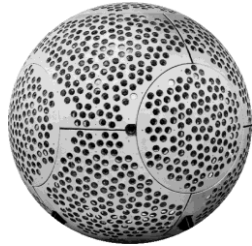




# Retroreflector systems used in laser ranging of geodetic and navigation satellites



Ajisai / Japan



ETALON / Russia

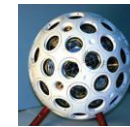
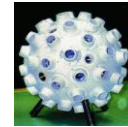


LAGEOS / USA

GFZ-1 / Russia

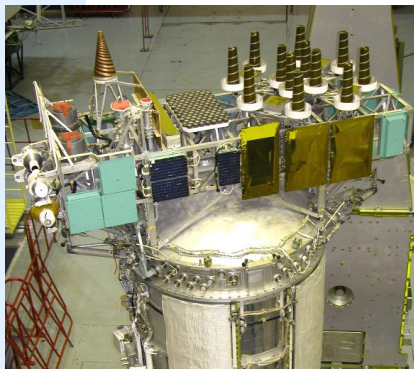


LARETS / Russia

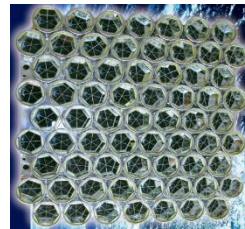


METEOR / Russia

WESTPAC / Russia



GLONASS / Russia



Compas / China



GIOVE / Russia



GPS №35,36 / Russia



# Main Laser Retroreflector Systems of “RPC “PSI”

Type of spacecraft	Altitude, km	Launching	Number of spacecrafts	Number of CCR on a spacecraft	Type of reflective coating
<b>Etalon - 1, -2 (Russia)</b>	<b>19 100</b>	<b>1989</b>	<b>2</b>	<b>2142</b>	<b>Al</b>
<b>GPS - 35, - 36 (USA)</b>	<b>20 150</b>	<b>1993, 1994</b>	<b>2</b>	<b>32</b>	<b>Al</b>
<b>GLONASS (Russia)</b>	<b>19 100</b>	<b>2000 - 2006</b>	<b>8</b>	<b>132</b>	<b>Al</b>
<b>REFLECTOR (Russia - USA)</b>	<b>1 020</b>	<b>2002</b>	<b>1</b>	<b>32</b>	<b>Al</b>
<b>Meteor-3M-1 (Russia)</b>	<b>1 020</b>	<b>2002</b>	<b>1</b>	<b>sphere</b>	<b>Al</b>
<b>LARETS (Russia)</b>	<b>690</b>	<b>2003</b>	<b>1</b>	<b>60</b>	<b>Al</b>
<b>Mozhaets (Russia)</b>	<b>690</b>	<b>2003</b>	<b>1</b>	<b>6</b>	<b>Al</b>
<b>GLONASS-M (Russia)</b>	<b>19100</b>	<b>from 2003 to present</b>	<b>17</b>	<b>112</b>	<b>Al</b>
<b>GLONASS-M № 729 (Russia)</b>	<b>19100</b>	<b>2008</b>	<b>1</b>	<b>112</b>	<b>TiR</b>
<b>GIOVE-A (ESA) (Galileo)</b>	<b>23 916</b>	<b>2006</b>	<b>1</b>	<b>76</b>	<b>Al</b>
<b>GIOVE-B (ESA) (Galileo)</b>	<b>23 916</b>	<b>2008</b>	<b>1</b>	<b>67</b>	<b>Al</b>
<b>GOCE (ESA)</b>	<b>295</b>	<b>2009</b>	<b>1</b>	<b>7</b>	<b>Al</b>
<b>BLITS 2009 (Russia)</b>	<b>832</b>	<b>2009</b>	<b>1</b>	<b>autonomous sphere</b>	<b>Al</b>
<b>GLONASS-K</b>	<b>19100</b>	<b>2010</b>	<b>1</b>	<b>123</b>	<b>TiR</b>
<b>SPECTOR-R(Russia)</b>	<b>до 330 000</b>	<b>2010</b>	<b>1</b>	<b>100</b>	<b>Ag</b>



# The main trends of laser retroreflector systems (LRS) optimization:

## Goals:

- decrease of the correction to the results of measurement;
- increase of cross-section.

## 1. New interference coatings (generally – gradient) with a view to:

- *optimize FFDP of reflected radiation to compensate speed aberrations;*
- *reduce solar heating influence;*
- *decrease a loss of light in CCR;*

## 2. Remote control of FFDP

- *Rotation of CCR array;*
- *Variation of the polarization state of laser radiation.*

## 3. Size of CCR and value of CCR dihedral angles.

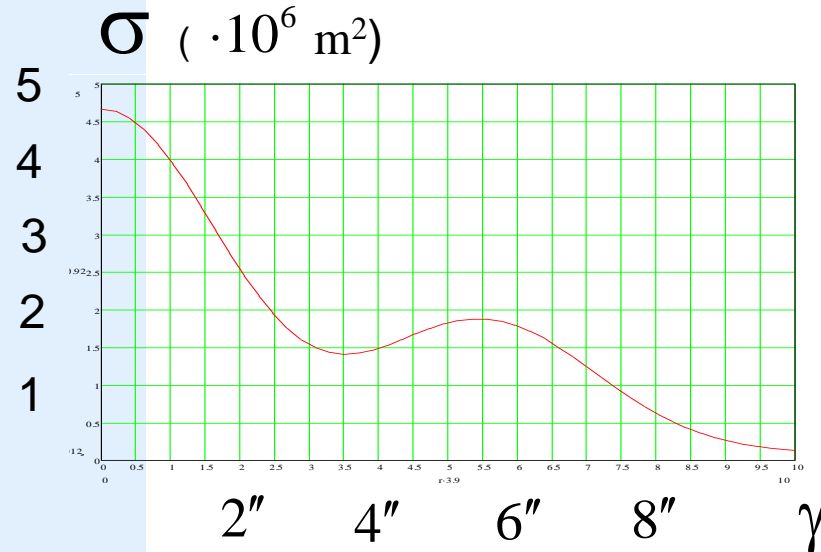
## 4. LRS configuration for an accurate correspondence to the center of mass of the satellite.

## 5. Glass spherical satellites of BLITS type – absolute correspondence of measurements to the center of mass of the spacecraft.

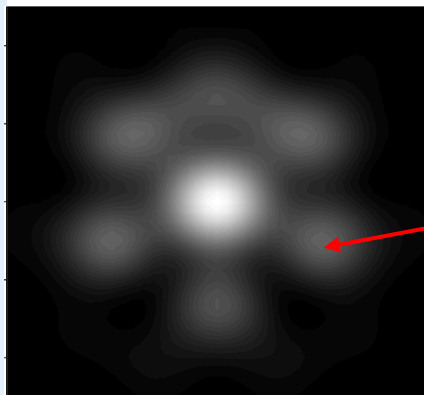
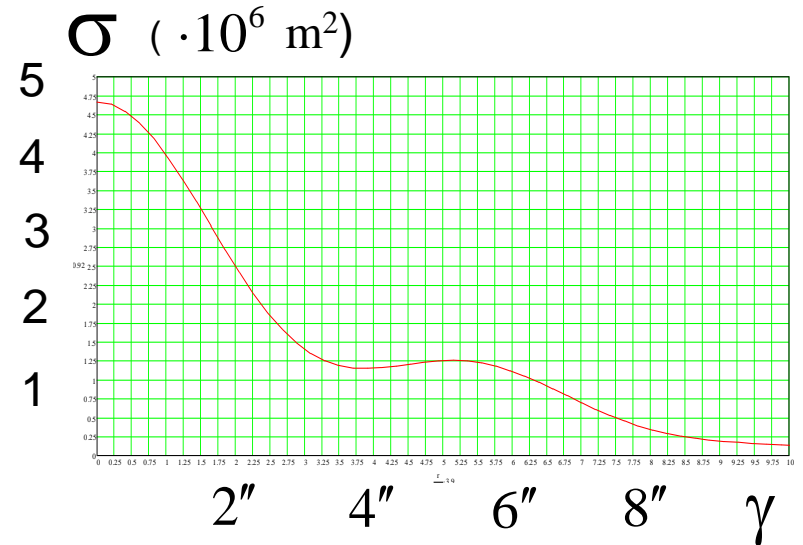


# 1 : FFDP and cross-section of CCR (TIR). Diameter – 28 mm

CS of one CCR

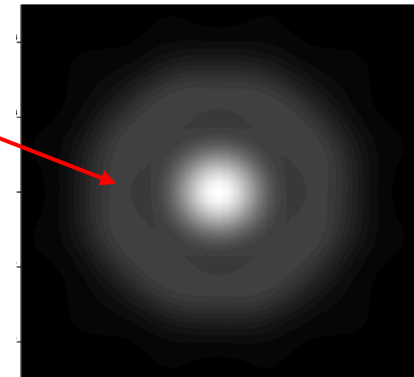


Average CS for the four turned CRR



CS =  $1,2 \cdot 10^6 \text{ m}^2$

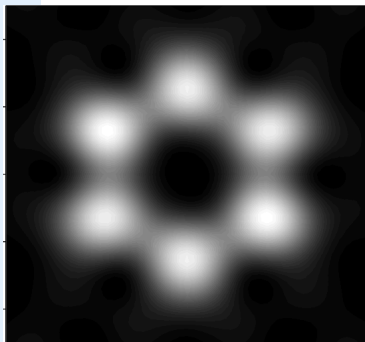
CS =  $1,9 \cdot 10^6 \text{ m}^2$



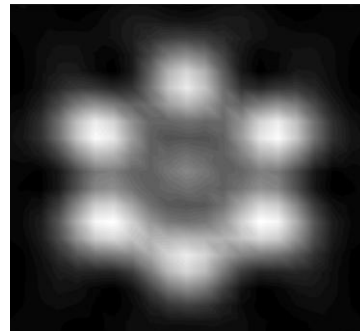


# 1 : New interference coatings

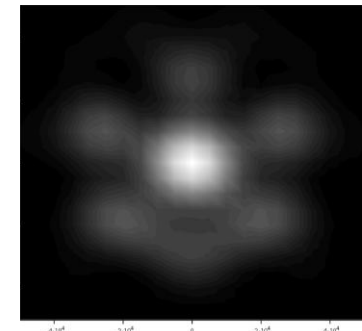
CCR's far field diffraction patterns as a function of the phase shift on reflection



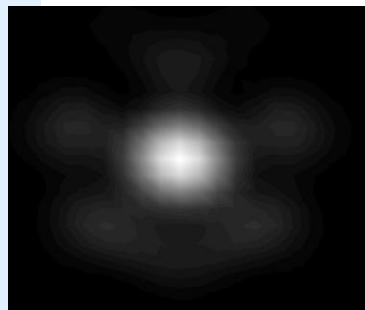
$\delta = 0$



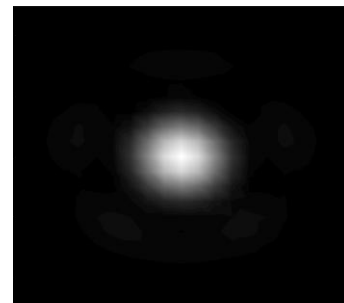
$\delta = 20$



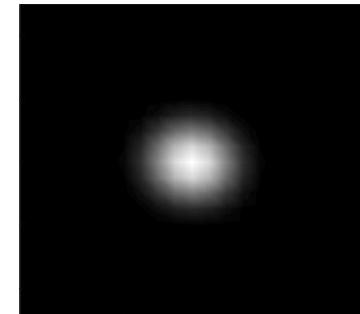
$\delta = 45$



$\delta = 60$



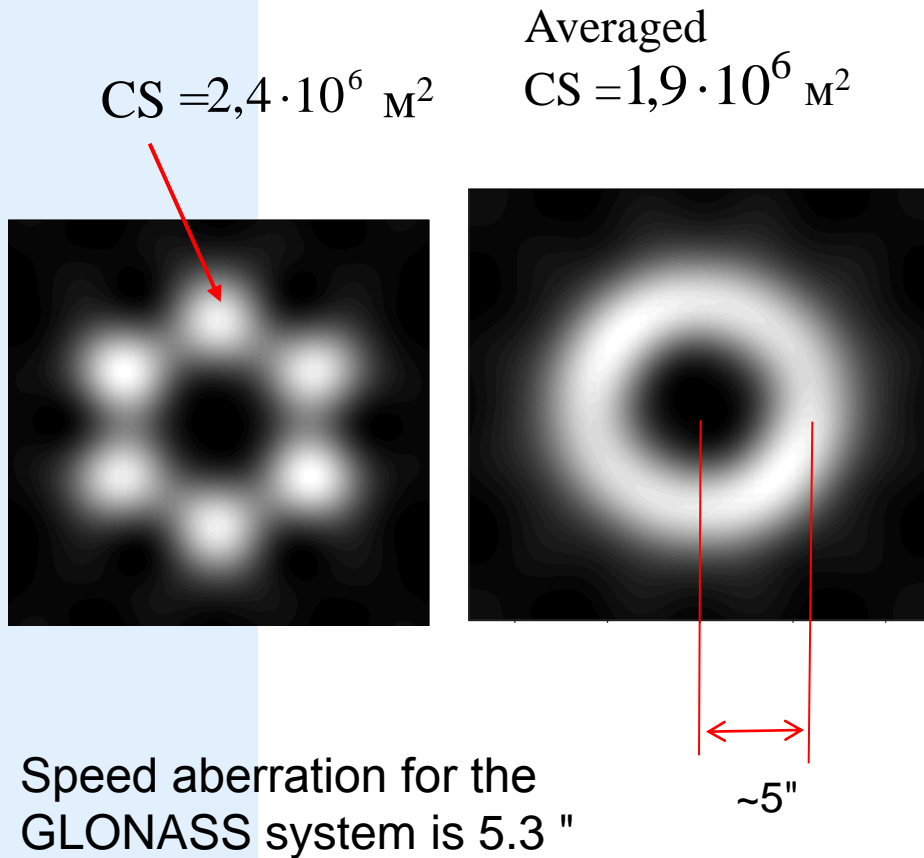
$\delta = 90$



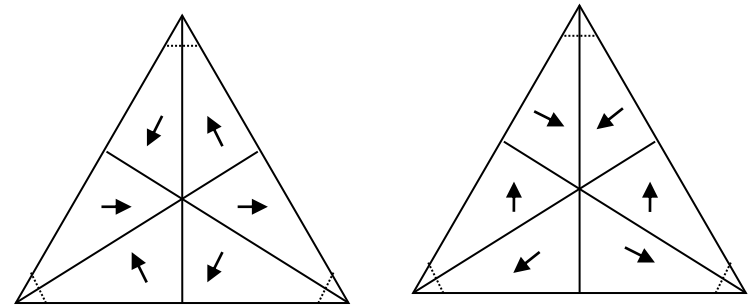
$\delta = 120$



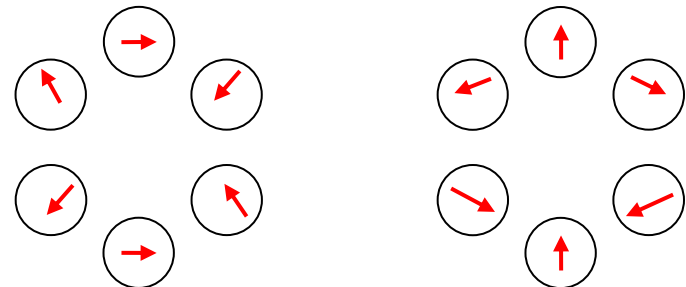
# 1 : FFDP of CCR with dielectric interference coatings of faces (the phase shift = 0)



**Polarization structure**  
in the near field:

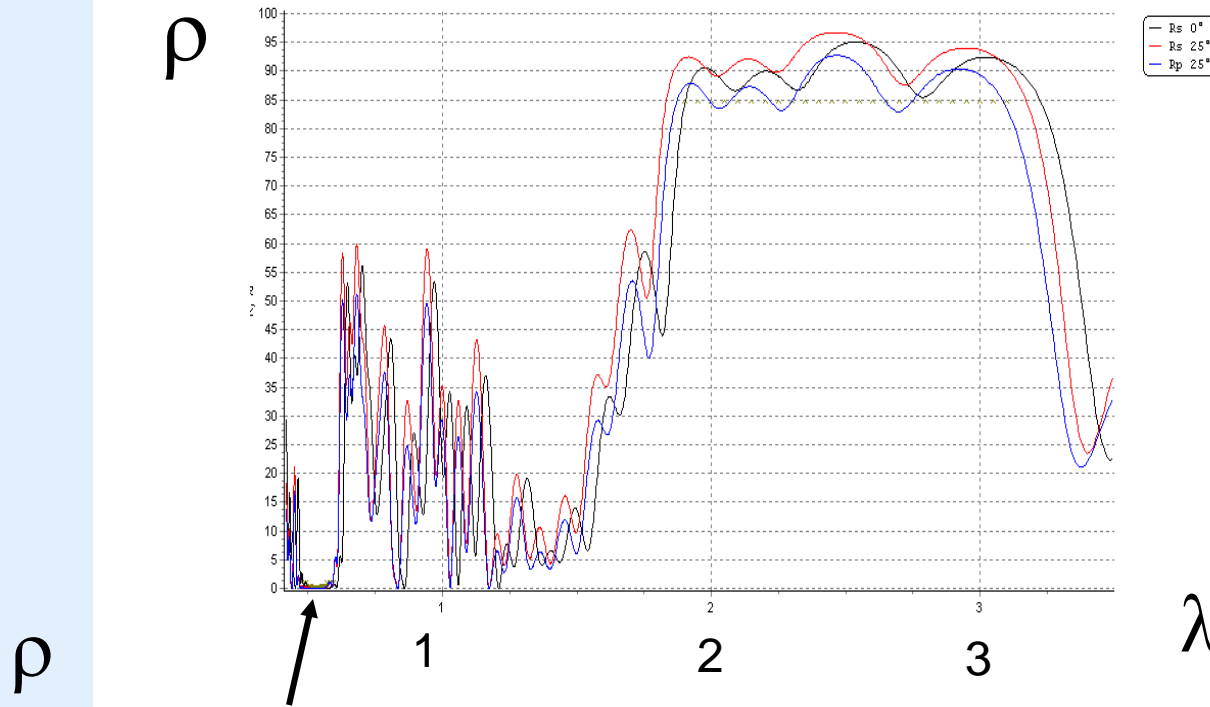


and far-field:

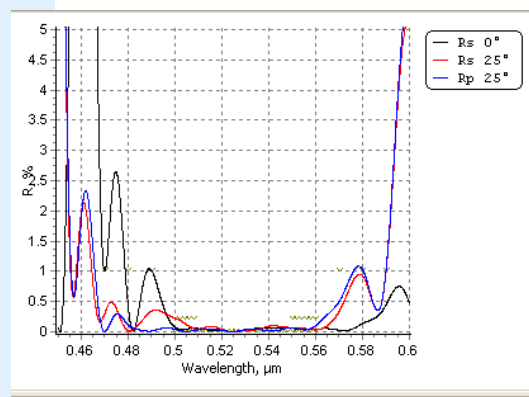




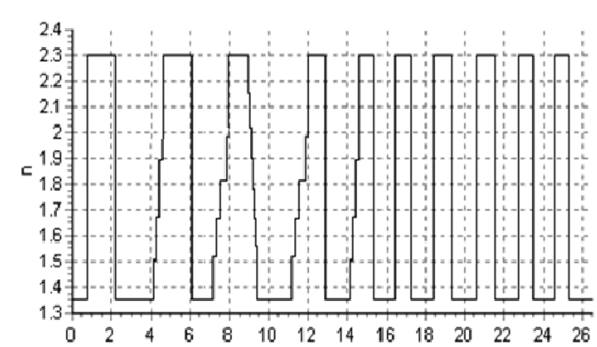
# 1 : Reduce solar heating influence



$\rho$

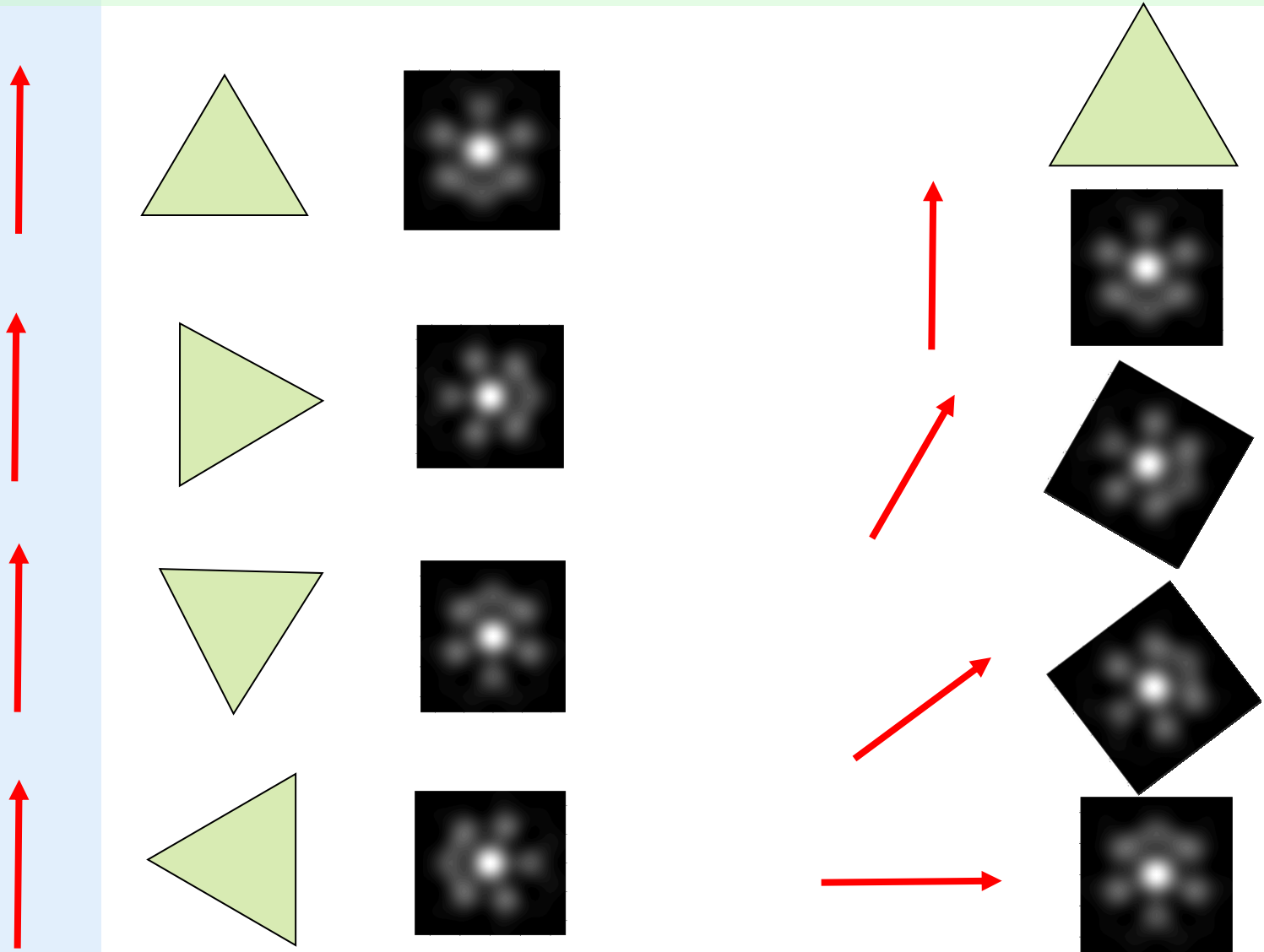


$\lambda$





# 2 : Remote control of FFDP



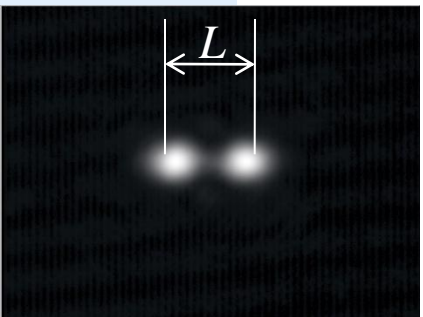
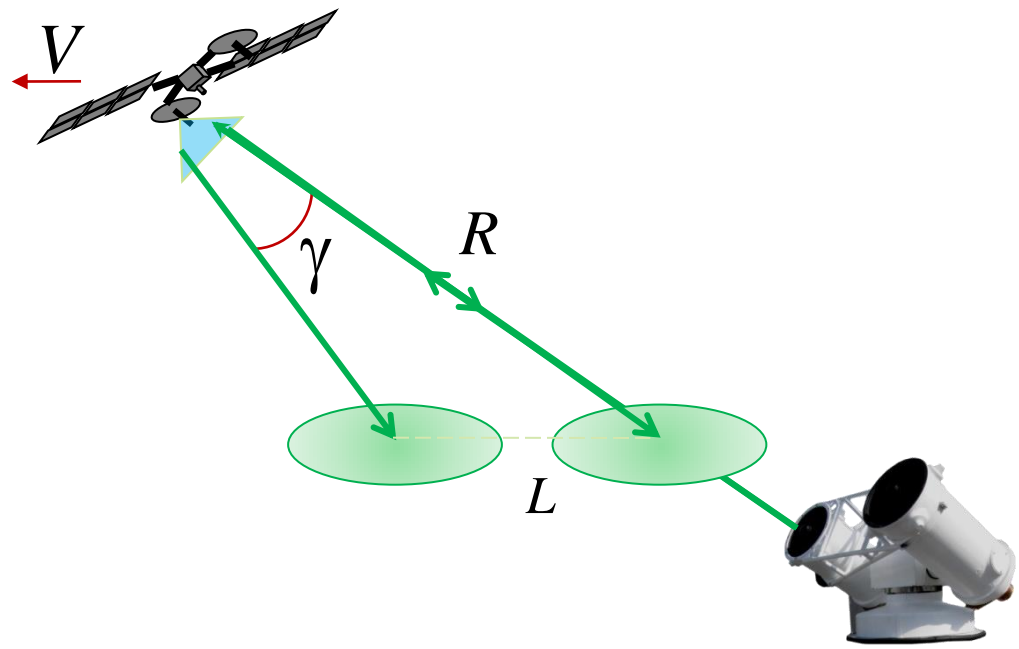




# 3 : CCR with the controlled DAO (dihedral angle offsets)

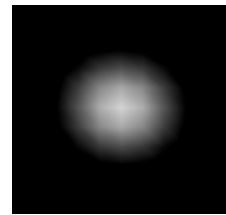
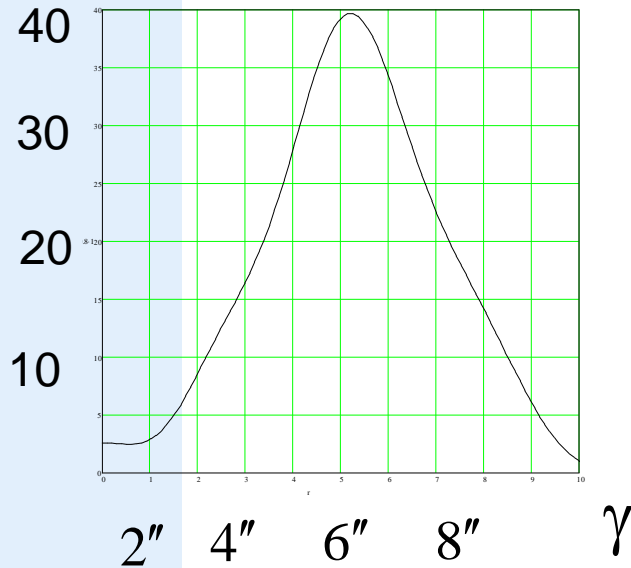
## Optimization of FFDP:

- for low-orbit three-axis attitude spacecrafts;
- for HEO spacecrafts with a ring-shape LR-array;
- for geostationary satellites.

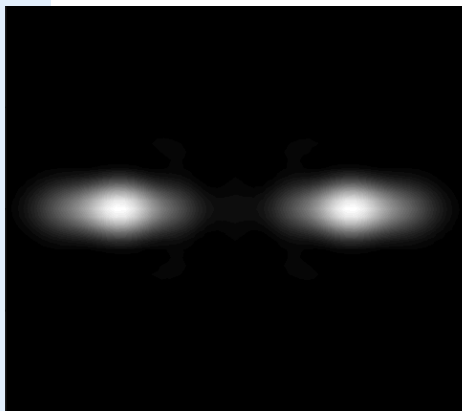
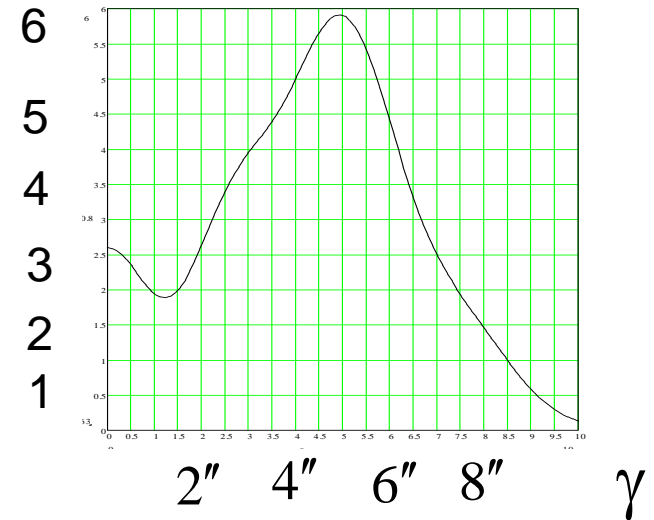


### 3 : CCR with DAO + coatings. Diameter 50 mm. Dihedral angle 2,4''

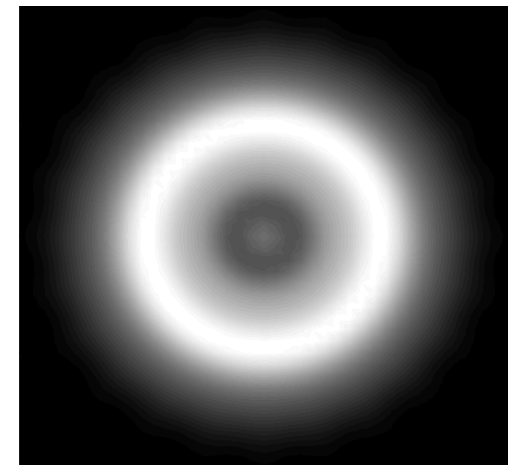
CS (  $\cdot 10^6$  M<sup>2</sup> )



Averaged CS (  $\cdot 10^6$  M<sup>2</sup> )

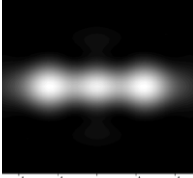
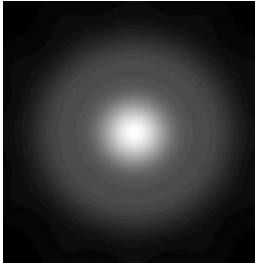
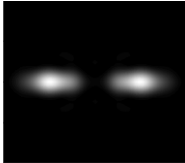
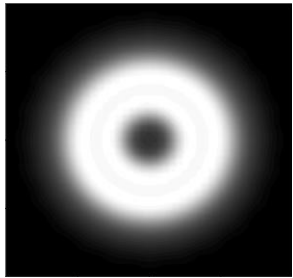
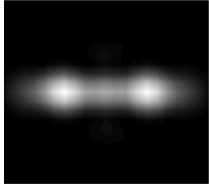
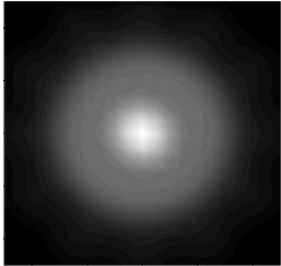
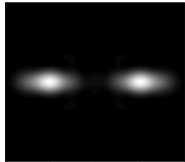
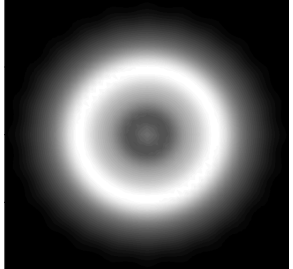
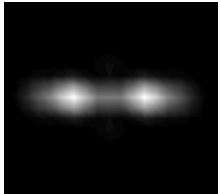
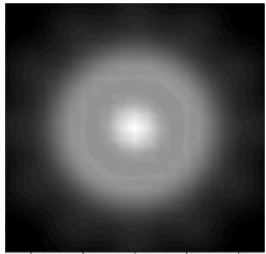
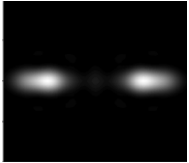
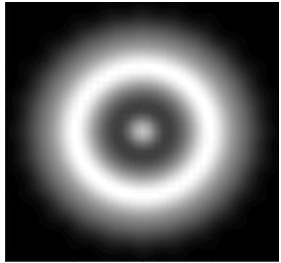


Range of 24 CCR



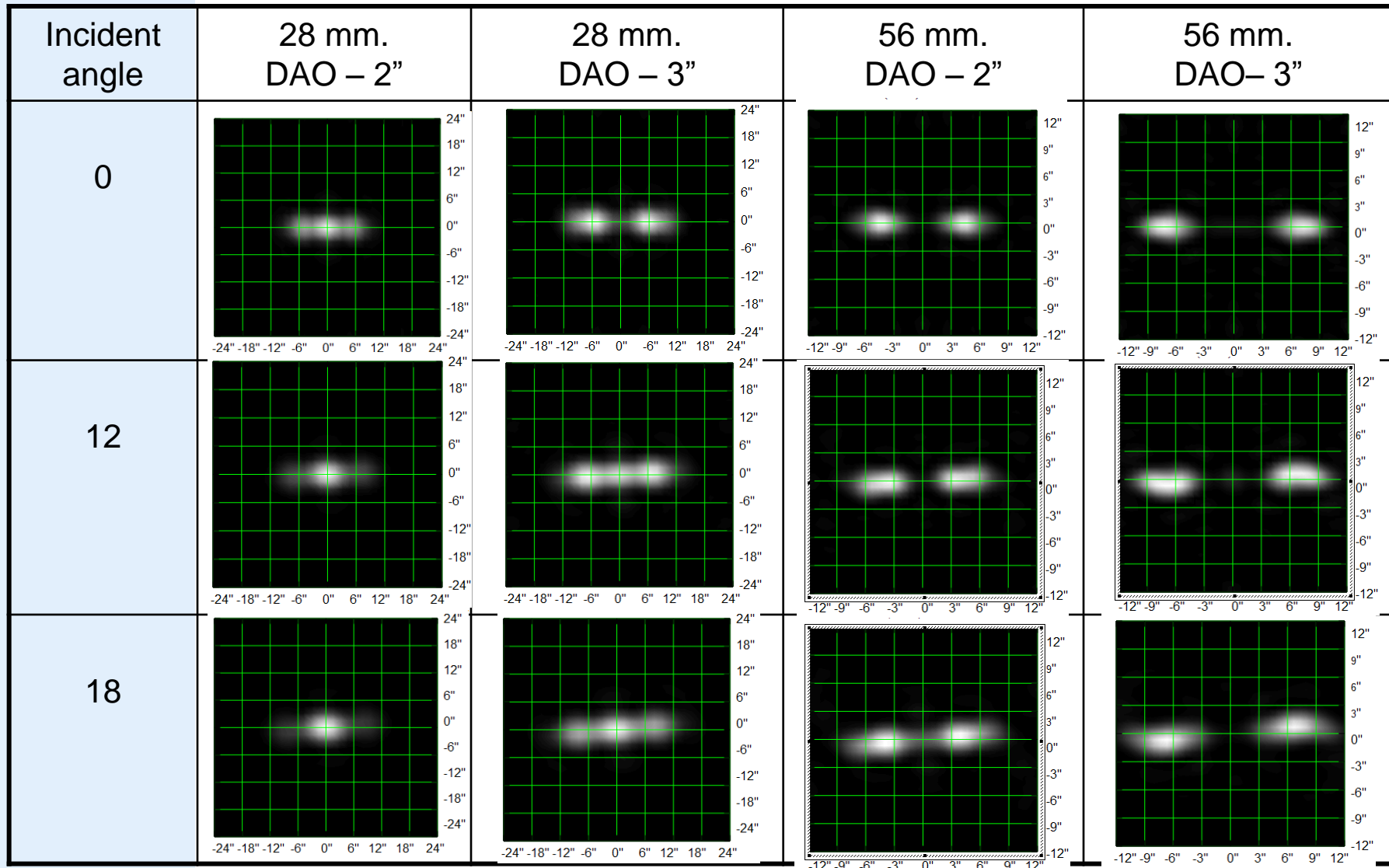


### 3 : CCR with different DAO. Diameters: 28 mm and 50 mm

DAO	Equivalent diameter - 28 mm		Equivalent diameter - 50 mm	
	One CCR	Range of CCR	One CCR	Range of CCR
2,2"				
2,4"				
2,6"				

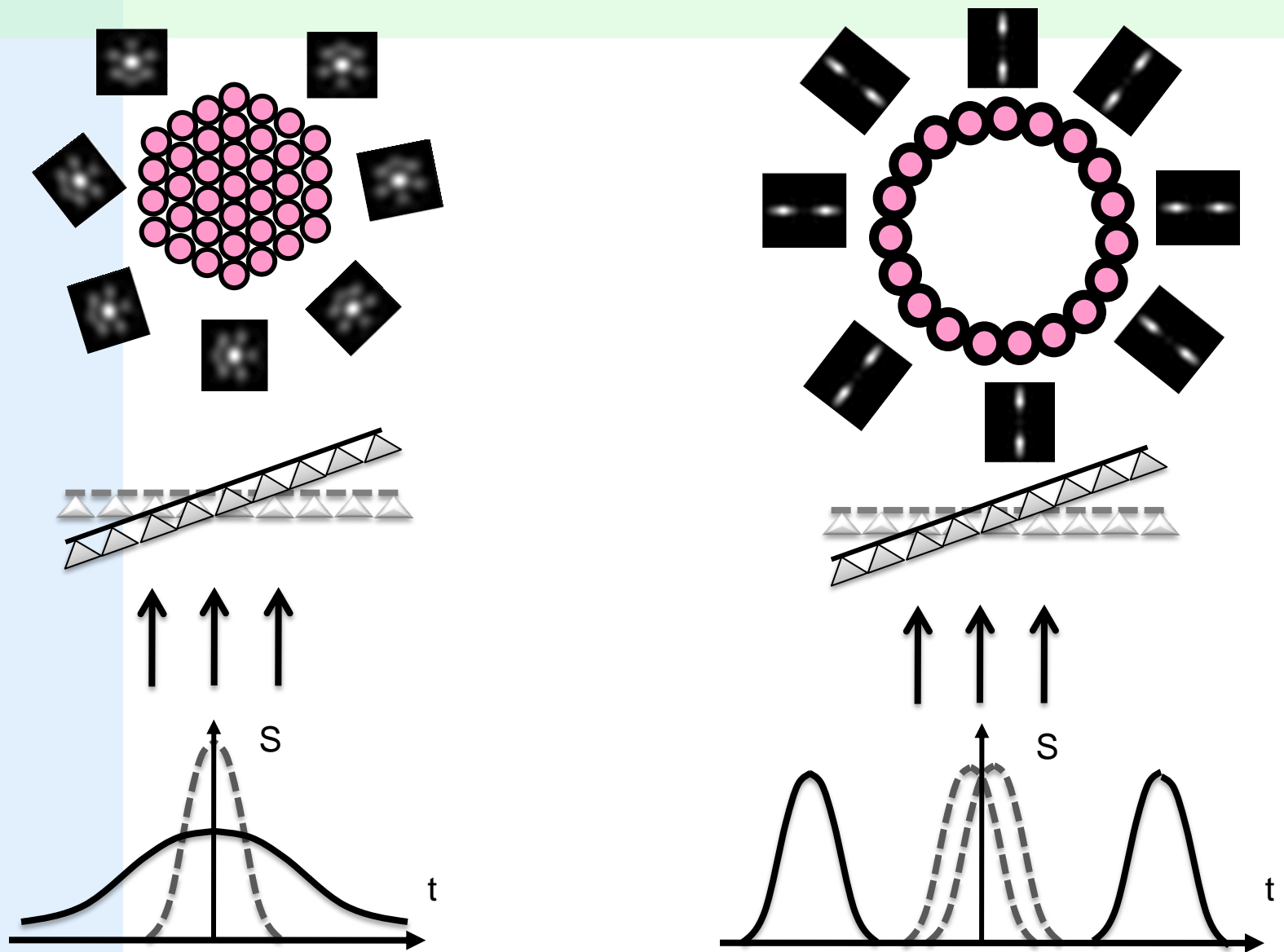


### 3 : Influence of incident angle on two-spots CCRs





# 4 : Optimization of LR array configuration





## 5 : Spherical glass nanosatellite «BLITS-M»

### Expected target parameters of the nanosatellite «BLITS-M»

goal error	no more than 0.1 mm
CS	$0.3 \cdot 10^6 - 1 \cdot 10^6 \text{ m}^2$
time of service under the condition of a flight	at least 10 years
orbital altitude (will be chosen)	1500 km – 3000 km
diameter	no more than 250 mm
mass	at least 20 kg



**Thank you for your attention!**

