out connector
- 1 GHz Bandwidth
- 4 Acquisition channels
- 8GS/s (2 GS/s per channel)
- 2M points acquisition memory (500k points per channel)
- External trigger, external clock

# Through the VGA out port the signals acquired are shown in the control room

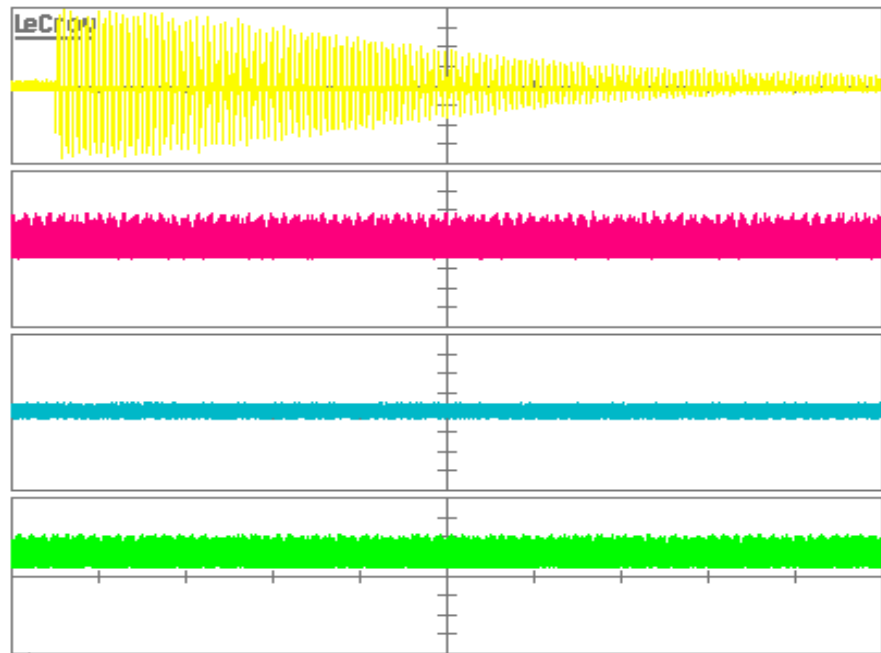
14-Oct-02  
15:37:40

1  
2 kS  
5.0 mV

2  
2 kS  
100 mV

3  
2 kS  
20.0 mV

4  
2 kS  
100 mV



$\Delta H$

$\Sigma H$

$\Delta V$

$\Sigma V$

External

1 5 mV 50Ω  
2 .1 V 50Ω  
3 20 mV 50Ω  
4 .1 V 50Ω



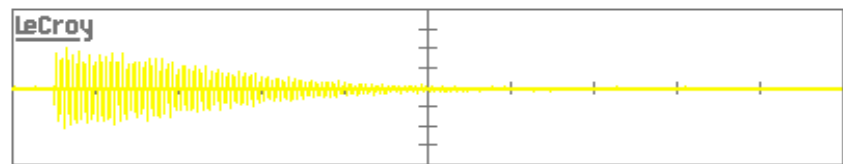
Ext DC -0.400 V 50Ω

EXT  
 NORMAL

# It is easy to check what happens after a kick (horiz. in this case)

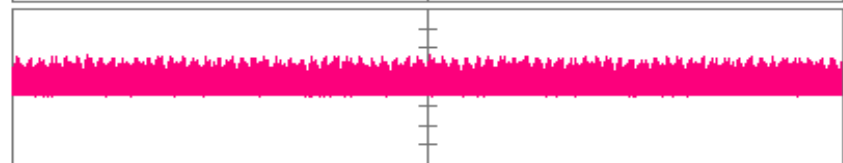
14-Oct-02  
15:42:06

1  
2 kS  
20.0mV



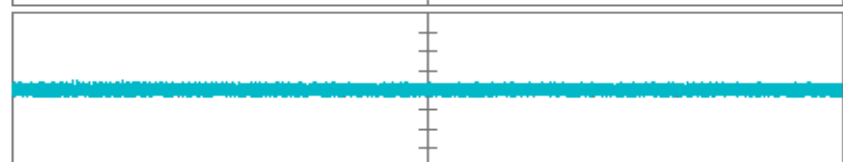
$\Delta H$

2  
2 kS  
100mV



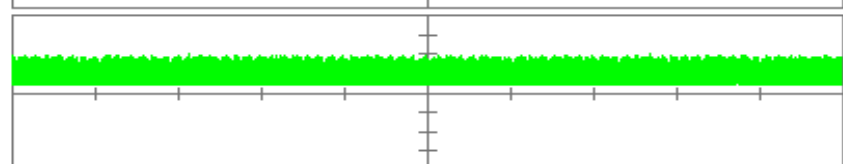
$\Sigma H$

3  
2 kS  
20.0mV



$\Delta V$

4  
2 kS  
100mV



$\Sigma V$

External

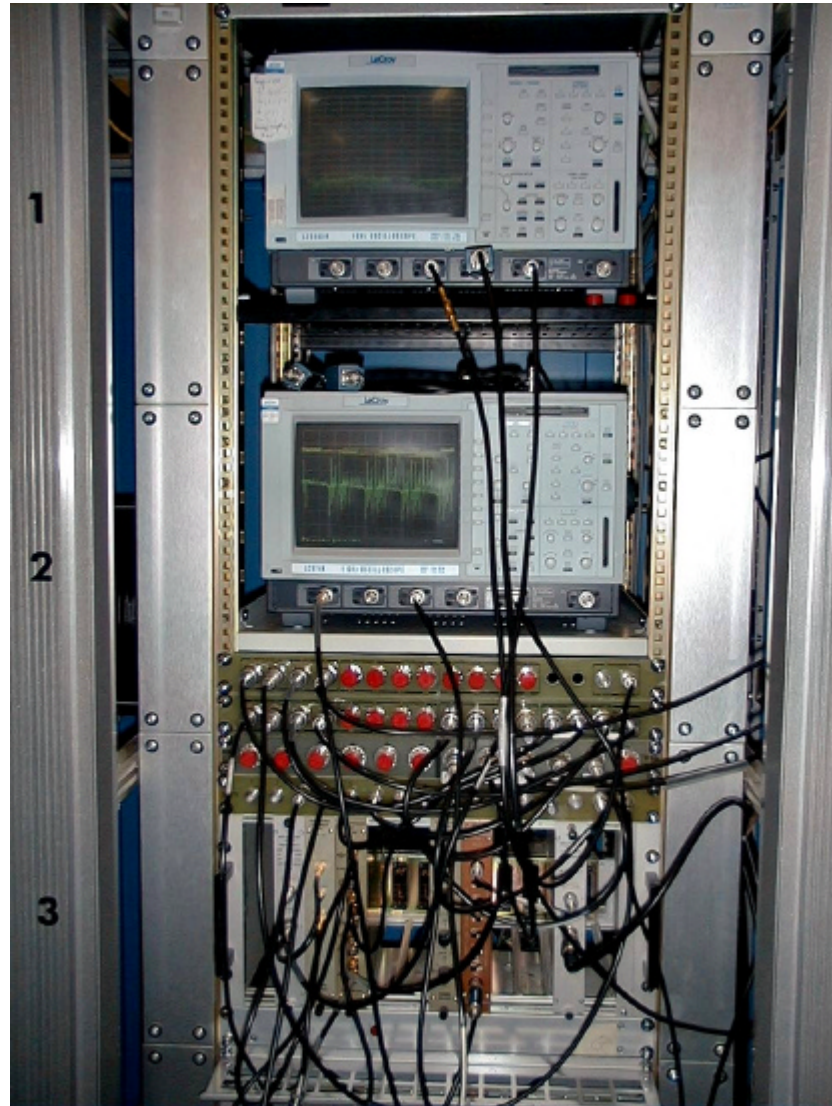
1 20 mV 50Ω  
2 .1 V 50Ω  
3 20 mV 50Ω  
4 .1 V 50Ω



Ext DC -0.400 V 50Ω

EXT

NORMAL



The system with two digitizers with 8 acquisition channel and the setup bringing the BPM signals from the DAΦNE hall.



# High-Performance GPIB Interface for PCI

## PCI-GPIB

### TNT4882C ASIC

- Complete IEEE 488.2 compatibility
- FIFO buffers to decouple GPIB transfers from PCI transfers
- GPIB monitor port for board and bus-level diagnostics
- Complete in-system functional testing with loop-back mode
- Reduced software overhead
- Maximum GPIB transfer rates
  - 1.5 Mbytes/s using IEEE 488.1 handshake
  - 7.7 Mbytes/s using HS488 handshake

### MITE PCI ASIC

- Complete PCI 2.1-compatible interface
- Bus-master DMA Controller

Contact National Instruments for OEM pricing on PCI-GPIB and other products.



### NI-488.2M Software

- Windows NT/98/95
- Solaris 2
- Digital Unix (OSF/1)

### NI-488.2 Software

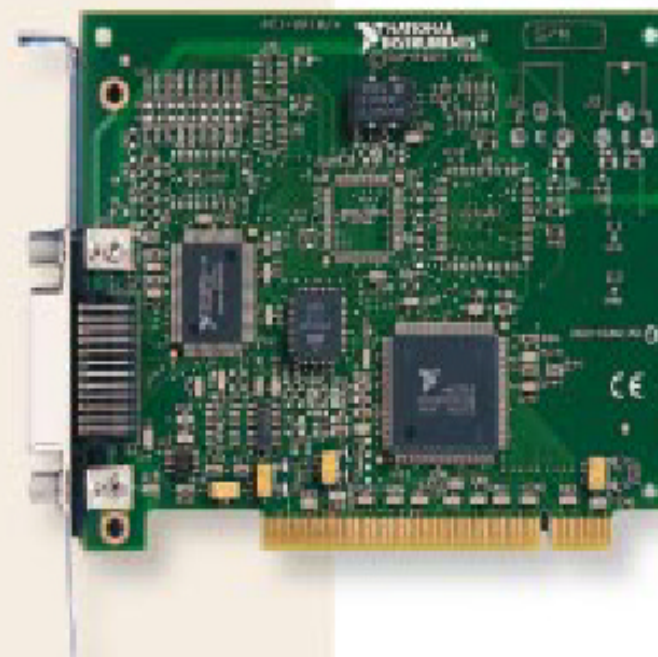
- Mac OS

### NI-488 DDK Software

- For any operating system
- Includes example OS implementations:
  - VxWorks
  - DOS
  - IRIX
  - Digital Unix

### Application Software

- LabVIEW
- LabWindows/CVI
- Measure
- ComponentWorks
- Visual Basic
- Visual C++



National Instruments

- **SUN Ultra 5 Workstation** • Desktop system

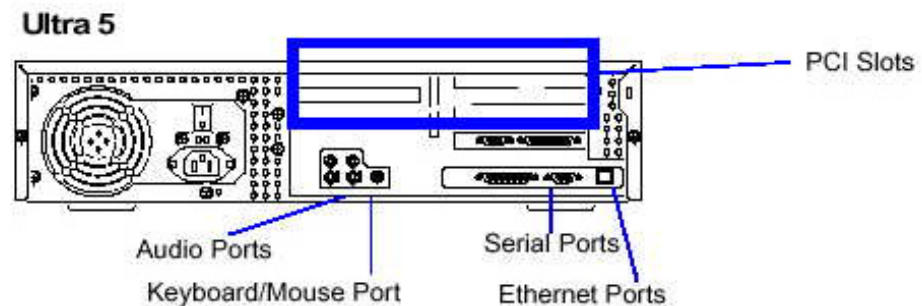
- **Processors** • 400-MHz UltraSPARC-Iii
- • 2-MB ECache



- **Memory**
- • 4 DIMM slots
- • Up to 512-MB memory

- **Internal Storage**

- • 8-GB disk
- • 1.44-MB floppy
- • 48x CD-ROM drive



- **System I/O** • Three 33-MHz 32-bit PCI slots
- • Two independent PCI I/O buses

- **Graphics** • Built-in PGX24™ 24-bit graphics

- **Performance** • 16.5 SPECint95
- • 21.3 SPECfp95

- **Operating Environment:** Solaris 7

# Acquisition, analysis and storing tools

DA\_recorder\_plus\_show.vi

File Edit Operate Tools Browse Window Help

10pt Application Font

Dynamic Tracking

Current Day Path Recording Time Directory lenght raw data  
 %/export/home/DA/data/E+/mar1902 155407 10002

Decimate YES First val 9 Best first val 9 Offset for calc.function 0

Acquire data CH 1 CH 2 CH 3 CH 4  
 ON  ON  ON  ON  
 Record CH 1 Record CH 2 Record CH 3 Record CH 4  
 YES  YES  YES  YES

Record raw data CH1:Data:CH2:Data CH3:Data:CH4:Data  
 deltax sigmax deltax sigmay  
 Record calc.1 Record calc.2 Record calc.2b Record calc.3 Record calc.4 Record calc.4b  
 YES  YES  YES  YES  YES  YES

Output range x y H pos x'Hilbert x'MatTr V pos y'Hilbert y'MatTr  
  x xph xpm y yph ypm  
 x'Hilbert error 0 y'Hilbert error 0  
 Qx Qy  
 5.114500000 5.150300000  
 ALFA\_x BETA\_x (m) ALFA\_y BETA\_y (m)  
 -5.500000000 5.300000000 -2.200000000 3.800000000

deltax (V) vs. time (turns)

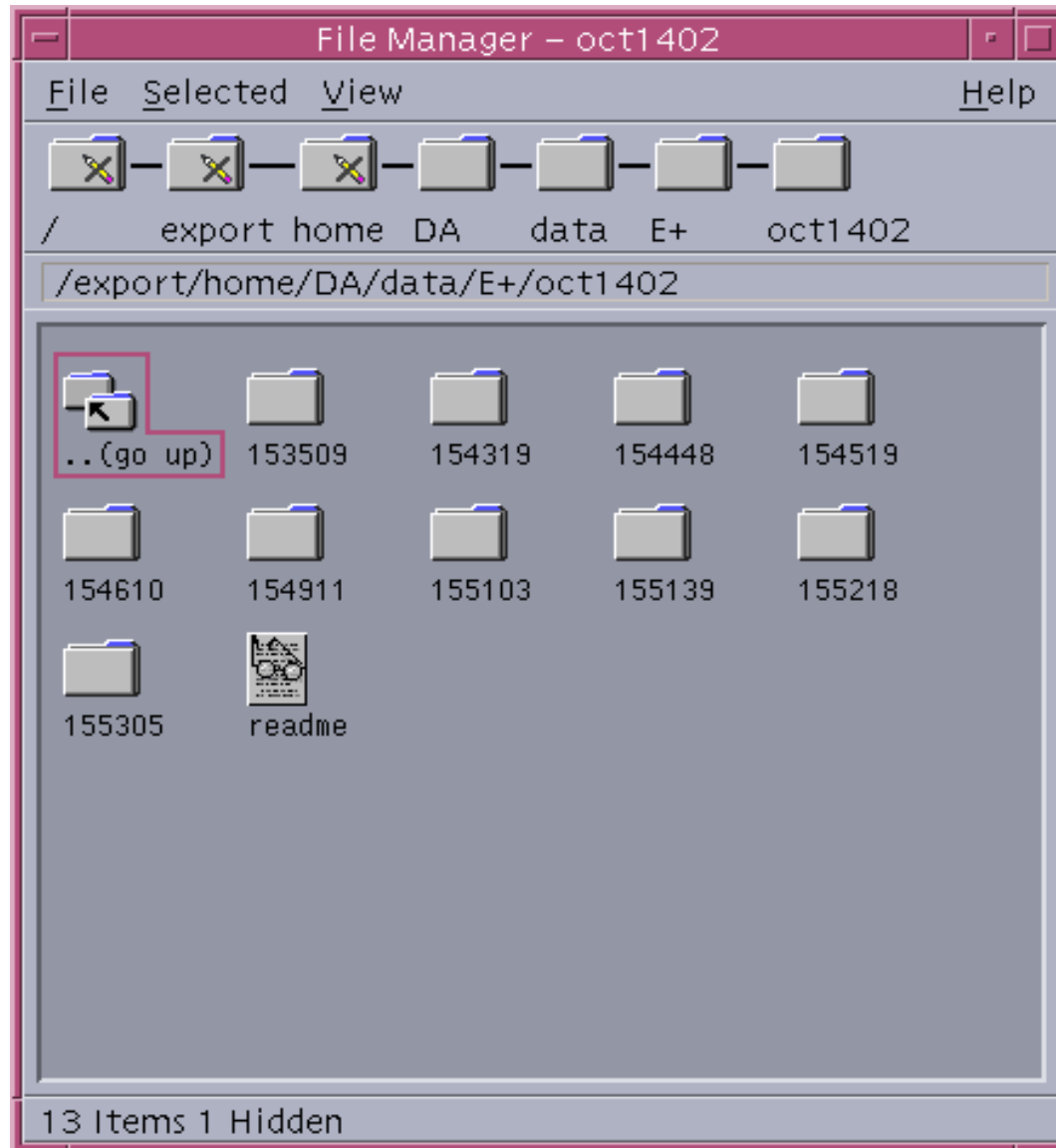
x' vs x (mm)

# Performances

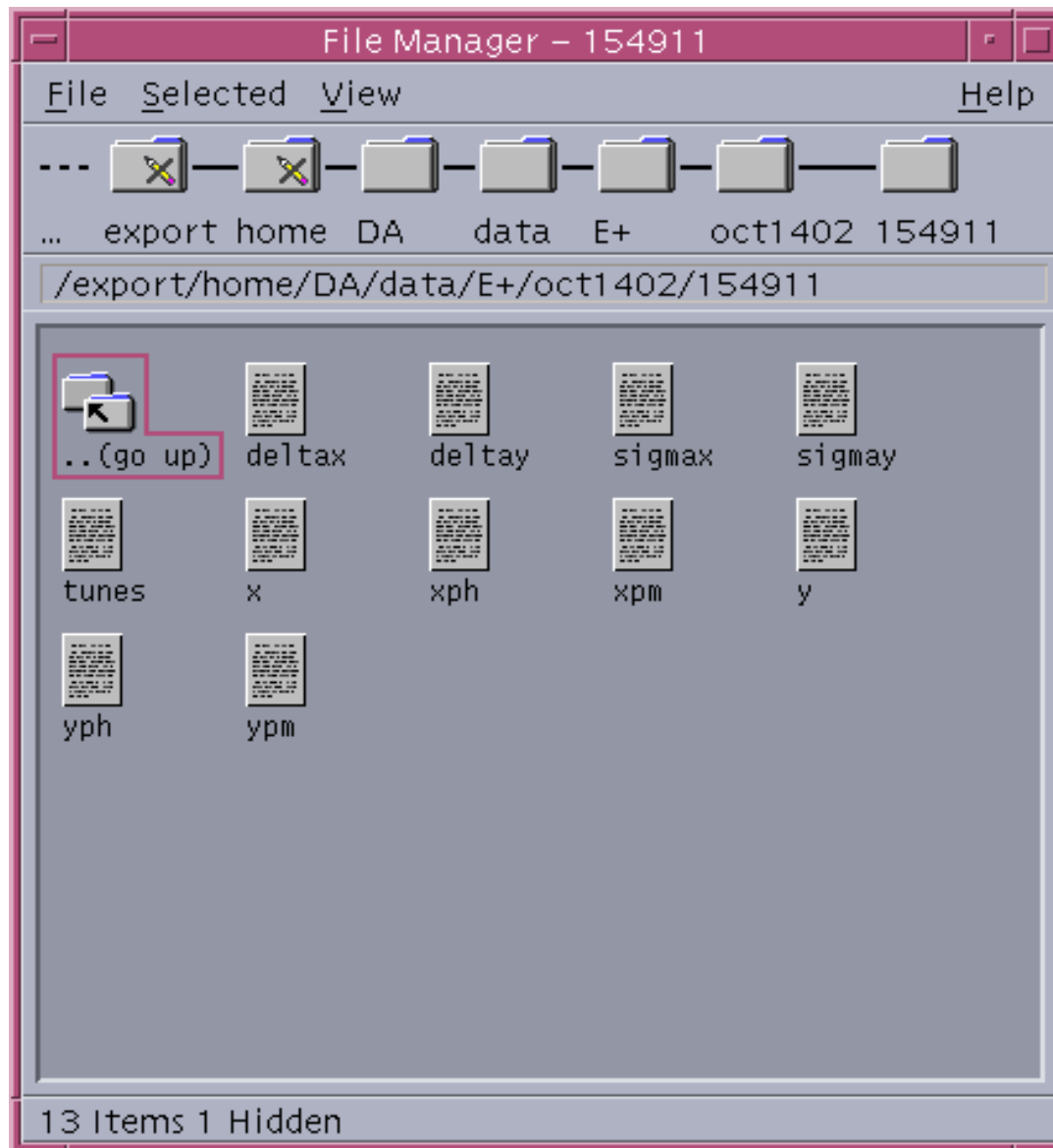
- All the programs are written using LABVIEW 6.0 and can run on different platforms.
- Acquisition, conversion and storing of **100k points x 4 channels** (.8M bytes through IEEE488) takes more than **1 minutes using a Macintosh Quadra** and only **12 sec with Sun Ultra 5**.
- Acquisition, conversion and storing of **500k points x 4 channels** (4M bytes through IEEE488) takes **½ minute on Sun Ultra 5, not possible on Macintosh Quadra**.

# Database

- A database tree is automatically generated by the acquisition program
- First level directories: E+ or E-
- Second level directories defined by the date: mmmddy (for example apr1902)
- Third level directories defined by the time: hhmmss (for example 143207)
- Data files for spreadsheet application: rough data in voltage (deltax, sigmax, deltay, sigmay) and calculated data in mm (x, xph, xpm, y, yph, ypm).



- Second level directories defined by the date
- The readme file contains every useful information about the machine conditions (current, kick value, magnets on/off)

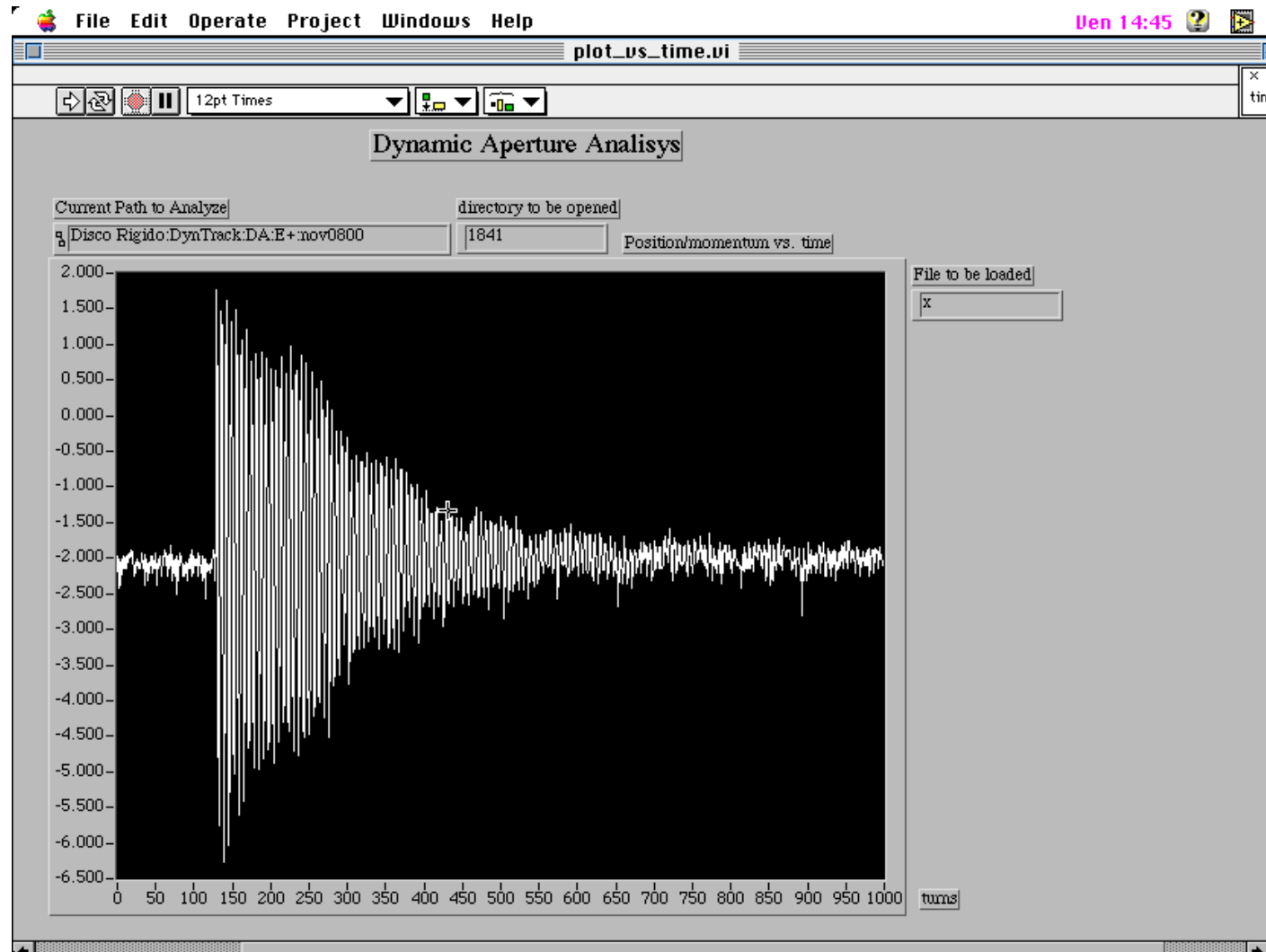


- Third level directories defined by the time
- Rough data in voltage and calculated data in mm
- Every file is composed by only column to be easily loaded in any spreadsheet

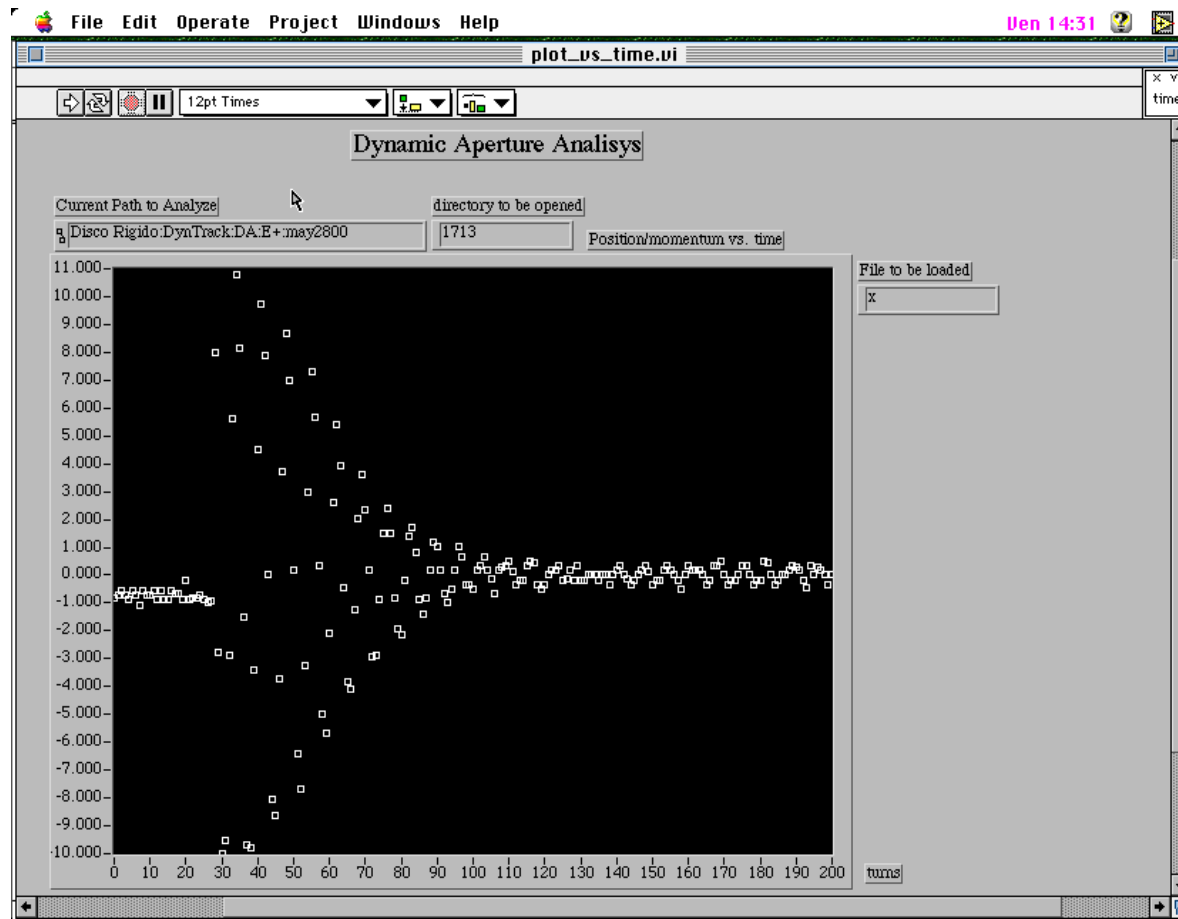


# Data retrieval and browsing tools

# Horizontal Displacement (in mm) Versus Number of Turns.



# A coherent signal decay due to non-linear filamentation (displacements versus turns)



The transport matrix method uses the Twiss parameters  $\alpha$ ,  $\beta$  at the monitor position as computed by the machine model.

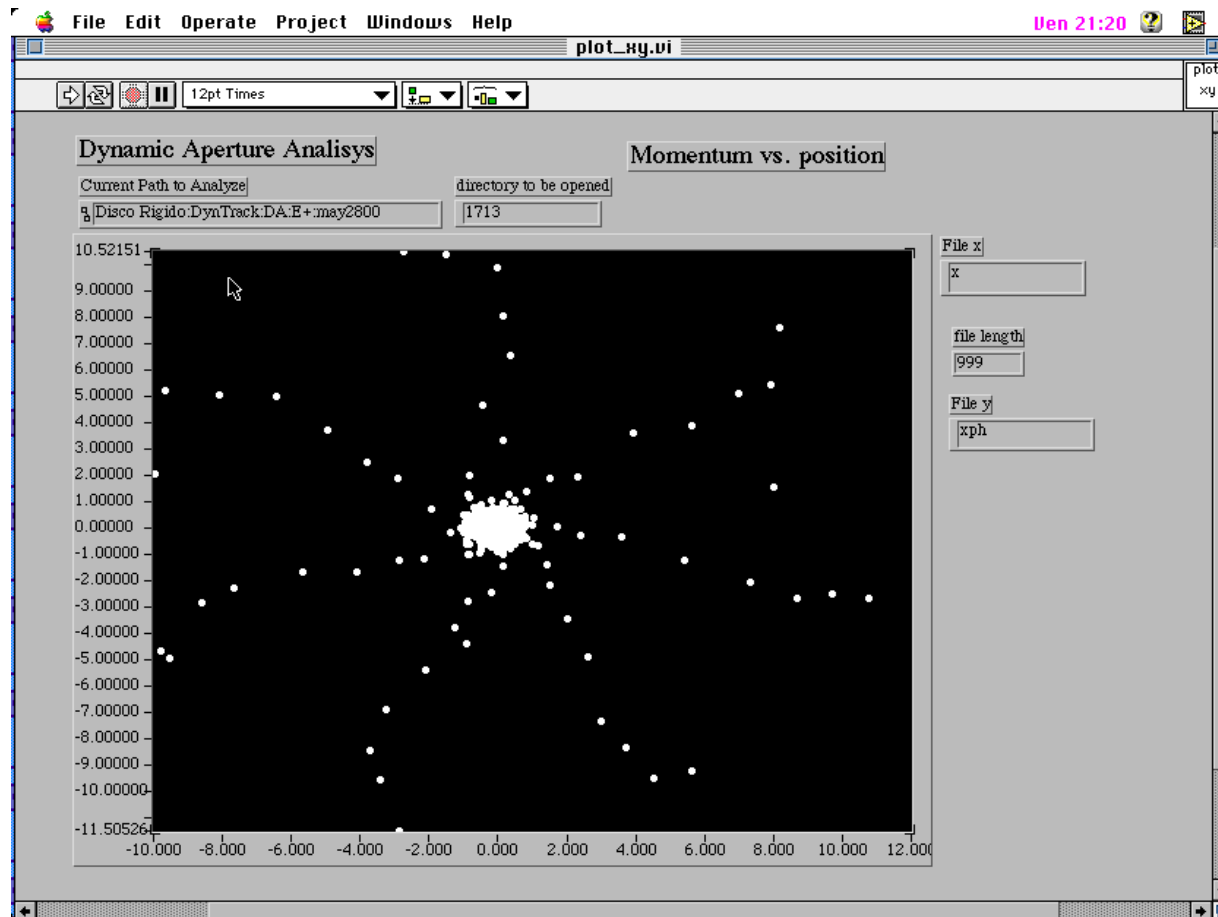
The transport matrix formula is

$$x'(i) = \frac{x(i+1) - (\cos(2PQ) + a \sin(2PQ)) x(i)}{b \sin(2PQ)}$$

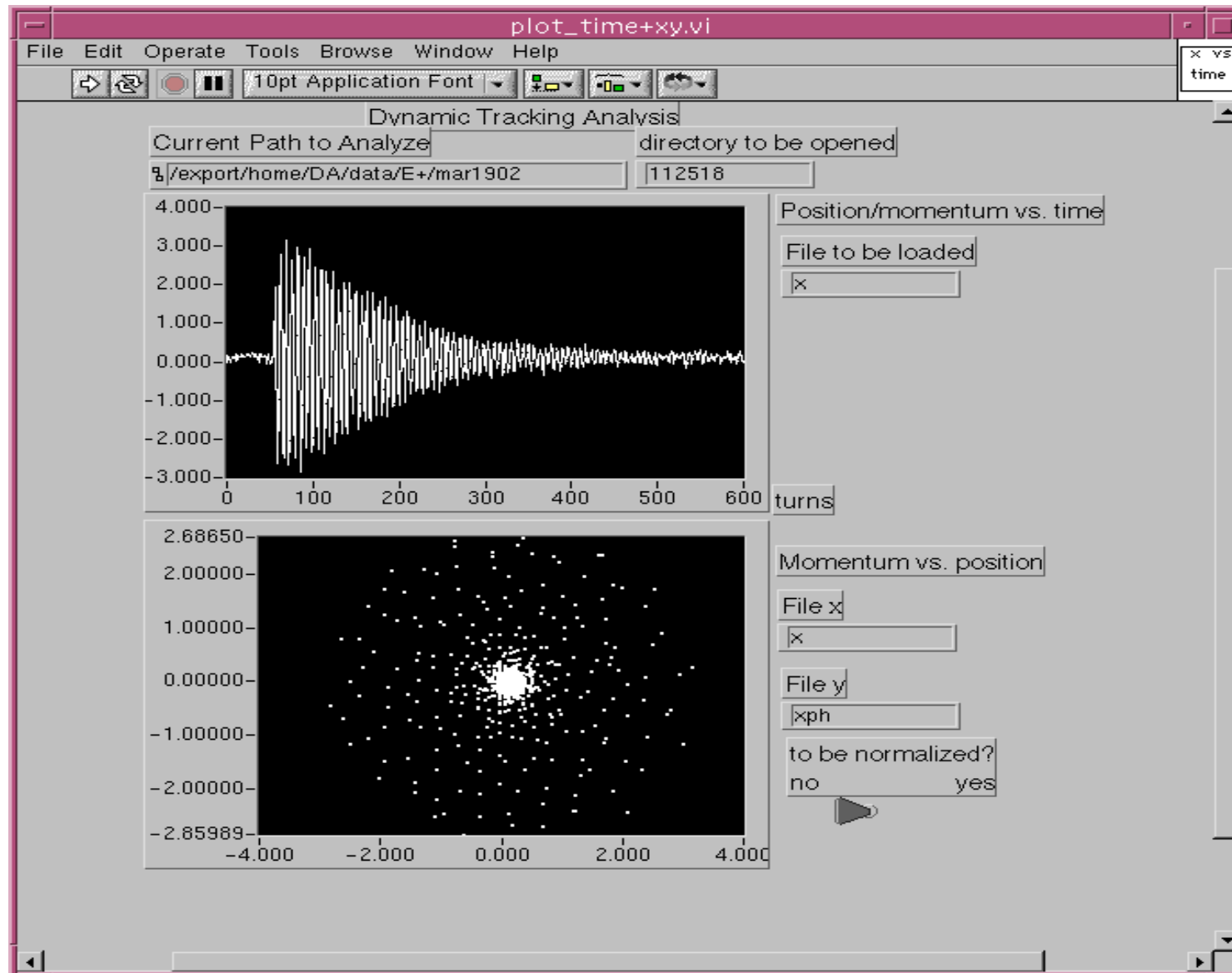
where  $\alpha$ ,  $\beta$  are the horizontal or vertical Twiss parameters, and  $Q$  is the betatron tune.

In alternative the Hilbert transform method can be used : a preliminary comparison has shown a good agreement between the the two methods.

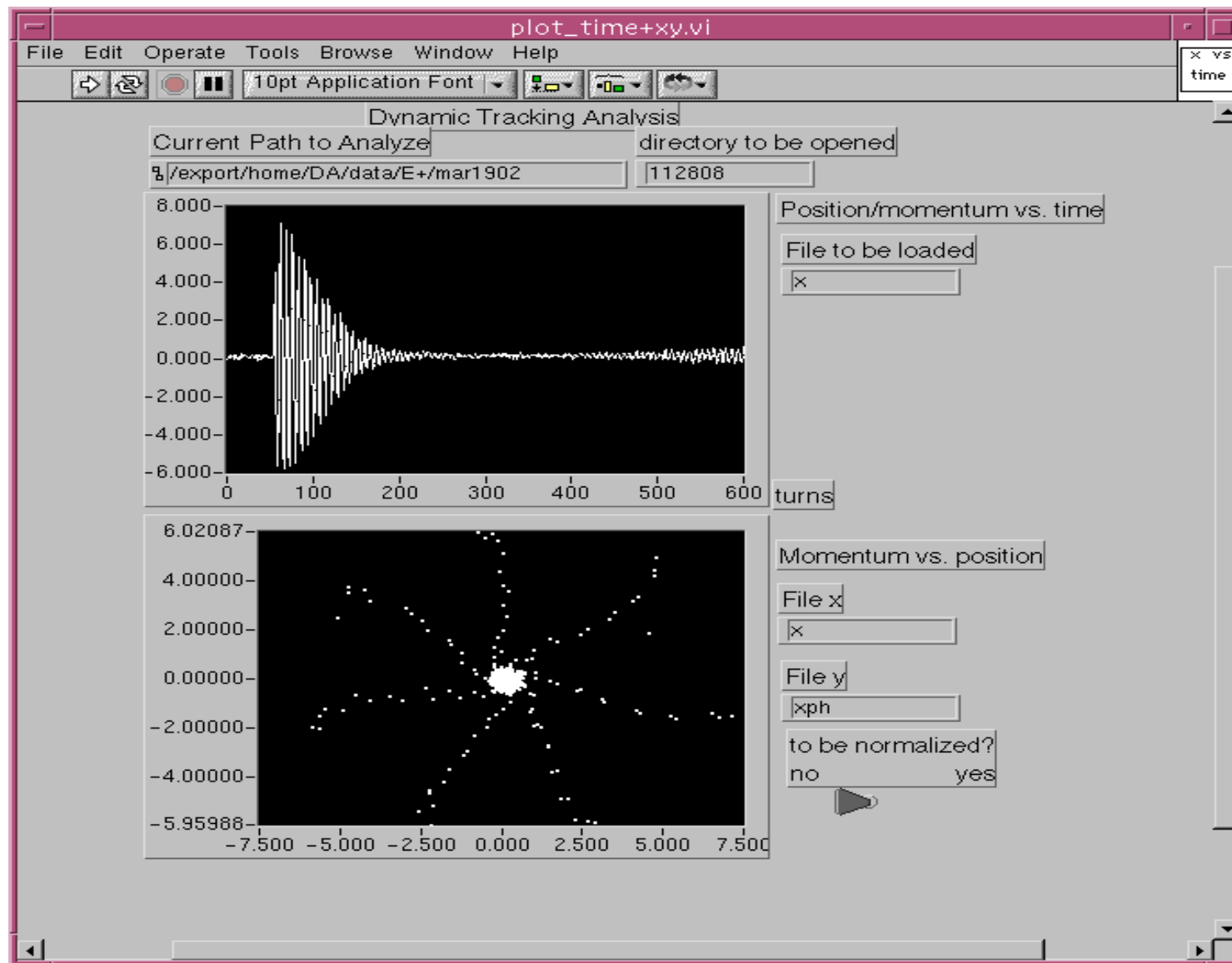
# Horizontal phase space plot drawn using the Hilbert transform



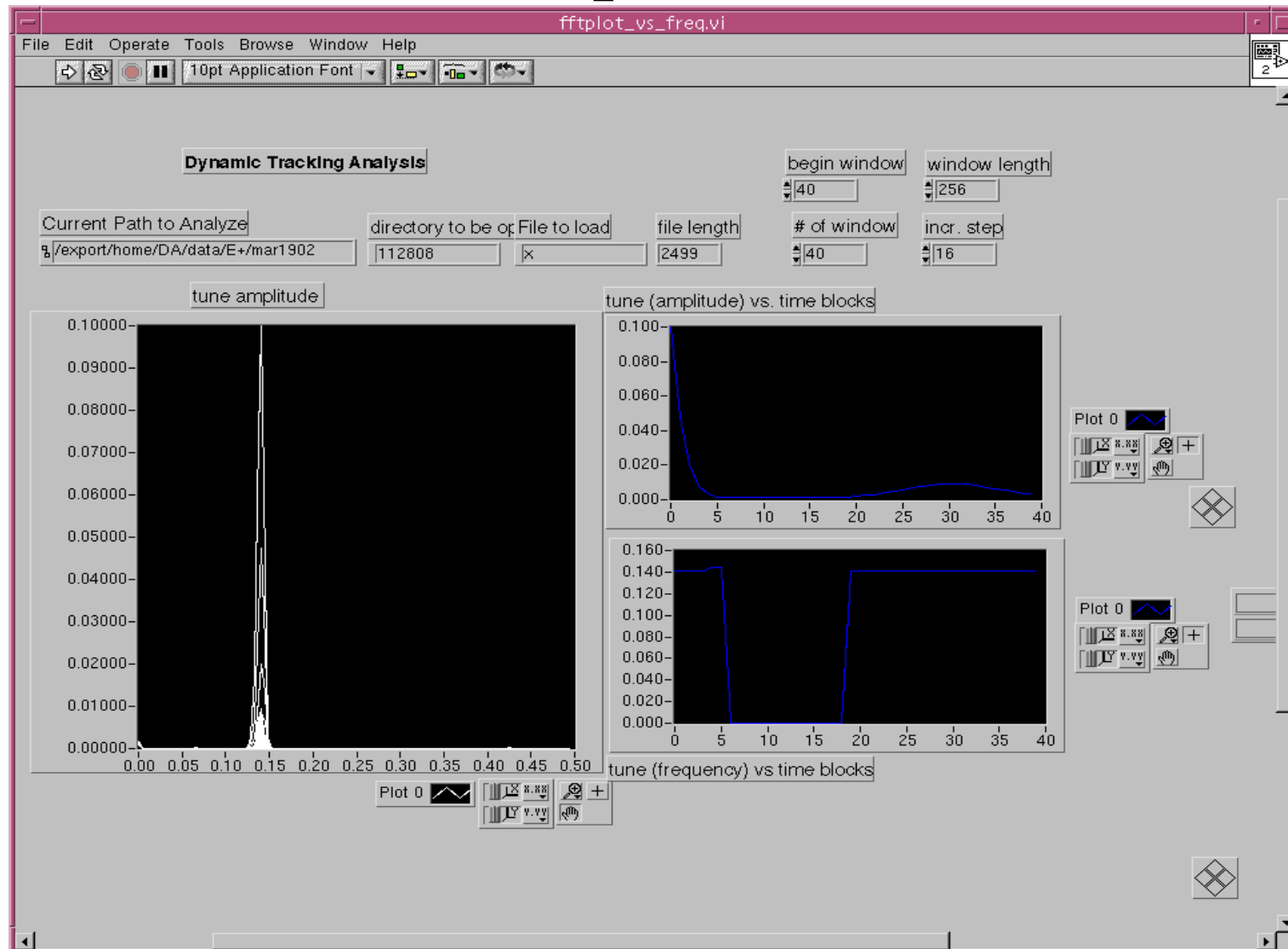
# Plot $x$ in time and $x'$ versus $x$ (3kV kick)



# Plot $x$ in time and $x'$ versus $x$ (6kV kick)

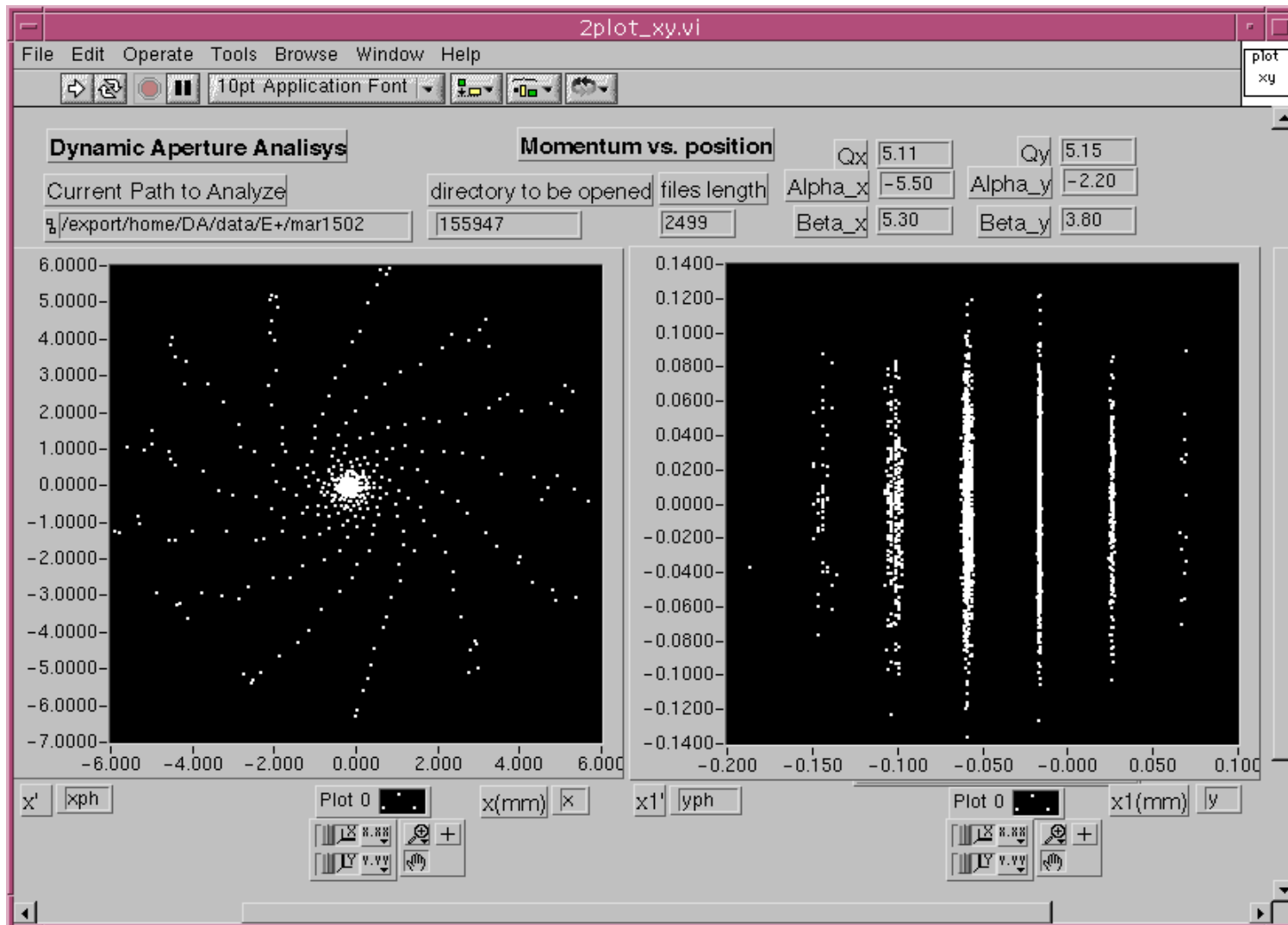


# Betatron tune analysis versus time & amplitude

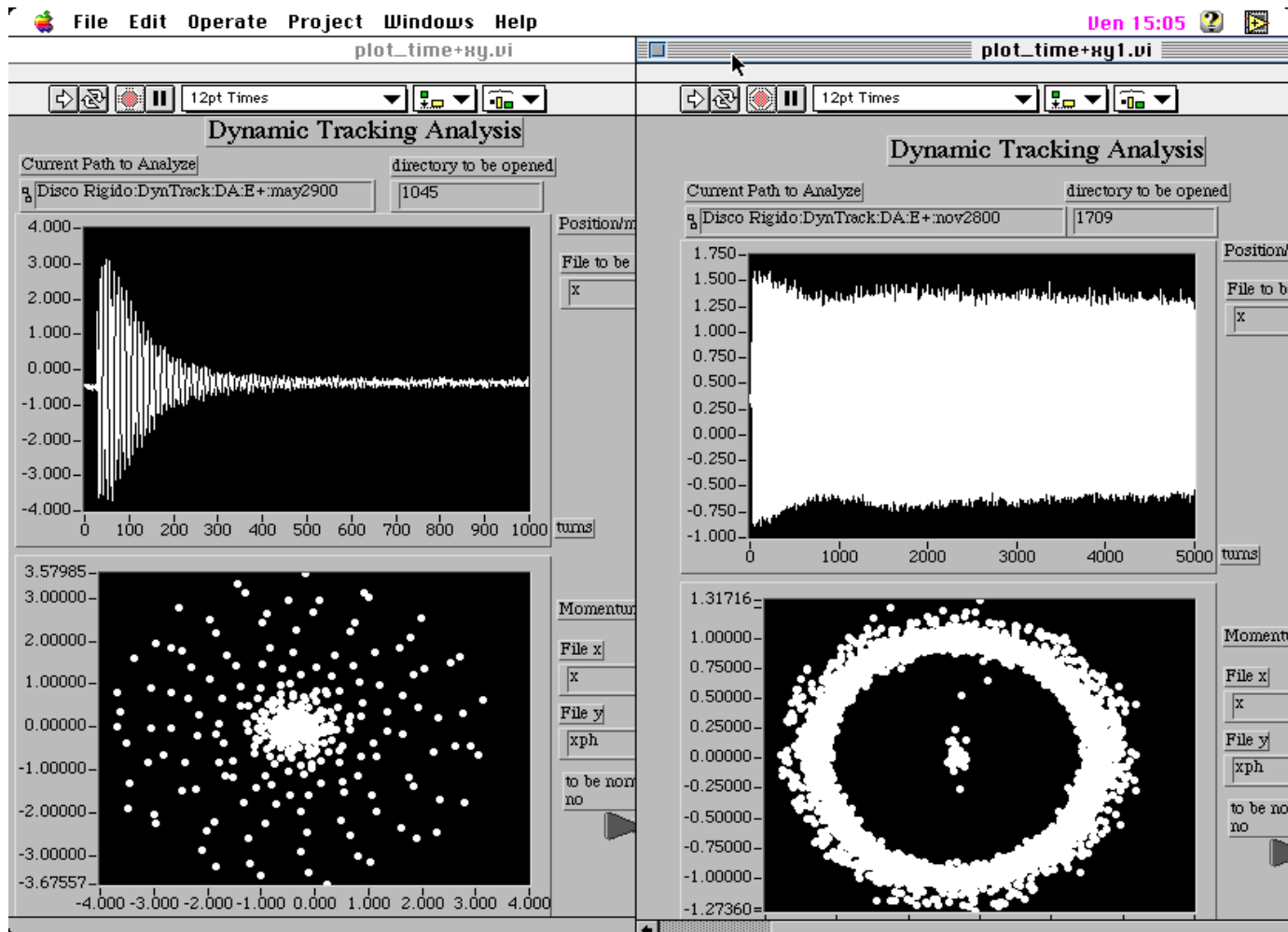




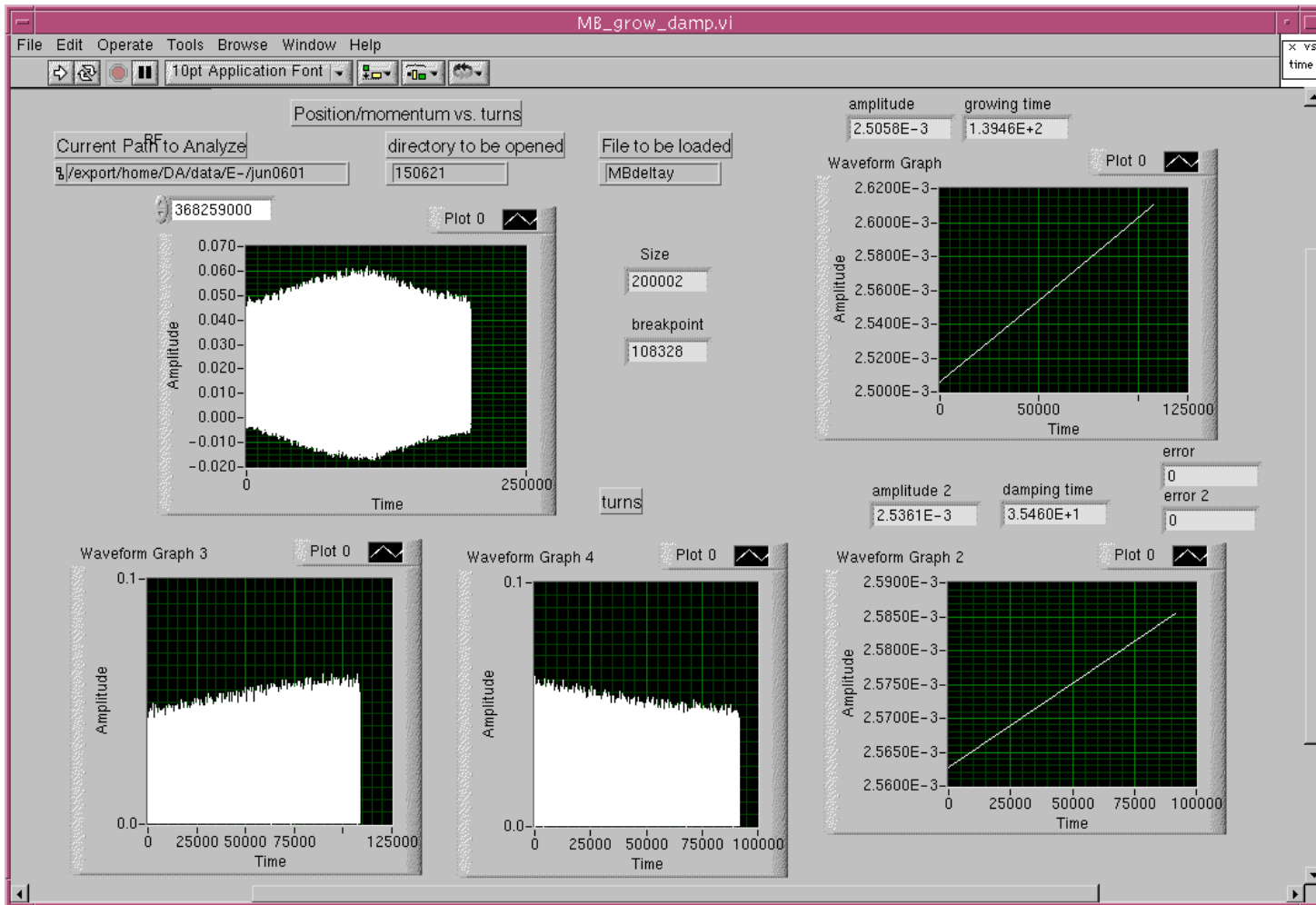
# Angle versus position H and V



# A comparison between two optics with wigglers on and off



# Multibunch grow-damp analysis



# Conclusions

- The dynamic tracking acquisition system has shown to be a very useful tool to investigate the non-linear behaviour of the Daφne rings and to improve their performances.
- The first version of system has been upgraded to download data more quickly from the oscilloscope and to share the database with the control system.
- A second oscilloscope has been added with the goal to have eight channels and to acquire signals from two BPM's.
- It is possible to begin to develop multibunch software tools to extend the use of the system at the transverse modal analysis.

## **Acknowledgements**

The authors wish to thank Oscar Coiro and Donato Pellegrini for the realization of the set-up, very critical on the equalization of the cables.

Thanks also to Mario Serio for many ideas and suggestions during the system implementation and to Mikhail Zobov for the interesting and useful discussions during the set-up of the system.